

Discontinuous Galerkin methods for advection-diffusion-reaction problems

Donatella Marini

Dipartimento di Matematica, Università di Pavia, Italy
& IMATI- C.N.R., Pavia, Italy

Joint work with Blanca Ayuso + ideas from works with Arnold, Brezzi, Cockburn, Hughes, Süli...

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A bit of History

Introduced for purely hyperbolic problems (Reed-Hill 70's, Lesaint-Raviart)

Used for second order elliptic (Douglas-Dupont school, mid 70's) and for fourth order (Baker).

Abandoned because of the big size of the final system.

Great revival some 10 years ago (mainly by Cockburn-Shu) also for applications to problems where the elliptic part is present but it is not dominant.

(example: strongly advection-dominated equations, very thin Reissner-Mindlin plates)

Outline

- 1 Original Derivation of DG methods for a model elliptic problem
- 2 DG Methods as Weighted Residuals
- 3 Advection-Diffusion-Reaction Problems
- 4 Numerical Results

Model Problem

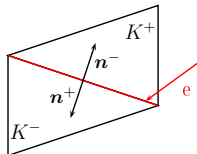
$\Omega \subset \mathbb{R}^d$ ($d = 2, 3$) bounded convex (polygonal or polyhedral)

$$\begin{cases} Au \equiv -\operatorname{div}(\kappa \nabla u) = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma = \partial\Omega \end{cases}$$

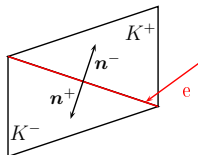
$$\boldsymbol{\sigma} = -\kappa \nabla u$$

$$\begin{cases} \kappa^{-1} \boldsymbol{\sigma} + \nabla u = 0 & \text{in } \Omega \\ \operatorname{div} \boldsymbol{\sigma} = f & \text{in } \Omega \\ u = 0 & \text{on } \Gamma \end{cases}$$

Averages & Jumps



Averages & Jumps



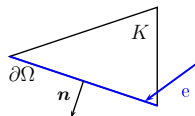
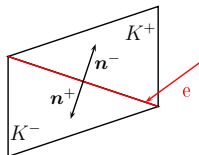
$$\{v\} = \frac{v^+ + v^-}{2};$$

$$[[v]] = v^+ \mathbf{n}^+ + v^- \mathbf{n}^- \quad \forall e \in \mathcal{E}_h^\circ \equiv \text{internal edges}$$

$$\{\tau\} = \frac{\tau^+ + \tau^-}{2};$$

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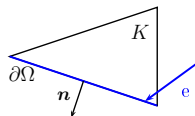
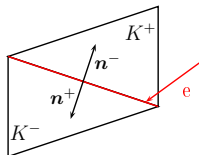


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$$\text{On boundary edges } \llbracket v \rrbracket = v \mathbf{n}; \quad \{\tau\} = \tau$$

Averages & Jumps



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On boundary edges $\llbracket v \rrbracket = v \mathbf{n}; \quad \{\tau\} = \tau$

Crucial Formula

$$\sum_{K \in \mathcal{T}_h} \int_{\partial K} v \boldsymbol{\tau} \cdot \mathbf{n}_T = \sum_{e \in \mathcal{E}_h} \int_e \llbracket v \rrbracket \cdot \{\tau\} + \sum_{e \in \mathcal{E}_h^\circ} \int_e \{v\} \llbracket \tau \rrbracket$$

Original Derivation of DG Methods

In the beginning DG methods were derived in a simple way (see e.g. Douglas-Dupont, M.F. Wheeler, D.N. Arnold).

Taking the equation $-\operatorname{div}(\kappa \nabla u) = f$, we multiply it by a piecewise smooth function v , and integrate by parts:

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \kappa \nabla u \cdot \mathbf{n} v = \int_{\Omega} f v.$$

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Rearranging terms with the **crucial formula** we have

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_{e \in \mathcal{E}_h} \int_e \llbracket v \rrbracket \cdot \{\kappa \nabla u\} - \sum_{e \in \mathcal{E}_h^o} \int_e \llbracket \kappa \nabla u \rrbracket \cdot \{v\} = \int_{\Omega} f v.$$

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Then, since u is smooth, $\llbracket \kappa \nabla u \rrbracket$ is zero and we can forget about it:

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_e \int_e \llbracket v \rrbracket \cdot \{\kappa \nabla u\} = \int_{\Omega} f v.$$

The Original Derivation of DG methods

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$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_e \int_e \llbracket v \rrbracket \cdot \{\kappa \nabla u\} = \int_{\Omega} f v.$$

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$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_e \int_e \llbracket v \rrbracket \cdot \{ \kappa \nabla u \} = \int_{\Omega} f v.$$

Then, always since u is smooth, also $\llbracket u \rrbracket = 0$, and can add a term "to restore symmetry"

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \sum_e \int_e \llbracket v \rrbracket \cdot \{ \kappa \nabla u \} - \sum_e \int_e \llbracket u \rrbracket \cdot \{ \kappa \nabla_h v \} = \int_{\Omega} f v.$$

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Then we realize that the method is unstable! However, since $\llbracket u \rrbracket = 0$, we can add a **stabilizing term**

$$\int_{\Omega} \kappa \nabla u \cdot \nabla_h v - \int_{\mathcal{E}_h} \llbracket v \rrbracket \cdot \{\kappa \nabla u\} - \int_{\mathcal{E}_h} \llbracket u \rrbracket \cdot \{\kappa \nabla_h v\} + \sum_e \frac{\gamma}{|e|} \int_e \llbracket u \rrbracket \cdot \llbracket v \rrbracket = \int_{\Omega} f v.$$

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\Rightarrow This is "IP" (Interior Penalty).

DG Methods as Weighted Residuals

(Brezzi-Cockburn-M.-Süli, CMAME 2006)

If you allow, a priori, your solution to be discontinuous, then the equations to be required are:

- $Au - f = 0$ in each element
- $[[u]] = 0$ on each edge
- $[[\sigma]] = 0$ on each internal edge

(remember that $\sigma = -\kappa \nabla u$).

Starting Point

We define $H^2(\mathcal{T}_h) := \{v \in L^2(\Omega) : v|_K \in H^2(K) \forall K \in \mathcal{T}_h\}$.

We take three operators B_0 , B_1 , B_2 from $H^2(\mathcal{T}_h)$ to $L^2(\mathcal{T}_h)$, $[L^2(\mathcal{E}_h)]^d$ and $L^2(\mathcal{E}_h^\circ)$ respectively.

Then we consider the following *variational* formulation

find $u \in H^2(\mathcal{T}_h)$ such that, $\forall v \in H^2(\mathcal{T}_h)$:

$$(Au - f, B_0(v))_h + \langle [u], B_1(v) \rangle_h + \langle [\sigma], B_2(v) \rangle_h^0 = 0,$$

where

$$(u, v)_h = \sum_{K \in \mathcal{T}_h} \int_K u v \, dx \quad \langle u, v \rangle_h = \sum_{e \in \mathcal{E}_h} \int_e u v \, ds$$

and $\langle u, v \rangle_h^0$ runs only on internal edges

Conditions on the Operators B_j

$$(A u - f, B_0(v))_h + \langle [u], B_1(v) \rangle_h + \langle [\sigma], B_2(v) \rangle_h^0 = 0 \quad \forall v$$

The above equation gives back the original three equations on u (that is $A u = f$, $[u] = 0$, and $[\sigma] = 0$) if (and, essentially, only if)

- $\forall K \in \mathcal{T}_h$ and $\forall \varphi \in C_0^\infty(K)$ there is a $v \in H^2(\mathcal{T}_h)$ such that

$$B_0 v = \varphi \text{ in } K, \quad B_0 v = 0 \text{ in } \mathcal{T}_h \setminus K, \quad B_1 v \equiv 0, \quad B_2 v \equiv 0$$

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- $\forall e \in \mathcal{E}_h$ and $\forall \psi \in C_0^\infty(e)$ there is a $v \in H^2(\mathcal{T}_h)$ such that

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- $\forall e \in \mathcal{E}_h^\circ$ and $\forall \chi \in C_0^\infty(e)$ there is a $v \in H^2(\mathcal{T}_h)$ such that

$$B_2 v = \chi \text{ on } e, \quad B_2 v = 0 \text{ on } \mathcal{E}_h^\circ \setminus e$$

Choosing B_0 and Using the Crucial Formula

- Choosing $B_0 v \equiv v$ and using the crucial formula, we can write:

$$(Au, B_0(v))_h \equiv \sum_{K \in \mathcal{T}_h} \int_K -\operatorname{div}(\kappa \nabla u) v \, dx$$

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The New Bilinear Form

$$(A u - f, B_0(v))_h + \langle [u], B_1(v) \rangle_h + \langle [\sigma], B_2(v) \rangle_h^0 = 0 \quad \forall v$$

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We had

$$\begin{aligned} (Au, B_0(v))_h &= (\kappa \nabla u, \nabla v)_h + \langle \{\sigma\}, [v] \rangle_h + \langle [\sigma], \{v\} \rangle_h^0 \\ &\equiv (\kappa \nabla u, \nabla v)_{h-} + \langle \{\kappa \nabla u\}, [v] \rangle_h + \langle [\sigma], \{v\} \rangle_h^0 \end{aligned}$$

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$$(Au - f, B_0(v))_{h+} + \langle [u], B_1(v) \rangle_h + \langle [\sigma], B_2(v) \rangle_h^0 = 0 \quad \forall v$$

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- Choosing $B_2(v) \equiv -\{v\}$ gives

$$\begin{aligned} (Au - f, B_0(v))_{h+} + \langle [u], B_1(v) \rangle_h + \langle [\sigma], B_2(v) \rangle_h^0 \\ \equiv (\kappa \nabla u, \nabla v)_{h-} + \langle \{\kappa \nabla u\}, [v] \rangle_h - (f, v)_{h+} + \langle [u], B_1(v) \rangle_h = 0 \end{aligned}$$

and we have just to choose B_1

Choices for B_1 : Symmetrizing and Stabilizing

Our equations are

$$(\kappa \nabla u, \nabla v)_h - \langle \{\kappa \nabla u\}, [v] \rangle_h + \langle [u], B_1(v) \rangle_h = (f, v)_h$$

You are not allowed to take $B_1 \equiv 0$. You can take, for instance

- $B_1(v)|_e := -\{\kappa \nabla_h v\} + \left(\frac{c}{|e|} [v]\right)$ (stabilized) IP

or

- $B_1(v)|_e := +\{\kappa \nabla_h v\} + \left(\frac{c}{|e|} [v]\right)$ (stabilized) BO (NIPG)

or

- $B_1(v)|_e := \frac{c}{|e|} [v]$ Wheeler-Sun (IIP)

Other Possibilities

On the other hand, the choice of B_2 can also be revisited. For instance taking

$$B_2 v|_e = -\{v\} - \gamma|e|[\![\nabla_h v]\!] \quad \text{and} \quad B_1(v)|_e := \frac{c(\kappa)}{|e|}[\![v]\!] - \{\kappa \nabla_h v\}$$

(Douglas-Dupont, Hansbo et als, etc.) your final bilinear form will be

$$\begin{aligned} & (\kappa \nabla u, \nabla v)_h - \langle \{\kappa \nabla u\}, [\![v]\!] \rangle_h - \langle \{\kappa \nabla_h v\}, [\![u]\!] \rangle_h \\ & + \sum_{e \in \mathcal{E}_h} \frac{c(\kappa)}{|e|} \int_e [\![u]\!] \cdot [\![v]\!] ds + \sum_{e \in \mathcal{E}_h^\circ} \gamma|e| \int_e [\![\kappa \nabla u]\!] \cdot [\![\nabla_h v]\!] ds \end{aligned}$$

where the **red part** is needed for **consistency**, and the others to **symmetrize** (if you choose to have it) and to **stabilize**

Error Estimates

$$V_h := \{v \in L^2(\Omega) : v|_K \in P_k(K) \forall K \in \mathcal{T}_h\} \subset H^2(\mathcal{T}_h)$$

The final bilinear form $a(u, v)$ should satisfy:

$$1) a(u - u_h, v_h) = 0 \quad \forall v_h \in V_h \quad 2) \alpha \|v_h\|^2 \leq a(v_h, v_h) \quad \forall v_h \in V_h$$

$$3) a(w, v) \leq C \|w\| \|v\| \quad \forall w, v \in H^2(\mathcal{T}_h) \quad 4) \|u - u_I\| \leq C h^k \|u\|_{k+1}$$

where

$$\|v\|^2 := \|\nabla_h v\|_0^2 + \sum_e |e|^{-1} \|\llbracket v \rrbracket\|_{0,e}^2 + \sum_K h_K^2 |v|_{2,K}^2$$

and u_h (discrete solution), and u_I (interpolant of u) are in V_h . Then:

$$\begin{aligned} \alpha \|u_h - u_I\|^2 &\leq a(u_h - u_I, u_h - u_I) = a(u - u_I, u_h - u_I) \\ &\leq C \|u - u_I\| \|u_h - u_I\| \leq C h^k \|u_h - u_I\|. \end{aligned}$$

Advection-Diffusion-Reaction Problems

Let $f \in L^2(\Omega)$, $g \in H^{3/2}(\Gamma)$. Consider the problem

$$\begin{aligned} \operatorname{div}(-\varepsilon \nabla u + \beta u) + \gamma u &= f && \text{in } \Omega, \\ u &= g && \text{on } \Gamma = \partial\Omega, \end{aligned}$$

Introducing the flux $\sigma(u) = -\varepsilon \nabla u + \beta u$ we can write

$$\begin{aligned} \operatorname{div} \sigma(u) + \gamma u &= f && \text{in } \Omega, \\ u &= g && \text{on } \Gamma = \partial\Omega, \end{aligned}$$

For simplicity of exposition we shall assume ε , β , γ constants:
 $\varepsilon > 0$, $\gamma \geq 0$. Unique solution $u \in H^2(\Omega)$.

$$\Gamma = \Gamma^+ \cup \Gamma^-, \quad \Gamma^- = \text{inflow } (\beta \cdot \mathbf{n} < 0), \quad \Gamma^+ = \text{outflow } (\beta \cdot \mathbf{n} \geq 0)$$

The Residuals

If we allow the solution to be a-priori discontinuous, we have to enforce the following equations:

$$\begin{aligned}R_0(u) &:= \operatorname{div} \sigma(u) + \gamma u - f = 0 && \text{in each } K \in \mathcal{T}_h, \\R_1(u) &:= \llbracket u \rrbracket = 0 && \text{on each } e \in \mathcal{E}_h^\circ, \\R_2(u) &:= \llbracket \sigma(u) \rrbracket = 0 && \text{on each } e \in \mathcal{E}_h^\circ, \\R_1^D(u) &:= u - g = 0 && \text{on each } e \in \Gamma\end{aligned}$$

Hence we need four operators B_0, B_1, B_2, B_1^D such that:

$$\begin{aligned}(R_0(u), B_0(v))_h &+ \langle R_1(u), B_1(v) \rangle_h^0 + \langle R_2(u), B_2(v) \rangle_h^0 \\&+ \langle R_1^D(u), B_1^D(v) \rangle_\Gamma = 0 \quad \forall v \in H^2(\mathcal{T}_h)\end{aligned}$$

Choices of the operators

Taking $B_0 v = v$ we have:

$$\begin{aligned}(\operatorname{div} \boldsymbol{\sigma}(u) + \gamma u - f, v)_h &+ \langle [u], B_1(v) \rangle_h^0 + \langle [\boldsymbol{\sigma}(u)], B_2(v) \rangle_h^0 \\ &+ \langle u - g, B_1^D(v) \rangle_{\Gamma} = 0 \quad \forall v \in H^2(\mathcal{T}_h)\end{aligned}$$

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Integrating by parts and using the crucial formula:

$$\begin{aligned}\int_{\Omega} \operatorname{div}_h \boldsymbol{\sigma}(u) v &= - \int_{\Omega} \boldsymbol{\sigma}(u) \cdot \nabla_h v + \sum_{K \in \mathcal{T}_h} \int_{\partial K} \boldsymbol{\sigma}(u) \cdot \mathbf{n}_v \\ &= -(\boldsymbol{\sigma}(u), \nabla v)_h + \langle [\boldsymbol{\sigma}(u)], \{v\} \rangle_h^0 + \langle \{\boldsymbol{\sigma}(u)\}, [v] \rangle_h\end{aligned}$$

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$$\begin{aligned}\int_{\Omega} \operatorname{div}_h \sigma(u) v &= - \int_{\Omega} \sigma(u) \cdot \nabla_h v + \sum_{K \in \mathcal{T}_h} \int_{\partial K} \sigma(u) \cdot \mathbf{n}_v \\ &= -(\sigma(u), \nabla v)_h + \langle [\sigma(u)], \{v\} \rangle_h^0 + \langle \{\sigma(u)\}, [v] \rangle_h\end{aligned}$$

Substituting in the equation we obtain:

$$\begin{aligned}(\gamma u, v) - (\sigma(u), \nabla v)_h &+ \langle [u], B_1(v) \rangle_h^0 + \langle \{\sigma(u)\}, [v] \rangle_h \\ &+ \langle [\sigma(u)], B_2(v) + \{v\} \rangle_h^0 + \langle u, B_1^D(v) \rangle_\Gamma \\ &= (f, v) + \langle g, B_1^D(v) \rangle_\Gamma\end{aligned}$$

Guidelines for choosing the operators

Our bilinear form is:

$$a_h(u, v) : = (\gamma u, v) - (\sigma(u), \nabla v)_h + \langle [u], B_1(v) \rangle_h^0 + \langle \{\sigma(u)\}, [v] \rangle_h \\ + \langle [\sigma(u)], B_2(v) + \{v\} \rangle_h^0 + \langle u, B_1^D(v) \rangle_\Gamma$$

We shall need stability (in the finite element space) in a suitable norm:

$$a_h(v, v) \geq \alpha \|v\|^2 \quad \forall v \in V_h^k.$$

$$(k \geq 1 \longrightarrow V_h^k = \{v \in L^2(\Omega) : v|_K \in P_k(K) \quad \forall K \in \mathcal{T}_h\})$$

$$\|v\|^2 = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 + \sum_{e \in \mathcal{E}_h} \frac{\varepsilon}{|e|} \| [v] \|_{0,e}^2 + \sum_{e \in \mathcal{E}_h} |\beta \cdot \mathbf{n}| \| [v] \|_{0,e}^2$$

Guidelines for choosing the operators. (Towards stability)

$$a_h(v, v) = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 - \int_{\Omega} (\beta \cdot \nabla_h v) v + \dots$$

$$\int_{\Omega} -(\beta \cdot \nabla_h v) v = -\frac{1}{2} \int_{\Omega} \beta \cdot \nabla_h (v^2) = - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \frac{\beta \cdot \mathbf{n}}{2} v^2$$

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$$\text{but } [\beta] = 0$$

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$$a_h(v, v) = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 - \int_{\Omega} (\boldsymbol{\beta} \cdot \nabla_h v) v + \dots$$

$$\begin{aligned} \int_{\Omega} -(\boldsymbol{\beta} \cdot \nabla_h v) v &= -\frac{1}{2} \int_{\Omega} \boldsymbol{\beta} \cdot \nabla_h (v^2) = -\sum_{K \in \mathcal{T}_h} \int_{\partial K} \frac{\boldsymbol{\beta} \cdot \mathbf{n}}{2} v^2 \\ &= -\frac{1}{2} \langle \{\boldsymbol{\beta}\}, [v^2] \rangle_h - \frac{1}{2} \langle \boldsymbol{\beta} \cdot \mathbf{n}, v^2 \rangle_{\Gamma} \end{aligned}$$

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$$\langle \{\sigma(v)\}, [v] \rangle_h = - \langle \{\varepsilon \nabla_h v\}, [v] \rangle_h + \langle \{\beta v\}, [v] \rangle_h$$

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$$a_h(v, v) = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 - \int_{\Omega} (\beta \cdot \nabla_h v) v + \dots$$

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$$\langle \{\beta v\}, [v] \rangle_h = \frac{1}{2} \langle \{\beta\}, [v^2] \rangle_h$$

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$$= -\frac{1}{2} \langle \{\beta\}, [v^2] \rangle_h - \frac{1}{2} \langle \beta \cdot \mathbf{n}, v^2 \rangle_{\Gamma}$$

$$\langle \{\sigma(v)\}, [v] \rangle_h = - \langle \{\varepsilon \nabla_h v\}, [v] \rangle_h + \frac{1}{2} \langle \{\beta\}, [v^2] \rangle_h + \langle \beta \cdot \mathbf{n}, v^2 \rangle_{\Gamma}$$

$$\begin{aligned} \langle [\sigma(v)], B_2(v) + \{v\} \rangle_h &= - \langle [\varepsilon \nabla_h v], B_2(v) + \{v\} \rangle_h \\ &\quad + \langle [\beta v], B_2(v) + \{v\} \rangle_h \end{aligned}$$

Guidelines for choosing the operators. (Towards stability)

$$a_h(v, v) = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 - \int_{\Omega} (\beta \cdot \nabla_h v) v + \dots$$

$$\begin{aligned} \int_{\Omega} -(\beta \cdot \nabla_h v) v &= -\frac{1}{2} \int_{\Omega} \beta \cdot \nabla_h (v^2) = - \sum_{K \in \mathcal{T}_h} \int_{\partial K} \frac{\beta \cdot \mathbf{n}}{2} v^2 \\ &= -\frac{1}{2} \langle \{\beta\}, [v^2] \rangle_h^0 - \frac{1}{2} \langle \beta \cdot \mathbf{n}, v^2 \rangle_{\Gamma} \end{aligned}$$

$$\langle \{\sigma(v)\}, [v] \rangle_h = - \langle \{\varepsilon \nabla_h v\}, [v] \rangle_h + \frac{1}{2} \langle \{\beta\}, [v^2] \rangle_h^0 + \langle \beta \cdot \mathbf{n}, v^2 \rangle_{\Gamma}$$

$$\begin{aligned} \langle [\sigma(v)], B_2(v) + \{v\} \rangle_h^0 &= - \langle [\varepsilon \nabla_h v], B_2(v) + \{v\} \rangle_h^0 \\ &\quad + \langle [\beta v], B_2(v) + \{v\} \rangle_h^0 \end{aligned}$$

$$\langle [u], B_1(v) \rangle_h^0, \quad \langle u, B_1^D(v) \rangle_{\Gamma}$$

Guidelines for choosing the operators. (Towards stability)

$$B_2(v) = -\{v\} + Q_2(v), \quad B_1(v) = \frac{c\varepsilon}{|e|} \llbracket v \rrbracket + Q_1(v)$$
$$B_1^D(v) = \frac{c\varepsilon}{|e|} v - \beta \cdot \mathbf{n}v + Q_1^D(v) \text{ on } \Gamma^-, \quad B_1^D(v) = \frac{c\varepsilon}{|e|} v + Q_1^D(v) \text{ on } \Gamma^+$$

with $Q_1(v)$, $Q_2(v)$, $Q_1^D(v)$ to be chosen such that

$$\langle \llbracket v \rrbracket, Q_1(v) \rangle_h^0 + \langle \llbracket \beta v \rrbracket, Q_2(v) \rangle_h^0 \geq \sum_{e \in \mathcal{E}_h^o} |\beta \cdot \mathbf{n}| \|\llbracket v \rrbracket\|_{0,e}^2$$

$Q_1^D(v)$ not depending on β .

In other words, we can upwind either with B_1 or with B_2

First choice - minimal choice

Set $S_e = \frac{c\varepsilon}{|e|}$, $Q_2(v) = 0$, $Q_1(v) = \frac{n^+}{2}[\beta v]$ $Q_1^D(v) = 0$, that is

$$B_2(v) = -\{v\} \quad B_1(v) = S_e[v] + \frac{n^+}{2}[\beta v]$$

$$B_1^D(v) = S_e v - \beta \cdot \mathbf{n}v \text{ on } \Gamma^-, \quad B_1^D(v) = S_e v \text{ on } \Gamma^+$$

$$\left\{ \begin{array}{l} \text{Find } u \in H^2(\mathcal{T}_h) \text{ such that } \forall v \in H^2(\mathcal{T}_h) \\ \int_{\Omega} (\gamma uv - \sigma(u) \cdot \nabla_h v) + \sum_{e \in \mathcal{E}_h} S_e \int_e [u] \cdot [v] - \sum_{e \in \mathcal{E}_h} \int_e \{\varepsilon \nabla_h u\} \cdot [v] \\ + \sum_{e \in \mathcal{E}_h^o} \int_e (\beta u)_{upw} [v] + \int_{\Gamma^+} \beta \cdot \mathbf{n}uv \\ = \int_{\Omega} f v + \sum_{e \in \Gamma} S_e \int_e g v - \sum_{e \in \Gamma^-} \int_e \beta \cdot \mathbf{n}g v. \end{array} \right.$$

For the diffusive part this choice corresponds to the IIP scheme.

Choice by Houston-Schwab-Süli (SINUM 2002)

Set

$$Q_2(v) = 0, \quad Q_1(v) = \{\varepsilon \nabla_h v\} + \frac{n^+}{2} \llbracket \beta v \rrbracket, \quad Q_1^D(v) = \varepsilon \nabla_h v \cdot \mathbf{n}$$

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$$\implies B_2(v) = -\{v\} \quad B_1(v) = S_e[v] + \{\epsilon \nabla_h v\} + \frac{n^+}{2} [\beta v]$$

$$B_1^D(v) = S_e v - \beta \cdot \mathbf{n} v + \epsilon \nabla_h v \cdot \mathbf{n} \text{ on } \Gamma^-,$$

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$$\left\{ \begin{array}{l}
 \text{Find } u \in H^2(\mathcal{T}_h) \text{ such that } \forall v \in H^2(\mathcal{T}_h) \\
 \int_{\Omega} (\gamma uv - \sigma(u) \cdot \nabla_h v) + \sum_{e \in \mathcal{E}_h} S_e \int_e [[u]] \cdot [v] + \sum_{e \in \mathcal{E}_h^o} \int_e (\beta u)_{upw} \cdot [v] \\
 + \sum_{e \in \mathcal{E}_h} \int_e ([[u]] \cdot \{\varepsilon \nabla_h v\} - \{\varepsilon \nabla_h u\} \cdot [v]) + \sum_{e \in \Gamma^+} \int_e \beta \cdot \mathbf{n} uv \\
 = \int_{\Omega} f v + \sum_{e \in \Gamma} \int_e g (S_e v + \varepsilon \nabla_h v \cdot \mathbf{n} - \beta \cdot \mathbf{n} v).
 \end{array} \right.$$

NIPG for the diffusive part (Wheeler-Rivière-Girault)

Choice by Hughes-Scovazzi-Bochev-Buffa (CMAME 2006)

$$Q_1(v) = \theta(\varepsilon \nabla_h v)_{upw} \equiv \theta(\{\varepsilon \nabla_h v\} + \frac{\mathbf{n}^+}{2} [[\varepsilon \nabla_h v]]),$$

$$Q_2(v) = \frac{\mathbf{n}^+}{2} \cdot [[v]], \quad Q_1^D(v) = \theta \varepsilon \nabla_h v \cdot \mathbf{n}$$

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$$\implies B_2(v) = -(v)_{dw} \equiv -\{v\} + \frac{\mathbf{n}^+}{2} \cdot [v]$$

$$B_1(v) = S_e [v] + \theta(\varepsilon \nabla_h v)_{upw}$$

$$B_1^D(v) = S_e v - \beta \cdot \mathbf{n} v + \theta \varepsilon \nabla_h v \cdot \mathbf{n} \text{ on } \Gamma^-,$$

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$$\left\{ \begin{aligned}
 & \text{Find } u \in H^2(\mathcal{T}_h) \text{ such that } \forall v \in H^2(\mathcal{T}_h) \\
 & \int_{\Omega} (\gamma uv - \sigma(u) \cdot \nabla_h v) + \sum_{e \in \mathcal{E}_h} S_e \int_e [[u]] \cdot [v] \\
 & + \sum_{e \in \mathcal{E}_h^o} \int_e (\theta [[u]] \cdot (\varepsilon \nabla_h v)_{upw} - (\varepsilon \nabla_h u)_{upw} \cdot [v]) + \sum_{e \in \mathcal{E}_h^o} \int_e (\beta u)_{upw} \cdot [v] \\
 & + \sum_{e \in \Gamma} \int_e \theta u (\varepsilon \nabla_h v \cdot \mathbf{n}) - (\varepsilon \nabla_h u \cdot \mathbf{n}) v + \sum_{e \in \Gamma^+} \int_e \beta \cdot \mathbf{n} u v \\
 & = \int_{\Omega} f v + \sum_{e \in \Gamma} \int_e g (S_e v + \theta \varepsilon \nabla v \cdot \mathbf{n}) - \sum_{e \in \Gamma^-} \int_e g \beta \cdot \mathbf{n} v.
 \end{aligned} \right.$$

$\theta = -1 \longrightarrow$ symmetric, $\theta = 1 \longrightarrow$ nonsymmetric, $\theta = 0 \longrightarrow$ neutral

Analyzed by Hughes-Buffa-Sangalli (to appear in SINUM)

Another choice

Let us first introduce a new average. Definition of weighted average on an internal edge. For α^1, α^2 real numbers, with $\alpha^1 + \alpha^2 = 1$:

$$\{\varphi\}_\alpha = \alpha^1 \varphi^1 + \alpha^2 \varphi^2$$

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$\alpha^i = (\text{sign}(\beta \cdot \mathbf{n}^i) + 1)/2 \longrightarrow$ classical upwind

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Indeed:

$$\{\varphi\}_\alpha = \{\varphi\} + \frac{[\![\alpha]\!] }{2} [\![\varphi]\!]]$$

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Indeed:

$$\{\varphi\}_\alpha = \{\varphi\} + \frac{[\![\alpha]\!] }{2} [\![\varphi]\!]$$

Ex: If K_1 upwind element ($\boldsymbol{\beta} \cdot \mathbf{n}^1 > 0$) then $\alpha = (1, 0)$

$$\{\varphi\}_\alpha \equiv (\varphi)_{upw} = \varphi^1 \quad \{\varphi\}_{1-\alpha} \equiv (\varphi)_{dw} = \varphi^2$$

Another choice

$$Q_1(v) = \theta(\{\sigma(v)\}_\alpha - \{\beta v\}), \quad Q_2(v) = \frac{[\alpha]}{2} \cdot [v], \quad Q_1^D(v) = -\theta \varepsilon \nabla_h v \cdot$$

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$$B_1 v = S_e [v] + \theta(\{\sigma(v)\}_\alpha - \{\beta v\}),$$

$$B_2 v = -\{v\}_{1-\alpha} \equiv -\{v\} + \frac{[\alpha]}{2} [v],$$

$$B_1^D v = S_e v - \beta \cdot \mathbf{n} v - \theta \varepsilon \nabla_h v \cdot \mathbf{n} \text{ on } \Gamma^-,$$

$$B_1^D v = S_e v - \theta \varepsilon \nabla_h v \cdot \mathbf{n} \text{ on } \Gamma^+.$$

Another choice

$$\left\{ \begin{array}{l} \text{Find } u \in H^2(\mathcal{T}_h) \text{ such that } \forall v \in H^2(\mathcal{T}_h) \\ \int_{\Omega} (\gamma uv - \sigma(u) \cdot \nabla_h v) + \sum_{e \in \mathcal{E}_h} S_e \int_e [u] \cdot [v] \\ + \sum_{e \in \mathcal{E}_h^o} \int_e \{\sigma(u)\}_\alpha \cdot [v] + \sum_{e \in \mathcal{E}_h^o} \int_e \theta [u] \cdot (\{\sigma(v)\}_\alpha - \{\beta v\}) \\ - \sum_{e \in \Gamma} \int_e (\varepsilon \nabla_h u \cdot \mathbf{n} v + \theta u \varepsilon \nabla_h v \cdot \mathbf{n}) + \sum_{e \in \Gamma^+} \int_e \beta \cdot \mathbf{n} u v \\ = \int_{\Omega} f v + \sum_{e \in \Gamma} \int_e g (S_e v - \theta \varepsilon \nabla_h v \cdot \mathbf{n}) - \sum_{e \in \Gamma^-} \int_e \beta \cdot \mathbf{n} g v \end{array} \right.$$

Another choice

$$\left\{ \begin{array}{l} \text{Find } u \in H^2(\mathcal{T}_h) \text{ such that } \forall v \in H^2(\mathcal{T}_h) \\ \int_{\Omega} (\gamma uv - \sigma(u) \cdot \nabla_h v) + \sum_{e \in \mathcal{E}_h} S_e \int_e [u] \cdot [v] \\ + \sum_{e \in \mathcal{E}_h^o} \int_e \{\sigma(u)\}_\alpha \cdot [v] + \sum_{e \in \mathcal{E}_h^o} \int_e \theta [u] \cdot (\{\sigma(v)\}_\alpha - \{\beta v\}) \\ - \sum_{e \in \Gamma} \int_e (\varepsilon \nabla_h u \cdot \mathbf{n} v + \theta u \varepsilon \nabla_h v \cdot \mathbf{n}) + \sum_{e \in \Gamma^+} \int_e \beta \cdot \mathbf{n} uv \\ = \int_{\Omega} f v + \sum_{e \in \Gamma} \int_e g (S_e v - \theta \varepsilon \nabla_h v \cdot \mathbf{n}) - \sum_{e \in \Gamma^-} \int_e \beta \cdot \mathbf{n} g v \end{array} \right.$$

$\theta = 1 \longrightarrow$ symmetric, $\theta = 0 \longrightarrow$ neutral

For $\theta = -1 \longrightarrow$ nonsymmetric, but stability in a weaker norm \implies
suboptimal order of convergence.

Error estimates

$$k \geq 1 \longrightarrow V_h^k = \{\mathbf{v} \in L^2(\Omega) : \mathbf{v}|_K \in P_k(K) \quad \forall K \in \mathcal{T}_h\}$$

In all the cases the discrete problem reads:

$$\begin{cases} \text{Find } u_h \in V_h^k \text{ such that :} \\ a_h(u_h, v) = F(v) \quad \forall v \in V_h^k. \end{cases}$$

We have consistency (by construction), and stability in the norm:

$$\|v\|^2 = \gamma \|v\|_{0,\Omega}^2 + \varepsilon |v|_{1,h}^2 + \sum_{e \in \mathcal{E}_h} \frac{\varepsilon}{|e|} \|\llbracket v \rrbracket\|_{0,e}^2 + \sum_{e \in \mathcal{E}_h} |\beta \cdot \mathbf{n}| \|\llbracket v \rrbracket\|_{0,e}^2$$

The following estimate holds:

$$\|u - u_h\| \leq C \begin{cases} h^{k+1/2} & \text{if advection dominates,} \\ h^k & \text{if diffusion dominates.} \end{cases}$$

Introducing a term of SUPG type

It is often desirable to have direct estimates in the norm

$$\|v\|_{SUPG}^2 = \|v\|^2 + \sum_{K \in \mathcal{T}_h} C_{0,K} \frac{h_K}{|\beta|} \|\beta \cdot \nabla v\|^2$$

For this we only have to choose B_0 as

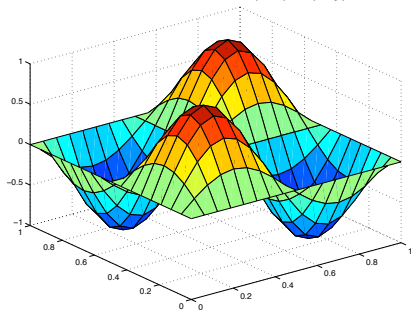
$$B_0(v) = v + \sum_{K \in \mathcal{T}_h} C_{0,K} \frac{h_K}{|\beta|} \beta \cdot \nabla v$$

The same estimates hold

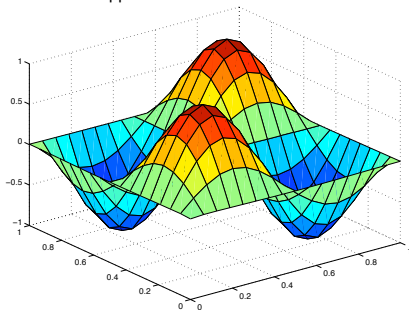
$$\|u - u_h\|_{SUPG} \leq C \begin{cases} h^{k+1/2} & \text{if advection dominates,} \\ h^k & \text{if diffusion dominates.} \end{cases}$$

Approximation to a Smooth Solution

exact solution: $u = \sin(2\pi x)\sin(2\pi y)$

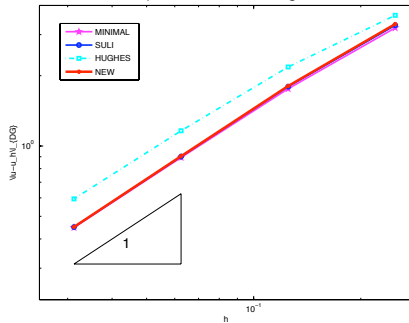


approximate solution with NEW

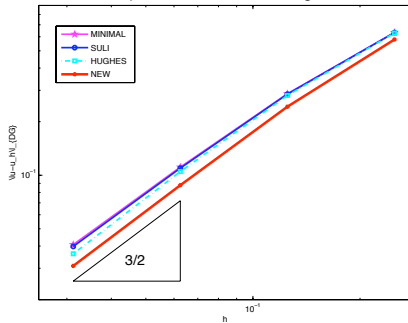


Convergence Diagrams: Smooth Solution

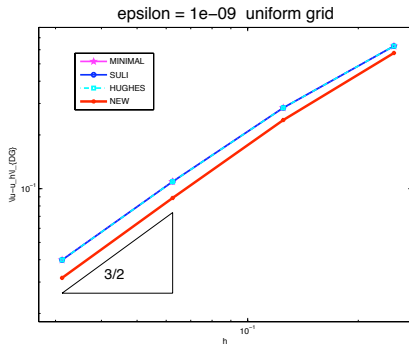
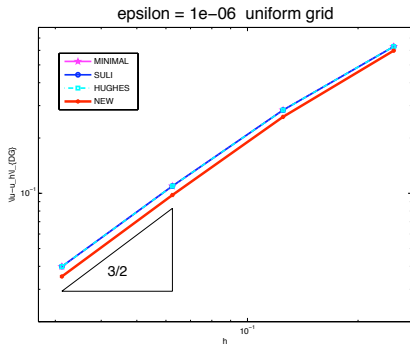
epsilon = 1 uniform grid



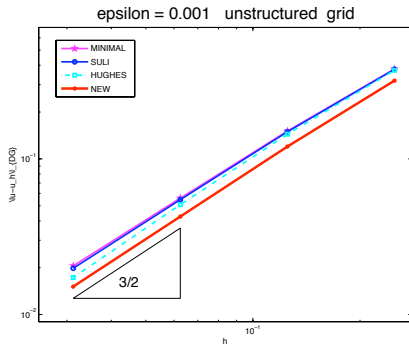
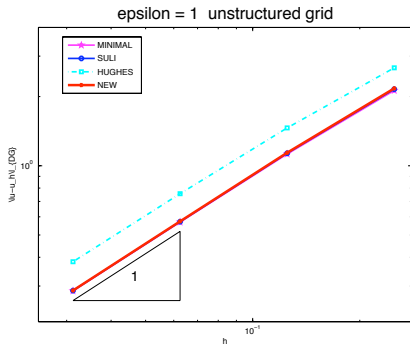
epsilon = 0.001 uniform grid



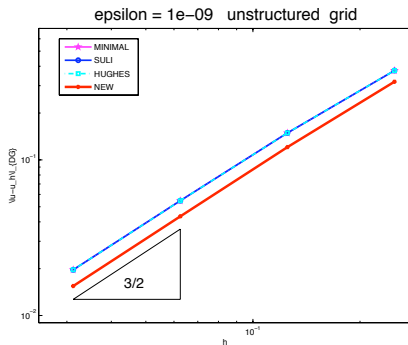
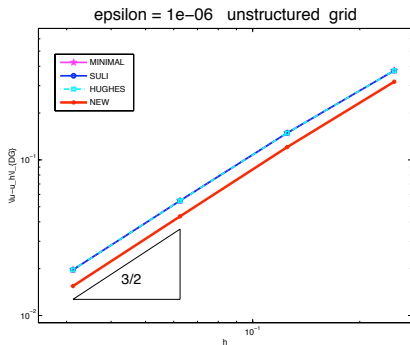
Convergence Diagrams: Smooth Solution



Convergence Diagrams: Unstructured Meshes

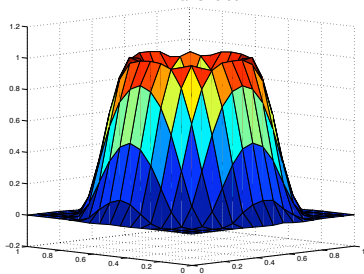


Convergence Diagrams: Smooth Solution

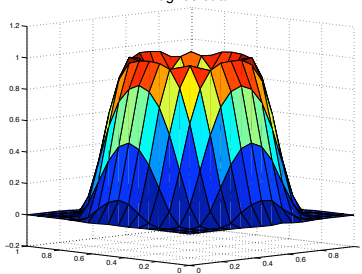


Rotating Flow $\varepsilon = 1e - 09$

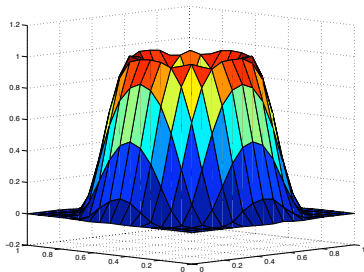
Minimal Choice



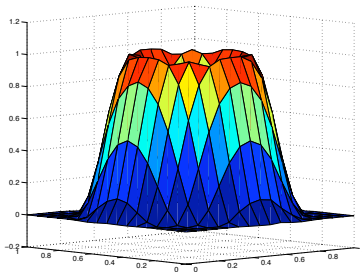
Hughes et al.



Suli et al.

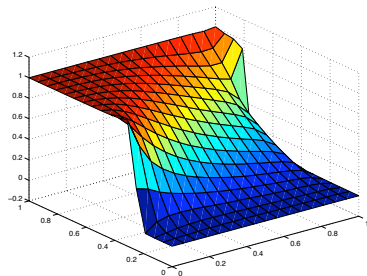


NEW

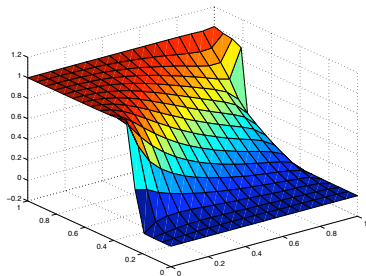


Internal Layer $\varepsilon = 0.1$

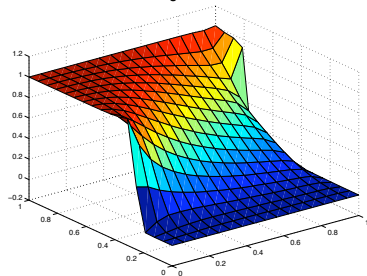
Minimal Choice



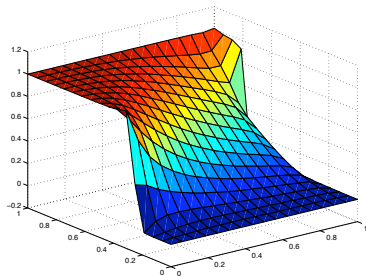
Suli et al.



Hughes et al.

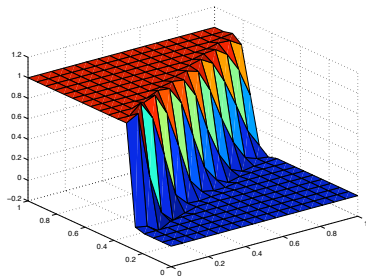


NEW

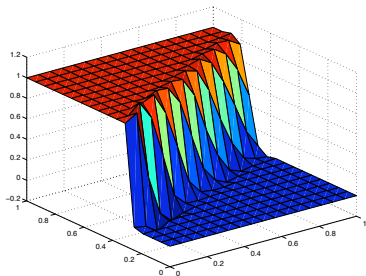


Internal Layer $\varepsilon = 0.001$

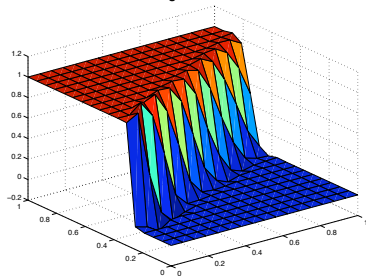
Minimal Choice



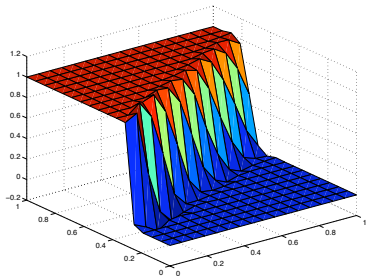
Suli et al.



Hughes et al.

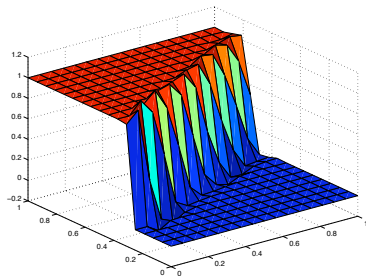


NEW

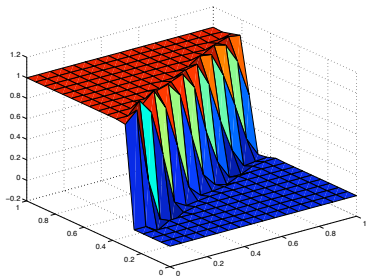


Internal Layer $\varepsilon = 1e - 06$

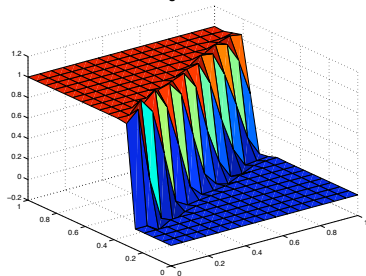
Minimal Choice



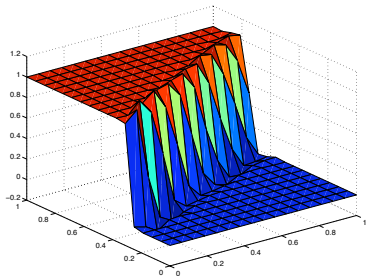
Suli et al.



Hughes et al.

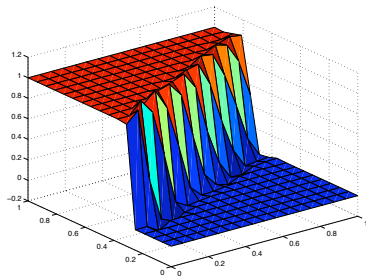


NEW

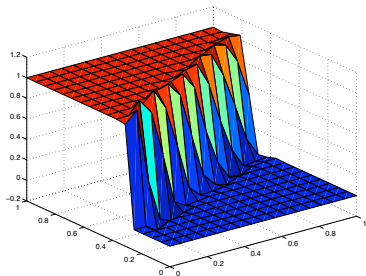


Internal Layer $\varepsilon = 1e - 09$

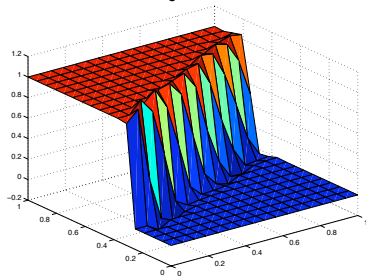
Minimal Choice



Suli et al.



Hughes et al.



NEW

