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Maurizio Grasselli a, Alain Miranville b, Riccarda Rossi c & Giulio Schimperna d

a Dipartimento di Matematica “F. Brioschi”, Politecnico di Milano, Milan, Italy
b Laboratoire de Mathématiques et Applications-SP2MI, Université de Poitiers, Chasseneuil-du-Poitou, France
c Dipartimento di Matematica, Università di Brescia, Brescia, Italy
d Dipartimento di Matematica “F. Casorati”, Università di Pavia, Pavia, Italy


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Analysis of the Cahn–Hilliard Equation with a Chemical Potential Dependent Mobility

MAURIZIO GRASSELLI¹, ALAIN MIRANVILLE², RICCARDA ROSSI³, AND GIULIO SCHIMPERNA⁴

¹Dipartimento di Matematica “F. Brioschi”, Politecnico di Milano, Milan, Italy
²Laboratoire de Mathématiques et Applications–SP2MI, Université de Poitiers, Chasseneuil-du-Poitou, France
³Dipartimento di Matematica, Università di Brescia, Brescia, Italy
⁴Dipartimento di Matematica “F. Casorati”, Università di Pavia, Pavia, Italy

The aim of this paper is to study the well-posedness and the existence of global attractors for a family of Cahn–Hilliard equations with a mobility depending on the chemical potential. Such models arise from generalizations of the (classical) Cahn–Hilliard equation due to Gurtin.

Keywords Cahn–Hilliard equation; Existence and uniqueness; Exponential attractors; Global attractors; Nonconstant mobility.

MSC 35K99; 35B41; 82C26.

1. Introduction

In this paper, we address the initial and boundary value problem for the following generalized Cahn–Hilliard equation:

\[ \chi_t - \Delta \tau (\delta \chi_t - \Delta \chi + \phi(\chi)) = 0 \text{ in } \Omega \times (0, T), \]  

where \( \delta \geq 0, \Omega \subset \mathbb{R}^3 \) is a bounded domain, \( T > 0 \) a finite time horizon and \( \tau : \mathbb{R} \rightarrow \mathbb{R} \) a strictly increasing function.

The classical Cahn–Hilliard equation reads

\[ \chi_t - \Delta w = 0, \quad w = -\Delta \chi + \phi(\chi) \text{ in } \Omega \times (0, T), \]  

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Address correspondence to Maurizio Grasselli, Dipartimento di Matematica “F. Brioschi”, Politecnico di Milano, Via Bonardi 9, I–20133, Milan, Italy; E-mail: maurizio.grasselli@polimi.it

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where $\chi$ is the order parameter (corresponding to a density of atoms), $w$ is the chemical potential (defined as a variational derivative of the free energy with respect to the order parameter), and $\phi$ is the derivative of a double-well potential. This equation plays an essential role in materials science and describes phase separation processes in binary alloys (see, e.g., [7, 8, 29]).

By considering a mechanical version of the second law of thermodynamics and introducing a new balance law for interactions at a microscopic level, Gurtin proposed in [20] the following equations:

$$\begin{cases}
\partial_t \chi - \text{div}(A(\chi, \nabla \chi, \chi, w) \nabla w) = 0, \\
w = \delta(\chi, \nabla \chi, w) \chi_t - \Delta \chi + \phi(\chi)
\end{cases} \quad \text{in } \Omega \times (0, T).$$

Taking $\delta$ constant and $A = a(w)I$, with $a : \mathbb{R} \to \mathbb{R}$ a positive function, we then obtain an equation of the form (1.1), in which $z$ is some primitive of the function $a$. In the following, we shall study (1.1) subject to the no-flux boundary conditions

$$\partial_n \chi = 0 \quad \text{and} \quad \partial_n (a(z)) = 0 \quad \text{on } \partial \Omega \times (0, T).$$

In the case when $z$ is linear, of course (1.1) reduces to (a reformulation of) the classical, and widely studied, Cahn–Hilliard model (1.2) (with viscosity if $\delta > 0$, see [28]). Even for this simple model, the mathematical literature is vast. Well-posedness, regularity properties of solutions, and their long-time behavior are nowadays rather well-understood. We just confine ourselves to quote some pioneering contributions [11, 19, 23, 27, 41, 43]. Moreover, (1.2) endowed with suitable boundary conditions (like, e.g., (1.3)) can be interpreted as a dissipative dynamical system on a suitable phase space. Such a system has a nontrivial behavior when its physical background is taken into account. This can be understood, for instance, by observing that the stationary problem may have a continuum of nonconstant solutions if $\phi$ is nonmonotone, i.e., the related potential is nonconvex. Thus the $\omega$-limit sets can exhibit a complicated structure and, a fortiori, the same is true for attractors. We recall that existence of global and exponential attractors has been proved, both in the viscous and in the non-viscous case, for a wide class of nonlinear functions $\phi$ (see, e.g., [12, 15, 16, 25, 39] and references therein). The stability properties of global and exponential attractors with respect to $\delta > 0$ has also been investigated. In particular, it has been established that the family of global attractors of the viscous equation is upper semicontinuous as $\delta \searrow 0$ (see [9, 17, 18]). On the other hand, we recall that there exist families of exponential attractors which are continuous as $\delta \searrow 0$ (cf. [16, 25]). A further type of results, motivated by the richness of the set of stationary states, is the convergence of a given trajectory to a single equilibrium. This issue has been firstly analyzed in [35] (cf. also, e.g., [1, 42]). We recall that the technique is based on the so-called Łojasiewicz-Simon inequality whose application requires $\phi$ to be real analytic. If the latter condition is not fulfilled, there are examples which show that the $\omega$-limit set can be a continuum (see [30]).

Considering the generalized model (1.1), the nonlinearity $z$ acts directly on second order derivatives of the unknown. Hence, it is no longer possible to rewrite the equation as a coupled semilinear system as in the case (1.2). For this reason, a mathematical study of (1.1) is more challenging, even when the basic question of existence of a weak solution is addressed. Actually, careful approximation and monotonicity methods are required in order to obtain suitable $a$ priori estimates
of the nonlinear terms in (1.1). Concerning uniqueness, regularity, and long-
time behavior of solutions, it is reasonable to expect that most of the results
and techniques available for the standard Cahn–Hilliard equation could not be
reproduced for (1.1).

The first results on equation (1.1) (both with the boundary conditions (1.3) and
with third type boundary conditions on the chemical potential \( \psi \)), in the case of a
genuinely nonlinear function \( \alpha \), were obtained in the viscous case \( \delta > 0 \) in [32, 33].
Therein, the well-posedness for the initial-boundary value problem for (1.1) and the
existence of the global attractor were proved.

Our main aim in this paper is, first of all, to address the problem given by
(1.1), (1.3) plus the initial conditions, when \( \delta = 0 \). To the best of our knowledge,
this situation has not yet been analyzed when the function \( \alpha \) is nonlinear. Actually,
the case \( \delta = 0 \) appears to be significantly more difficult, mainly due to the fact
that the time derivative \( \chi_t \) can only be estimated in a negative order Sobolev space
and, consequently, the regularity satisfied by weak solutions is rather poor. Here we
prove the existence of such weak solutions in Theorem 1, provided \( \alpha \) and \( \phi \) satisfy
suitable assumptions.

We also consider the viscous case \( \delta > 0 \) under different (and more general)
conditions on \( \alpha \) and \( \phi \) from those in [32, 33], and we first obtain an existence result
(see Theorem 2). In the viscous setting, under more restrictive assumptions on \( \alpha \)
and \( \phi \), we also prove (cf. Theorems 3.1 and 3.2) well-posedness and continuous
dependence results for (1.1), (1.3) with initial condition. A close perusal of the proofs
of Theorems 3.1 and 3.2 shows that our continuous dependence estimates cannot be
extended to the non-viscous case (i.e., when \( \delta = 0 \)), essentially due to the nonlinear
character of the function \( \alpha \) and to the weaker regularity of solutions. In this case,
establishing uniqueness of solutions also remains an open problem.

For \( \delta > 0 \) we are also able to study the asymptotic behavior of the system and
establish the existence of the global attractor (see Theorem 3) for a rather general
class of \( \alpha \) and \( \phi \), which may allow for non-uniqueness of solutions. That is why,
for this long-time analysis we rely on the notion of generalized semiflows proposed
by Ball in [3] and on the extension given in [34]. Of course, in that frame, the
global attractor turns out to be a very general object, with rather weak regularity
properties. It is then far from being clear what is its dependence on \( \delta \) and, in
particular, its behavior as \( \delta \downarrow 0 \). Actually, in the non-viscous case \( \delta = 0 \), due to the
apparent lack of any type of energy equality, the best that one could expect is the
existence of a weak trajectory attractor (i.e., of a trajectory attractor with respect
to a topology weaker than that characterizing the phase space), in the sense of
Chepyzhov and Vishik [10]. Thus, any type of analysis of the stability of attractors
with respect to \( \delta \downarrow 0 \) should be addressed in that very weak frame.

On the other hand, still in the viscous case, but under more restrictive
hypotheses on \( \alpha \) and \( \phi \) (entailing in particular uniqueness of solutions for positive
times), relying on the short-trajectory approach developed in [24] we can prove the
existence of exponential attractors and, thus, of finite-dimensional global attractors.
We recall that an exponential attractor is a compact and semi-invariant set which
has finite fractal dimension and attracts the trajectories exponentially fast; note that
the global attractor may attract the trajectories at a slow (polynomial) rate (see, e.g.,
[2, 14, 26]). Still, it is unlikely that these results could be extended to the case \( \delta = 0 \),
where any form of contractive estimate is apparently lost.
Summing up, our results seem to indicate that the non-viscous case is far more difficult than the viscous one when the mobility depends non-linearly on the chemical potential.

This paper is organized as follows. In Section 2, we define our notation and give some preliminary results. Then, in Section 3, we state our main theorems whose proofs are carried out in the remaining sections. Finally, in the Appendix, we introduce the approximation scheme for our problem and justify the a priori estimates (formally) developed throughout the paper.

2. Preliminaries

Notation and functional setup. Throughout the paper, we consider a bounded domain \( \Omega \subset \mathbb{R}^3 \), with sufficiently smooth boundary \( \partial \Omega \), and write \( |\theta| \) for the Lebesgue measure of any (measurable) subset \( \theta \subset \Omega \). Furthermore, given a Banach space \( B \), we denote by \( \| \cdot \|_B \) the norm in \( B \) and by \( \langle \cdot, \cdot \rangle_B \) the duality pairing between \( B' \) and \( B \). We use the notation

\[
H := L^2(\Omega), \quad V := H^1(\Omega), \quad Z := \{ v \in H^2(\Omega) : \partial_n v = 0 \},
\]

and identify \( H \) with its dual space \( H' \), so that \( Z \subset V \subset H \subset V' \subset Z' \), with dense and compact embeddings. We denote by \( H, \mathcal{V}, \mathcal{X}, \mathcal{V}', \) and \( \mathcal{X}' \) the subspaces of the elements \( v \) of \( H, V, Z, V' \), and \( Z' \), respectively, with zero mean value \( m(v) = \frac{1}{|\Omega|} \langle v, 1 \rangle_Z \). We consider the operator

\[
A : V \to V', \quad \langle Au, v \rangle_V := \int_\Omega \nabla u \cdot \nabla v \quad \forall u, v \in V, \quad (2.1)
\]

and note that \( Au \in \mathcal{V}' \) for every \( u \in V \). Indeed, the restriction of \( A \) to \( \mathcal{V}' \) is an isomorphism, so that we can introduce its inverse operator \( \mathcal{N} : \mathcal{V}' \to \mathcal{V} \). We recall the relations

\[
\langle Au, N(v) \rangle_V = \langle v, u \rangle_V \quad \forall u \in V, \quad \forall v \in \mathcal{V}', \quad (2.2)
\]

\[
\langle u, \mathcal{N}(v) \rangle_V = \int_\Omega \nabla(N(u)) \cdot \nabla(N(v)) \, dx = \langle v, \mathcal{N}(u) \rangle_V \quad \forall u, v \in \mathcal{V}', \quad (2.3)
\]

and that, on account of Poincaré’s inequality for zero mean value functions, the following norms on \( V \) and \( V' \):

\[
\|u\|_V^2 := \langle Au, u \rangle_V + m(u)^2 \quad \forall u \in V,
\]

\[
\|v\|_{V'}^2 := \langle v, \mathcal{N}(v - m(v)) \rangle_V + m(v)^2 \quad \forall v \in V',
\]

are equivalent to the standard ones. It follows from the above formulae that

\[
\|v\|_{V'}^2 = \langle v, \mathcal{N}(v) \rangle_V = \|\mathcal{N}(v)\|_V^2 \quad \forall v \in \mathcal{V}'.
\]

It is well known that the operator \( A \) (2.1) extends to an operator (which will be denoted by the same symbol) \( A : H \to \mathcal{X}' \). The inverse of the restriction of \( A \) to \( \mathcal{X} \)
is the extension of $\mathcal{N}$ to an operator $\mathcal{N} : \mathcal{L}' \to \mathcal{H}$. By means of the latter, we define the space

$$\mathcal{W}^{-2,q}(\Omega) := \{ v \in \mathcal{L} : \mathcal{N}(v) \in L^q(\Omega) \} \text{ for a given } q > 1,$$

with the norm $\| v \|_{\mathcal{W}^{-2,q}(\Omega)} := \| \mathcal{N}(v) \|_{L^q(\Omega)}$. \hfill (2.4)

The following result shows that, for $q \in (2, 6)$ (which is the index range relevant to the analysis to be developed in what follows, cf. (3.7)), the space $\mathcal{W}^{-2,q}(\Omega)$ can be identified with the dual of the space

$$\mathcal{W}^{2,q}(\Omega) = \{ z \in \mathcal{V} : Az \in L^q(\Omega) \},$$

$q'$ being the conjugate exponent of $q$. We endow the latter space with the norm $\| z \|_{\mathcal{W}^{2,q}(\Omega)} := \| Az \|_{L^q(\Omega)}$, which is equivalent to the standard $\mathcal{W}^{2,q}$-norm by the (generalized) Poincaré inequality.

**Lemma 2.1.** For $q \in (2, 6)$, the operator $J : \mathcal{W}^{-2,q}(\Omega) \to (\mathcal{W}^{2,q}(\Omega))'$ defined by

$$\langle (\mathcal{W}^{2,q}(\Omega))'(J(v), z)_{\mathcal{W}^{2,q}(\Omega)'}, z \rangle_{\mathcal{W}^{2,q}(\Omega)} := \langle v', \langle Az, v \rangle \rangle_{V}$$

for all $z \in \mathcal{W}^{2,q}(\Omega)$ and $v \in \mathcal{W}^{-2,q}(\Omega)$ \hfill (2.5)

is an isomorphism.

**Proof.** We preliminarily note that, since $q \in (2, 6)$, the conjugate exponent $q'$ belongs to $(6/5, 2)$ and, consequently, one has the following embeddings:

$$\mathcal{H} \subset \mathcal{V}' \subset \mathcal{W}^{-2,q}(\Omega), \quad L^q(\Omega) \subset \mathcal{V}', \quad \mathcal{L} \subset \mathcal{W}^{2,q}(\Omega). \hfill (2.6)$$

Clearly, the operator $J$ is well defined, linear, and continuous, since, for all $z \in \mathcal{W}^{2,q}(\Omega)$ and $v \in \mathcal{W}^{-2,q}(\Omega)$,

$$\| (\mathcal{W}^{2,q}(\Omega))'(J(v), z)_{\mathcal{W}^{2,q}(\Omega)'} \|_{(\mathcal{W}^{2,q}(\Omega))'} \leq \| Az \|_{L^q(\Omega)} \| N(v) \|_{L^q(\Omega)} \leq \| z \|_{\mathcal{W}^{2,q}(\Omega)} \| v \|_{\mathcal{W}^{-2,q}(\Omega)}.$$

(2.7)

Furthermore, for every $v \in \mathcal{W}^{-2,q}(\Omega)$, one can choose $z_v = \mathcal{N}([N(v)]^{q-2}N(v))$ (note that $z_v$ is well defined and belongs to $\mathcal{V}$, since $[N(v)]^{q-2}N(v) \in L^q(\Omega) \subset \mathcal{V}'$ by the second of (2.6)). Then,

$$\langle (\mathcal{W}^{2,q}(\Omega))'(J(v), z_v)_{\mathcal{W}^{2,q}(\Omega)'}, z_v \rangle_{\mathcal{W}^{2,q}(\Omega)} = \| N(v) \|_{L^q(\Omega)}^q,$$

$$\| Az_v \|_{L^q(\Omega)} = \| [N(v)]^{q-2}N(v) \|_{L^q(\Omega)} = \| N(v) \|_{L^q(\Omega)}^{q-1},$$

so that

$$\| J(v) \|_{(\mathcal{W}^{2,q}(\Omega))'} \geq \frac{\| (\mathcal{W}^{2,q}(\Omega))'(J(v), z_v)_{\mathcal{W}^{2,q}(\Omega)'} \|_{\mathcal{W}^{2,q}(\Omega)'} \| z_v \|_{\mathcal{W}^{2,q}(\Omega)'} \| z_v \|_{\mathcal{W}^{2,q}(\Omega)}}{\| z_v \|_{\mathcal{W}^{2,q}(\Omega)}},$$

$$= \frac{\| N(v) \|_{L^q(\Omega)}^q}{\| N(v) \|_{L^q(\Omega)}^{q-1}} = \frac{\| N(v) \|_{L^q(\Omega)}^q}{\| N(v) \|_{L^q(\Omega)}^{q-1}} = \| v \|_{\mathcal{W}^{-2,q}(\Omega)}.$$
In view of (2.7), we conclude that $J$ is an isometry. In particular, it is injective and the image $J(W^{-2,q}(\Omega))$ is closed in $(W^{-2,q}(\Omega))'$. To conclude that $J$ is surjective, we will prove that

$$J(W^{-2,q}(\Omega)) \text{ is dense in } (W^{-2,q}(\Omega))'. \tag{2.8}$$

Indeed, let $\bar{z} \in W^{-2,q}(\Omega)$ be such that

$$(W^{-2,q}(\Omega))' \langle J(v), \bar{z} \rangle_{W^{-2,q}(\Omega)} = 0 \text{ for all } v \in W^{-2,q}(\Omega). \tag{2.9}$$

In particular, (2.9) holds for all $v \in \mathbb{H}$, so that, also in view of (2.2),

$$0 = \langle A\bar{z}, N(v) \rangle_v = \langle v, \bar{z} \rangle_v = \int_\Omega \bar{z} v \text{ for all } v \in \mathbb{H}.$$ 

From the above relation, we easily conclude that $\bar{z} = 0$, whence (2.8). $\square$

A generalization of Poincaré’s inequality. The following result will play an important role in the derivation of the a priori estimates of Section 4.1.

**Lemma 2.2.** Let $X$ and $Y$ be Banach spaces, with $X$ reflexive, and assume that

$$X \subset Y \text{ with compact embedding.} \tag{2.10}$$

Consider

$$G : X \to Y \text{ a linear, weakly-weakly continuous functional,} \tag{2.11}$$

$$\Psi : X \to [0, +\infty) \text{ a } 1\text{-positively homogeneous, sequentially weakly lower-semicontinuous functional.} \tag{2.12}$$

Assume that $G$ and $\Psi$ comply with the following compatibility condition: for all $v \in X$,

$$Gv = 0 \text{ and } \Psi(v) = 0 \Rightarrow v = 0, \tag{2.13}$$

and that

$$\exists C \geq 1 : \ \forall v \in X \ \frac{1}{C}(\|v\|_Y + \|Gv\|_Y) \leq \|v\|_X \leq C(\|v\|_Y + \|Gv\|_Y). \tag{2.14}$$

Then,

$$\exists K > 0 : \ \forall v \in X \ \|v\|_X \leq K(\|Gv\|_Y + \Psi(v)). \tag{2.15}$$

**Proof.** Assume, by contradiction, that (2.15) does not hold: then, there exists a sequence $\{v_n\} \subset X$ such that, for every $n \in \mathbb{N}$,

$$\|v_n\|_X > n(\|Gv_n\|_Y + \Psi(v_n)). \tag{2.16}$$
In particular, this yields that \( \|v_n\|_X \neq 0 \) for all \( n \). Letting \( w_n := \frac{v_n}{\|v_n\|_X} \) and using the 1-homogeneity of \( \Psi \), we deduce from (2.16) that

\[
\|Gw_n\|_Y + \Psi(w_n) < \frac{1}{n} \quad \text{for every } n \in \mathbb{N},
\]

giving

\[
Gw_n \to 0 \text{ in } Y \quad \text{and} \quad \Psi(w_n) \to 0 \text{ as } n \to +\infty. \tag{2.17}
\]

On the other hand, by the reflexivity of \( X \), there exists a subsequence \( \{w_{n_k}\} \) weakly converging in \( X \) to some \( \bar{w} \). In view of (2.10)–(2.12), we find

\[
w_{n_k} \rightharpoonup w \text{ in } Y, \quad Gw_{n_k} \rightharpoonup Gw \text{ in } Y, \quad \Psi(w) \leq \lim_{k \to +\infty} \Psi(w_{n_k}).
\]

Hence, (2.17) yields that \( Gw = 0 \) and \( \Psi(w) = 0 \), so that, by (2.13), \( w = 0 \). Thus, by (2.14) and (2.17),

\[
\lim_{k \to +\infty} \|w_{n_k}\|_X \leq C \lim_{k \to +\infty} (\|w_{n_k}\|_Y + \|Gw_{n_k}\|_Y) = 0,
\]

in contrast with the fact that \( \|w_n\|_X = 1 \) for all \( n \in \mathbb{N} \).

A compactness criterion. Let

\[
\emptyset \subset \mathbb{R}^d, \ d \geq 1, \ \text{be an open set with } |\emptyset| < +\infty, \quad B \text{ a separable Banach space, and } 1 \leq p < +\infty. \tag{2.18}
\]

We recall that a sequence \( \{u_n\} \subset L^p(\emptyset; B) \) is \( p \)-uniformly integrable (or simply uniformly integrable if \( p = 1 \)) if

\[
\forall \varepsilon > 0 \ \exists \delta > 0 : \ \forall J \subset \emptyset \ |J| < \delta \Rightarrow \sup_{n \in \mathbb{N}} \int_J \|u_n(y)\|^p_B \, dy \leq \varepsilon. \tag{2.19}
\]

We quote the following result (cf. [13, Theorem III.6]) which will be extensively used in what follows.

**Theorem 2.1.** In the setting of (2.18), given a sequence \( \{u_n\} \subset L^p(\emptyset; B) \), assume that there exist a subsequence \( \{u_{n_k}\} \) and a measurable function \( u : \emptyset \to B \) such that

\[
u_{n_k}(y) \to u(y) \text{ in } B \text{ for almost all } y \in \emptyset.
\]

Then, \( u_{n_k} \to u \) in \( L^p(\emptyset; B) \) if and only if it is \( p \)-uniformly integrable.

Finally, for the reader’s convenience, here below we report the celebrated lower semicontinuity result due to Ioffe [22].

**Theorem 2.2.** Let \( f : \emptyset \times \mathbb{R}^n \times \mathbb{R}^m \to [0, +\infty] \), \( n, m \geq 1 \), be a measurable non-negative function such that

\[
f(x, \cdot, \cdot) \text{ is lower semicontinuous on } \mathbb{R}^n \times \mathbb{R}^m \text{ for every } x \in \emptyset, \tag{2.20}
\]
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\[ f(x, u, \cdot) \text{ is convex on } \mathbb{R}^m \text{ for every } (x, u) \in \Theta \times \mathbb{R}^n. \]  \hfill (2.21)

Let \((u_k, v_k, (u, v)) : \Theta \rightarrow \mathbb{R}^n \times \mathbb{R}^m\) be measurable functions such that

\[ u_k(x) \rightarrow u(x) \text{ in measure in } \Theta, \quad v_k \rightharpoonup v \text{ weakly in } L^1(\Theta; \mathbb{R}^m). \]

Then,

\[ \liminf_{k \to +\infty} \int_{\Theta} f(x, u_k(x), v_k(x)) dx \geq \int_{\Theta} f(x, u(x), v(x)) dx. \]  \hfill (2.22)

### 2.1. Global Attractors for Generalized Semiflows

As mentioned in the introduction, in order to study the long-time behavior of solutions to the generalized Cahn–Hilliard equation (1.1) (supplemented with the boundary conditions (1.3)) in the viscous case, we rely on the theory of generalized semiflows introduced by Ball in [3]. In order to make this paper as self-contained as possible, in this section we recall the main definitions and results of this theory, closely following [3].

**Notation 2.3.** The phase space is a (not necessarily complete) metric space \((X, d_X)\), the distance \(d_X\) inducing the Hausdorff semidistance \(e\) of two non-empty subsets \(A, B \subset X\) by the formula

\[ e(A, B) = \sup_{a \in A} \inf_{b \in B} d_X(a, b). \]

**Definition 2.4 (Generalized Semiflow).** A generalized semiflow \(\mathcal{S}\) on \(X\) is a family of maps \(g : [0, +\infty) \rightarrow X\) (referred to as “solutions”) satisfying the following properties:

- **(P1) (Existence)** for any \(g_0 \in X\), there exists at least one \(g \in \mathcal{S}\) such that \(g(0) = g_0\);

- **(P2) (Translates of solutions are solutions)** for any \(g \in \mathcal{S}\) and \(\tau \geq 0\), the map \(g^\tau(t) := g(t + \tau), t \in [0, +\infty)\), belongs to \(\mathcal{S}\);

- **(P3) (Concatenation)** for any \(g, h \in \mathcal{S}\) and \(\tau \geq 0\) with \(h(0) = g(\tau)\), then \(z \in \mathcal{S}\), \(z\) being the map defined by

\[ z(t) := \begin{cases} g(t) & \text{if } 0 \leq t \leq \tau, \\ h(t - \tau) & \text{if } t > \tau; \end{cases} \]  \hfill (2.23)

- **(P4) (Upper-semicontinuity with regards to the initial data)** if \(\{g_n\} \subset \mathcal{S}\) and \(g_n(0) \rightarrow g_0\), then there exist a subsequence \(\{g_{n_k}\}\) of \(\{g_n\}\) and \(g \in \mathcal{S}\) such that \(g(0) = g_0\) and \(g_{n_k}(t) \rightarrow g(t)\) for all \(t \geq 0\).

**Orbits, \omega\)-limits and attractors.** Given a solution \(g \in \mathcal{S}\), we recall that the \(\omega\)-limit \(\omega(g)\) of \(g\) is defined by

\[ \omega(g) := \{x \in X : \exists \{t_n\} \subset [0, +\infty), t_n \rightarrow +\infty, \text{ such that } g(t_n) \rightarrow x\}. \]
Similarly, the \( \omega \)-limit of a set \( E \subset X \) is given by

\[
\omega(E) := \{ x \in X : \exists \{g_n\} \subset \mathcal{F} \text{ such that } \{g_n(0)\} \subset E, \{g_n(0)\} \text{ is bounded, and } \\
\exists \{t_n\} \subset [0, +\infty), t_n \to +\infty, \text{ such that } g_n(t_n) \to x \}.
\]

Furthermore, we say that \( w : \mathbb{R} \to X \) is a complete orbit if, for any \( s \in \mathbb{R} \), the translate map \( w' \), restricted to the positive half-line \( [0, +\infty) \), belongs to \( \mathcal{F} \). For every \( t \geq 0 \), we can introduce the operator \( T(t) : 2^X \to 2^X \) by setting

\[
T(t)E := \{ g(t) : g \in \mathcal{F} \text{ with } g(0) \in E \} \quad \text{for all } E \subset X,
\]

and define, for \( \tau \geq 0 \), the set

\[
\gamma^\tau(E) := \bigcup_{t \geq \tau} T(t)E.
\]

The family of operators \( \{T(t)\}_{t \geq 0} \) defines a semigroup on the power set \( 2^X \). Given subsets \( U, E \subset X \), we say that \( U \) attracts \( E \) if \( e(T(t)E, U) \to 0 \) as \( t \to +\infty \). Furthermore, we say that \( U \) is fully invariant if \( T(t)U = U \) for every \( t \geq 0 \). Finally, a set \( \mathcal{A} \subset X \) is the global attractor for \( \mathcal{F} \) iff it is compact, fully invariant under \( \mathcal{F} \), and attracts all the bounded sets of \( X \).

Compactness and dissipativity properties. Let \( \mathcal{F} \) be a generalized semiflow. We say that \( \mathcal{F} \) is:

1. **eventually bounded** iff, for every bounded set \( B \subset X \), there exists \( \tau \geq 0 \) such that \( \gamma^\tau(B) \) is bounded;
2. **point dissipative** iff there exists a bounded set \( B_0 \subset X \) such that, for any \( g \in \mathcal{F} \), there exists \( \tau \geq 0 \) such that \( g(t) \in B_0 \) for all \( t \geq \tau \). The set \( B_0 \) is then called a (pointwise) absorbing set;
3. **compact** iff, for any sequence \( \{g_n\} \subset \mathcal{F} \) with \( \{g_n(0)\} \) bounded, there exists a subsequence \( \{g_{n_k}\} \) such that \( \{g_{n_k}(t)\} \) is convergent for any \( t > 0 \).

We note that the notions that we have just introduced are not independent one from another (cf. [3, Propositions 3.1 and 3.2] for more details).

**Lyapunov function.** The notion of a Lyapunov function can be introduced starting from the following definitions: we say that a complete orbit \( g \in \mathcal{F} \) is stationary if there exists \( x \in X \) such that \( g(t) = x \) for all \( t \in \mathbb{R} \) such an \( x \) is then called a rest point. Note that the set of rest points of \( \mathcal{F} \), denoted by \( Z(\mathcal{F}) \), is closed in view of (P4). A function \( V : X \to \mathbb{R} \) is said to be a Lyapunov function for \( \mathcal{F} \) if \( V \) is continuous, \( V(g(t)) \leq V(g(s)) \) for all \( g \in \mathcal{F} \) and \( 0 \leq s \leq t \) (i.e., \( V \) decreases along all solutions), and, whenever the map \( t \mapsto V(g(t)) \) is constant for some complete orbit \( g \), then \( g \) is a stationary orbit.

**Existence of the global attractor.** The following theorem subsumes the main results from [3] (cf. Theorems 3.3, 5.1, and 6.1 therein) and provides the basic criteria for the existence of the global attractor \( \mathcal{A} \) for a generalized semiflow \( \mathcal{F} \).
Theorem 2.3. Let $\mathcal{F}$ be an eventually bounded and compact generalized semiflow. Assume that $\mathcal{F}$ also admits a Lyapunov function $V$ and that

the set of its rest points $Z(\mathcal{F})$ is bounded. \hfill (2.25)

Then, $\mathcal{F}$ is also point dissipative, and, consequently, it possesses a global attractor. Moreover, the attractor $\mathcal{A}$ is unique, it is the maximal compact fully invariant subset of $X$, and it can be characterized as

$$\mathcal{A} = \bigcup \{ \omega(B) : B \subset X \text{ bounded} \} = \omega(X). \hfill (2.26)$$

Finally, for every $g \in \mathcal{F},$

$$\omega(g) \subset Z(\mathcal{F}). \hfill (2.27)$$

Remark 2.5. Actually, it is immediate to check that, if $\mathcal{F}$ is compact, eventually bounded, and admits a Lyapunov function, then condition (2.25) can be replaced by

$$\exists \mathcal{D} \subset X, \mathcal{D} \neq \emptyset, \text{ such that } \begin{cases} T(t) \mathcal{D} \subset \mathcal{D} \quad \forall t \geq 0, \\ \text{the set } Z(\mathcal{F}) \cap \mathcal{D} \text{ is bounded in } X. \end{cases} \hfill (2.28)$$

Then, under these hypotheses, $\mathcal{F}$ also possesses a (unique) global attractor $\mathcal{A} \subset \mathcal{D}$ and (2.27) holds.

3. Main Results

3.1. A Global Existence Result for the Non-Viscous Problem

Assumptions on the nonlinearities. We assume that

$$x : \mathbb{R} \rightarrow \mathbb{R} \quad \text{is a strictly increasing, differentiable function such that}$$

$$\exists p \geq 0, \quad \exists C_1, C_2 > 0 : \quad \forall r \in \mathbb{R}$$

$$C_1(|r|^{2p} + 1) \leq x'(r) \leq C_2(|r|^{2p} + 1). \hfill (H1)$$

Clearly, the latter growth condition entails that

$$\exists C_3, C_4, C_5 > 0 : \quad \forall r \in \mathbb{R} \quad C_3|r|^{2p+1} - C_4 \leq x(r) \text{sign}(r) \leq C_5(|r|^{2p+1} + 1). \hfill (3.1)$$

Concerning the nonlinearity $\phi$, we require that

$$\text{dom}(\phi) = I, \quad I \text{ being an open, possibly unbounded, interval } (a, b),$$

$$-\infty \leq a < 0 < b \leq +\infty,$$

$$\phi \in C^1(I), \quad \text{(H2)}$$

$$\lim_{r \searrow a} \phi(r) = -\infty, \quad \lim_{r \nearrow b} \phi(r) = +\infty,$$

$$\lim_{r \searrow a} \phi'(r) = \lim_{r \nearrow b} \phi'(r) = +\infty.$$
We shall denote by \( \hat{\phi} \) (one of) the antiderivative(s) of \( \phi \). It follows from the above assumptions that \( \hat{\phi} \) is bounded from below. Hereafter, for the sake of simplicity, we assume that
\[
\hat{\phi}(r) \geq 0 \quad \text{for all } r \in I. \tag{3.2}
\]
Furthermore, (H2) obviously yields that
\[
\exists C_{\phi,1} > 0 : \forall r \in I \quad \phi'(r) \geq -C_{\phi,1}, \tag{3.3}
\]
namely, \( \phi \) is a Lipschitz perturbation of a non-decreasing function. In particular, we will use the fact that there exists a non-decreasing function \( \beta : I \to \mathbb{R} \) such that
\[
\phi(r) = \beta(r) - C_{\phi,1}r \quad \forall r \in I. \tag{3.4}
\]
Consequently, \( \hat{\phi} \) is a quadratic perturbation of a convex function. Arguing in the very same way as in [25] (where the case \( I = (-1, 1) \) was considered), it can be proved that, under these conditions, the following crucial estimate holds:
\[
\forall m \in (a, b) \quad \exists C_m, C'_m > 0 : \forall r \in (a - m, b - m) \quad |\phi(r + m)| \leq C_m \phi(r + m) r + C'_m. \tag{3.5}
\]
Finally, we also assume that
\[
\exists \sigma \in (0, 1), \quad \exists C_\sigma > 0 : \forall r \in (a, b) \quad |\phi(r)|^\sigma \leq C_\sigma (\hat{\phi}(r) + 1), \tag{H3}
\]
and that the following compatibility condition holds between \( \sigma \) and the growth index \( p \) of \( \sigma \) in (H1):
\[
\sigma > \max \left\{ \frac{6p - 3}{6p + 2}, 0 \right\}. \tag{H4}
\]
Hence, if \( p \leq 1/2 \), then any \( \sigma \in (0, 1) \) is admissible, while if, for instance, \( p = 1 \), then the range of admissible \( \sigma \)'s is \((3/8, 1)\), and it is \((9/14, 1)\) for \( p = 2 \).

**Notation 3.1.** Hereafter, we will use, for every \( p \geq 0 \), the short-hand notation
\[
\rho_p := \frac{2p + 2}{2p + 1}, \quad \kappa_p := \frac{6p + 6}{2p + 1}, \quad \eta_{p\sigma} = \frac{6 - \sigma}{(3 - 3\sigma)(2p + 1)}. \tag{3.6}
\]
For later convenience, we note that \( \rho_p \) and \( \kappa_p \) are decreasing functions of \( p \) and
\[
1 < \rho_p < 2, \quad 3 < \kappa_p < 6 \quad \text{for every } p \geq 0. \tag{3.7}
\]
Furthermore, it can be checked that
\[
\eta_{p\sigma} > 1 \quad \text{for every } p \geq 0 \text{ and for all } \sigma > \max \left\{ \frac{6p - 3}{6p + 2}, 0 \right\}. \tag{3.8}
\]
The existence result. We are now able to give the variational formulation of the boundary value problem associated with (1.1)–(1.3) in the non-viscous case.

**Problem 1.** Find a pair \((\chi, w)\) fulfilling
\[
\chi_t + A(\chi(\alpha(w))) = 0 \quad \text{in} \quad W^{2,2}_{\gamma}(\Omega) \text{ a.e. in } (0, T),
\]
\[
A\chi + \phi(\chi) = w \quad \text{a.e. in } \Omega \times (0, T).
\]

Note that, owing to Lemma 2.1, (3.9) is equivalent to
\[
W^{2,2}_{\gamma}(\Omega) \langle \chi_t, v \rangle_{W^{2,2}_{\gamma}(\Omega)} + W^{2,2}_{\gamma}(\Omega) \langle A(\alpha(w)), v \rangle_{W^{2,2}_{\gamma}(\Omega)} = 0
\]
for all \(v \in W^{2,2}_{\gamma}(\Omega)\) a.e. in \((0, T)\).

**Theorem 1.** Under assumptions (H1)–(H4), for every initial datum \(\chi_0\) satisfying
\[
\chi_0 \in V, \quad \hat{\phi}(\chi_0) \in L^1(\Omega),
\]
there exists at least a solution \((\chi, w)\) to Problem 1, with the regularity
\[
\chi \in L^2(0, T; W^{2,6}(\Omega)) \cap L^{\infty}(0, T; V), \quad \chi_t \in L^{6r}(0, T; W^{2,2r}(\Omega)),
\]
\[
w \in L^2(0, T; V), \quad \alpha(w) \in L^{6r}(0, T; L^{2r}(\Omega)),
\]
fulfilling the initial condition
\[
\chi(0) = \chi_0 \quad \text{in } V.
\]

A formal proof of this result will be developed in Section 4 and rigorously justified in Appendix.

### 3.2. A Global Existence Result for the Viscous Problem

We replace our assumptions (H2)–(H4) on \(\phi\) and its antiderivative \(\hat{\phi}\) by
\[
\hat{\phi} : \mathbb{R} \to \mathbb{R} \quad \text{belongs to } C^2(\mathbb{R}) \quad \text{and satisfies}
\]
\[
\exists C_7 > 0 : \quad \forall r \in \mathbb{R} \quad |\phi(r)| \leq C_7(\hat{\phi}(r) + 1).
\]

The latter assumption means that we consider potentials with at most an exponential growth at \(\infty\), and it clearly yields that \(\hat{\phi}\) is bounded from below. Hence, as in (3.2), we again assume that \(\hat{\phi}\) takes non-negative values. Furthermore, as in the non-viscous case we require that
\[
\exists C_{\phi,2} > 0 : \forall r \in \mathbb{R} \quad \phi'(r) \geq -C_{\phi,2}.
\]

This and (H5) imply that the map
\[
r \in \mathbb{R} \mapsto \hat{\phi}(r) + \frac{C_{\phi,2}}{2} r^2
\]
is convex and bounded from below.
Remark 3.2. Let us point out that (3.16) yields
\[
|\dot{\phi}(r)| \leq |\dot{\phi}(0)| + |\phi(r)||r| + \frac{C_{\phi,2}}{2}r^2 \quad \text{for all } r \in \mathbb{R}.
\] (3.17)

Indeed, it follows from (3.16) and an elementary convexity inequality that, for every \( r \in \mathbb{R} \),
\[
\dot{\phi}(0) - \dot{\phi}(r) - \frac{C_{\phi,2}}{2}r^2 \geq -r(\phi(r) + C_{\phi,2}r),
\]
whence we deduce (3.17) by straightforward algebraic manipulations.

We will address the analysis of the Cahn–Hilliard equation (1.1) with the boundary conditions (1.3) in the viscous case under the aforementioned assumptions. The related variational formulation reads

**Problem 2.** Given \( \delta > 0 \), find a pair \((\chi, w)\) fulfilling
\[
\chi_t + A(\chi(w)) = 0 \quad \text{a.e. in } \Omega \times (0, T),
\] (3.18)
\[
\delta \chi_t + A\chi + \phi(\chi) = w \quad \text{a.e. in } \Omega \times (0, T).
\] (3.19)

*The existence result.*

**Theorem 2.** Assume (H1), (H5), and (H6). Then, for every initial datum \( \chi_0 \) complying with (3.12), there exists at least a solution \((\chi, w)\) to Problem 2, with the regularity
\[
\chi \in L^2(0, T; Z) \cap L^\infty(0, T; V) \cap H^1(0, T; H),
\] (3.20)
\[
w \in L^2(0, T; V) \cap L^{2p+2}(0, T; L^\infty(\Omega)), \quad \chi(w) \in L^{p^*}(0, T; Z),
\] (3.21)
and such that \( \chi \) satisfies the initial condition (3.15).

We refer to Section 4 for a formal proof of Theorem 2 and to Appendix for all rigorous calculations.

In addition, we also have the following regularity result, which plays a key role in Section 3.4.

**Proposition 3.3.** Assume (H1), (H5), and (H6). Assume that, in addition, \( \phi \) satisfies
\[
\hat{\phi} \in C^2(\mathbb{R}) \quad \text{and} \quad \exists C_{\phi,3} > 0 : \quad \forall r \in \mathbb{R} \quad |\phi'(r)| \leq C_{\phi,3}(1 + |r|^3).
\] (3.22)

Then, for all \( 0 < \tau < T \), the pair \((\chi, w)\) has the further regularity
\[
\chi \in L^\infty(\tau, T; Z) \cap H^1(\tau, T; V),
\] (3.23)
\[
\chi(w) \in L^{p^*}(\tau, T; H^3(\Omega)).
\] (3.24)

In particular, if \( \chi_0 \in Z \), then the above properties hold for any \( \tau \in [0, T) \).
Remark 3.4. From the proof of Proposition 3.3, it is not difficult to recover a uniform estimate of the following form:

\[ \|x\|_{L^\infty(t,T;H^1(t,T,V))} + \|x(u)\|_{L^p(t,T;H^p(\Omega))} \leq Q(t^{-1}, \|Z_0\|_V), \]  

where \( Q \) is a suitable function which is nondecreasing with respect to both arguments.

3.3. Well-Posedness for the Viscous Problem

Continuous Dependence on the Initial Data and Uniqueness. We will prove uniqueness (and continuous dependence) results for Problem 2 under more restrictive assumptions on \( x \) and on the growth of the function \( \phi \). In particular, we are going to consider two sets of assumptions.

First, we will suppose that \( \phi \) behaves like a polynomial of degree at most 3. For the sake of simplicity and without loss of generality, we will carry out our analysis in the case when \( \phi \) is the derivative of the double-well potential \( \hat{\phi}(r) = (r^2 - 1)^2/4 \).

Furthermore, we will replace (H1) by

\[ x : \mathbb{R} \to \mathbb{R} \text{ is a strictly increasing and differentiable function such that} \]

\[ \exists C_9, C_{10} > 0 : \forall r \in \mathbb{R} \quad C_9 \leq x'(r) \leq C_{10}, \]  

and (H5)–(H6) by

\[ \phi(r) = r^3 - r \quad \forall r \in \mathbb{R}. \]  

Theorem 3.1. Assume (H7) and (H8). Let \( \chi_0^1 \) and \( \chi_0^2 \) be two initial data for Problem 2 fulfilling (3.12) and set \( M_* := \max_{i=1,2}\{\|\chi_0^i\|_V\} \); let \( \chi_i, i = 1, 2, \) be the corresponding solutions. Then, for every \( \delta > 0 \), there exists a positive constant \( S_\delta \), also depending on

\[ M_*, T, |\Omega|, C_9, \text{ and } C_{10}, \]  

such that

\[ \|x_1(t) - x_2(t)\|_V + \|x_1 - x_2\|_{H^1(0,T;H^p(\Omega))} \leq S_\delta \|\chi_0^1 - \chi_0^2\|_V \quad \forall t \in [0, T]. \]  

Our second continuous dependence results holds in the more general frame of assumptions of Proposition 3.3, but for more regular initial data. Indeed, we have

Theorem 3.2. Assume that (H1) holds for some \( p \in [0, 1] \), and that \( \phi \) complies with (H5), (H6), and (3.22). Let \( \chi_0^1 \) and \( \chi_0^2 \) be two initial data for Problem 2 such that \( \chi_0^i \in Z \) and \( \phi(\chi_0^i) \in L^1(\Omega) \) for \( i = 1, 2 \), and let \( \chi_i, i = 1, 2, \) be the corresponding solutions. Then, for every \( \delta > 0 \), there exists a positive constant \( S_\delta \), also depending on \( T, |\Omega|, C_1, C_2, \) and \( M^* := \max_{i=1,2}\{\|\chi_0^i\|_Z\} \), such that estimate (3.27) holds for all \( t \in [0, T] \).
3.4. Global Attractor and Exponential Attractors for the Viscous Problem

The energy functional associated with Problem 2 reads

$$\mathcal{E} : X \to \mathbb{R}, \quad \mathcal{E}(v) := \frac{1}{2} \int_{\Omega} |\nabla v|^2 + \int_{\Omega} \hat{\phi}(v) \quad \text{for all } v \in X. \quad (3.28)$$

Consequently, we introduce the phase space $X, d_X$ of energy bounded solutions, defined by

$$X = \{v \in V : \hat{\phi}(v) \in L^1(\Omega)\},$$

$$d_X(v_1, v_2) = \|v_1 - v_2\|_{H^1(\Omega)} + \|\hat{\phi}(v_1) - \hat{\phi}(v_2)\|_{L^1(\Omega)} \quad \text{for all } v_1, v_2 \in X. \quad (3.29)$$

The following definition details the properties of the solutions to Problem 2 to which our long-time analysis will apply.

**Definition 3.5.** We say that a function $\chi : [0, +\infty) \to X$ is a solution to Problem 2 on $(0, +\infty)$ if, for all $T > 0$, $\chi$ enjoys regularity $(3.20)$ on the interval $(0, T)$ and there exists a function $w$, with regularity $(3.21)$ for all $T > 0$, such that equations $(3.18)$–$(3.19)$ hold almost everywhere on $\Omega \times (0, +\infty)$. We set

$$\mathcal{P} = \{\chi : [0, +\infty) \to X : \chi \text{ is a solution to Problem 2 on } (0, +\infty)\}. \quad (3.30)$$

We assume that, besides (H1), $\alpha$ complies with the following condition, slightly stronger than (H1):

$$\exists c_\alpha > 0, \quad \exists \Psi : \mathbb{R} \to [0, +\infty) \text{ convex} : \forall r \in \mathbb{R} \quad \alpha(r) r - c_\alpha |r|^{2p+2} = \Psi(r). \quad (H9)$$

Hence, our first result asserts that the solution set $\mathcal{P}$ is a generalized semiflow in the sense of Definition 2.4.

**Proposition 3.6.** Assume (H1), (H5)–(H6). Then,

1. every $\chi \in \mathcal{P}$ (cf. (3.30)) complies with the energy identity

$$\delta \int_s^t \int_\Omega |\chi_r|^2 + \int_s^t \int_\Omega \beta(u)|\nabla u|^2 + \mathcal{E}(\chi(t)) = \mathcal{E}(\chi(s)) \quad \text{for all } 0 \leq s \leq t, \quad (3.31)$$

the function $w : (0, +\infty) \to V$ being defined by (3.19) on $\Omega \times (0, +\infty)$.

2. Assume that $\alpha$ in addition complies with (H9). Then, the set $\mathcal{P}$ is a generalized semiflow in the phase space $(3.29)$, and its elements are continuous functions from $[0, +\infty)$ onto $X$.

We prove our main result on the long-time behavior of the solutions to Problem 2 under a further condition on $\phi$, which in particular implies (and thus replaces) (H6), namely

$$\lim_{r \to +\infty} \phi(r) = +\infty, \quad \lim_{r \to -\infty} \phi(r) = -\infty,$$

$$\lim_{r \to +\infty} \phi'(r) = \lim_{r \to -\infty} \phi'(r) = +\infty. \quad (H10)$$
Theorem 3. Assume (H1), (H5), (H9), and (H10). For a given \( m_0 \geq 0 \), denote by \( \mathcal{D}_{m_0} \) the set
\[
\mathcal{D}_{m_0} = \{ \chi \in X : |m(\chi)| \leq m_0 \}. \tag{3.32}
\]
Then, the semiflow \( \mathcal{S} \) possesses a unique global attractor \( \mathcal{A} \) in \( \mathcal{D}_{m_0} \), given by
\[
\mathcal{A} := \bigcup \{ \omega(D) : D \subset \mathcal{D}_{m_0} \text{ bounded} \}. \tag{3.33}
\]
Finally, we have the following enhanced regularity for the elements of the \( \omega \)-limit of every trajectory:
\[
\forall p \in [1, +\infty) \exists C_p > 0 : \forall \chi \in \mathcal{S}, \ \forall \hat{\chi} \in \omega(\chi) \ \left\| \hat{\chi} \right\|_{W^{2,p}(\Omega)} + \left\| \hat{\phi}(\hat{\chi}) \right\|_{L^p(\Omega)} \leq C_p. \tag{3.34}
\]

Remark 3.7. Notice that, in the case
\[
\hat{\phi} \text{ is a polynomial of even degree } m \geq 4, \text{ with a positive leading coefficient}, \tag{3.35}
\]
then conditions (H5) and (H10) are satisfied.

Remark 3.8 (Enhanced Regularity of the Global Attractor). In addition to hypotheses (H1), (H5), (H9), and (H10) of Theorem 3, assume that \( \phi \) complies with (3.22). Then, the enhanced regularity estimate (3.23) holds for \( \chi \).

This regularity is reflected in the further regularity
\[
\mathcal{A} \subset Z, \tag{3.36}
\]
for the global attractor \( \mathcal{A} \), which holds provided that one works with the (smaller) set of solutions to Problem 2 arising from the approximation procedure which will be detailed in Appendix. In fact, the estimates leading to (3.23) can be rigorously justified only for this approximate problem, as we will see in the proof of Proposition 3.3, cf. Section 4.3. Now, the aforementioned family of “approximable” solutions to Problem 2 (see, e.g., \cite{2, 34, 36, 37} for analogous constructions) complies with the properties defining a generalized semiflow, except for the concatenation axiom. This has motivated the introduction in \cite{34, 37} of the (slightly more general) notion of weak global attractor, tailored to the weak generalized semiflows without the concatenation property. Hence, relying on the abstract results of \cite{34, 37} and arguing as in the proof of Theorem 3, it is straightforward to prove that the semiflow associated with the approximable solutions to Problem 2 admits a weak global attractor for which (3.36) holds. On the other hand, Theorem 4 below shows that, under the stronger assumptions of Theorem 3.2, the semiflow possesses the standard global attractor \( \mathcal{A} \) satisfying (3.36), namely, \( \mathcal{A} \) is a compact and invariant set which attracts (in the \( V \)-metric) all bounded sets of initial data as time goes to infinity.

We conclude this section by showing that it is also possible to construct an exponential attractor through the short-trajectories approach developed in \cite{24}. Let
us first set for a given $\tau > 0$

$$X_\tau = L^2(0, \tau; V), \quad Y_\tau = \{u \in L^2(0, \tau; Z) : u_\tau \in L^2(0, \tau; H)\}$$

and observe that $Y_\tau$ is compactly embedded in $X_\tau$.

Under assumptions (H1), (H5), (H6), and (3.22), we know that, for any $x_0 \in V$ and any $T > 0$, there exists a pair $(\chi, w)$ which solves Problem 2 with the regularity (3.20), (3.21), (3.23), (3.24) (cf. Theorem 2 and Proposition 3.3). In particular, $\chi \in Y_T$. In addition, thanks to (3.31) and arguing in the same way as in the forthcoming Section 4.1, it is not difficult to show that $\|x\|_{Y_T}$ can be estimated uniformly with respect to $\|x_0\|_V$. The energy identity also entails the existence of a bounded set $B^0 \subset V$ such that, if $(\chi, w)$ is a solution to Problem 2 with the aforementioned properties, then there exists $t_0 > 0$, only depending on $\|x_0\|_V$, such that $\chi(t) \in B^0$ for all $t \geq t_0$ and $\chi(t) \in B^0$ for all $t \geq 0$ whenever $x_0 \in B^0$ (see the proof of the eventual boundedness of $\mathcal{S}$ in Section 5.2). Let us now consider the set $\mathcal{X}_\ell = \{\chi : (0, \ell) \rightarrow V\}$ of all the $\ell$-trajectories $\chi$ such that $(\chi, w)$ is a solution to Problem 2 satisfying (3.20), (3.21), (3.23), (3.24). Then, we endow this set with the $X_\ell$-topology (note that it might be a non-complete metric space). Moreover, denoting by $V_\ell$ the space $V$ endowed with the weak topology, we have $\mathcal{X}_\ell \subset C^0([0, \ell]; V_\ell)$. Consequently, any $\ell$-trajectory makes sense pointwise.

From now on, we assume that assumption (H1) holds for some $p \in [0, 1]$. Thanks to (3.23), for any $\ell$-trajectory, there exists $\tau \in (0, \ell)$ such that $\chi(\tau) \in Z$. This is sufficient to conclude that $\chi$ is unique from $\tau$ on, as a consequence of Proposition 3.3 and Theorem 3.2. Therefore, if $\chi \in \mathcal{X}_\ell$ and $T > \ell$, then there exists a unique $\tilde{\chi} \in \mathcal{X}_T$ such that $\tilde{\chi}|_{[0, \ell]} = \chi$. Thus, we can define a semigroup $L_\ell$ on $\mathcal{X}_\ell$ by setting

$$(L_\ell \chi)(\tau) := \tilde{\chi}(\tau + \tau), \quad \tau \in [0, \ell],$$

where $\tilde{\chi}$ is the unique element of $\mathcal{X}_{T+\tau}$ such that $\tilde{\chi}|_{[0, \ell]} = \chi$.

Let us now set

$$B^0_\ell := \{\chi \in \mathcal{X}_\ell : \chi(0) \in B^0\}.$$

Then, by Proposition 3.3, we can infer that the set $\{\chi|_{[\ell/2, \ell]} : \chi \in B^0_\ell\}$ is bounded in $L^\infty(\ell/2, \ell; Z)$. Hence, we can prove a continuous dependence estimate like (3.27), which allows us to apply [24, Lemma 2.1] and deduce that $L_\ell$ is Lipschitz continuous on $B^0_\ell$, uniformly with respect to $\ell \in [0, \ell]$ for any fixed $\tau > 0$. Observe that, arguing as in Section 4.3, we can prove that $B^0_\ell$ is bounded in $L^\infty(0, \ell; Z) \cap H^1(0, \ell; V)$ and use (3.27). Thus, on account of [24, Theorem 2.2], we can infer that $\mathcal{A}_\ell$ has finite fractal dimension. In order to go back to the original geometric space $V$, we introduce the evaluation mapping $e : \mathcal{X}_\ell \rightarrow V, e(\chi) := \chi(\ell)$. Then, we set $B^1 := e(B^0_\ell)$ and we note that, for any $x_0 \in B^1$, there is a unique solution to Problem 2, so that the solution operator $S_t$ is well defined on $B^1$ and $S_t(B^1) \subseteq B^1$, for all $t \geq 0$. In addition, $e$ is (Lipschitz) continuous on $B^1$ (use (3.27) and [24, Lemma 2.1] once more). Therefore, we use [24, Theorem 2.4] to deduce that $\mathcal{A} := e(\mathcal{A}_\ell)$ is the finite-dimensional global attractor of the dynamical system $(B^1, S_t)$. 

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It remains to prove the existence of an exponential attractor. We already know that $L_t$ is Lipschitz continuous on $B_1^\ell$, uniformly with respect to $t \in [0, \tau]$ for every fixed $\tau > 0$ (see above). Thus, we only need to show that $t \mapsto L_t \chi$ is Hölder continuous with values in $V$, uniformly with respect to $\tau \in [0, \tau]$. This follows from [24, Lemma 2.2], recalling that $B_1^\ell$ is, in particular, bounded in $H^1(0, \ell; V)$. Hence, $(\mathcal{X}_\ell, L_\ell)$ has an exponential attractor $\mathcal{E}_\ell$ and $\mathcal{E} := e(\mathcal{E}_\ell)$ is an exponential attractor for $(B_1^\ell, S_\ell)$.

Summing up, we have proved the

**Theorem 4.** Assume that (H1) holds for some $p \in [0, 1]$. Also, assume (H5), (H6), and (3.22). Then, there exists a bounded invariant set $B_1^\ell \subset V$ such that Problem 2 generates a dynamical system $(B_1^\ell, S_\ell)$ which possesses an exponential attractor $\mathcal{E}$. In addition, the system also has a global attractor $\mathcal{A}$ with finite fractal dimension.

Note that, in the framework of Theorem 4, neither assumption (H9) nor (H10) are needed.

### 4. Proofs of Theorems 1 and 2

**Scheme of the proofs of Theorems 1 and 2.** We will prove Theorems 1 and 2 by taking the limit of a suitable approximation scheme for Problems 1 and 2. For the sake of readability, we postpone detailing such a scheme in Appendix.

In Section 4.1, we will instead perform all estimates leading to the aforementioned passage to the limit directly on systems (3.9)–(3.10) and (3.18)–(3.19). Note that, at this stage, some of the following calculations will only be formal, cf. Remark 4.2 below. Their rigorous justification will be given in Appendix, see Section 6.

Next, in Section 4.2 (in Section 4.3, respectively), we will carry out a passage to the limit in some unspecified approximation scheme for Problem 1 (for Problem 2, respectively) and conclude the (formal) proof of Theorem 1 (of Theorem 2, respectively). In Section 6, we will adapt the limiting arguments developed in Sections 4.2 and 4.3 to the approximation scheme for Problems 1 and 2 and carry out the rigorous proofs of the related existence theorems.

**Notation 4.1.** We will perform the *a priori* estimates on systems (3.9)–(3.10) and (3.18)–(3.19), distinguishing the ones which hold both in the viscous and the non-viscous cases from the ones which depend on the constant $\delta$ in (3.19) (which can be either strictly positive or equal to zero), and on our different assumptions on the nonlinearity $\phi$ in the viscous and non-viscous cases. Accordingly, we will use the generic notation $C$ for most of the constants appearing in the forthcoming calculations and depending on the problem data, and $C_\delta$ ($C_0$, respectively) for those constants substantially depending on the problem data and on $\delta > 0$ (on $\delta = 0$, respectively). We will adopt the same convention for the constants $S'_{\ell}, S'_{\ell}^i, S''_{\ell}, i \geq 1$.

#### 4.1. A Priori Estimates

**First a priori estimate.** We test (3.18) by $w$, (3.19) by $\chi$, add the resulting relations, and integrate over some time interval $(0, t) \subset (0, T)$. Elementary calculations
lead to
\[
\int_0^t \int_\Omega |\xi'(w)|^2 \leq \delta \int_0^t \|Z(t)\|_{H^1}^2 + \frac{1}{2} \|\nabla Z(t)\|_H^2 + \int_\Omega \phi'(\xi(t)) - \frac{1}{2} \|\nabla Z_0\|_H^2 + \int_\Omega \phi(\xi_0).
\] (4.1)

Recalling (3.12), the second of (H1) (which, in particular, yields that $\xi'$ is bounded from below on $\mathbb{R}$ by a positive constant) and the positivity of $\hat{\phi}$ (cf. (3.2)), we conclude that, for some constant $S^1 > 0$,
\[
\|\nabla w\|_{L^2(0,T;H)} + \|\nabla x\|_{L^\infty(0,T;H)} + \|\phi(\xi)\|_{L^\infty(0,T;L^1(\Omega))} \leq S^1.
\] (4.2)

**First a priori estimate in the viscous case.** In the case $\delta > 0$, from the previous a priori estimate we also have
\[
\|Z(t)\|_{L^2(0,T;H)} + \|Z\|_{L^\infty(0,T;V)} \leq S^1.
\] (4.3)

**Second a priori estimate.** We test (3.18) by 1 and find $m(\xi_0) = 0$ a.e. in $(0, T)$, so that, in particular,
\[
m(\xi(t)) = m_0 := m(\xi_0) \quad \forall t \in [0, T].
\] (4.4)

Hence, testing (3.19) by 1, we obtain
\[
m(\phi(\xi(t))) = m(\xi(t)) \quad \text{for a.a. } t \in (0, T).
\] (4.5)

**Second a priori estimate in the non-viscous case.** It follows from (4.4) and the Poincaré inequality that
\[
\|\xi\|_{L^\infty(0,T;V)} \leq S^2.
\] (4.6)

**Third a priori estimate in the non-viscous case.** We test (3.10) by $\xi - m(\xi)$: we have, for a.e. $t \in (0, T),
\[
\|\nabla \xi(t)\|_H^2 + \int_\Omega \phi(\xi(t))(\xi(t) - m(\xi(t)))
\]
\[
= \int_\Omega w(t)(\xi(t) - m(\xi(t)))
\]
\[
= \int_\Omega (w(t) - m(\xi(t)))(\xi(t) - m(\xi(t)))
\]
\[
\leq C\|\nabla \xi(t)\|_H \|\nabla w(t)\|_H \leq CS^1\|\nabla w(t)\|_H.
\] (4.7)

the latter estimate ensuing from the Poincaré inequality for zero mean value functions and the previous (4.2). On the other hand, (3.5) and (4.4) yield that there exist constants $C_m, C'_m > 0$ such that, for a.e. $t \in [0, T],
\[
\int_\Omega |\phi(\xi(t))| \leq C_m \int_\Omega \phi(\xi(t))(\xi(t) - m(\xi(t))) + C'_m.
\] (4.8)
Combining this with (4.7), we deduce that there exists $C > 0$, also depending on $C_{m_0}$ and on $C_{m_0}'$, such that, for a.e. $t \in (0, T)$,

\[
\int_{\Omega} |\phi(\chi(t))| \leq C(\|\nabla u(t)\|_{H} + 1).
\]  

(4.9)

Thus, in view of (4.2), we obtain an estimate for $\phi(\chi)$ in $L^2(0, T; L^1(\Omega))$. Finally, due to (4.5), we find

\[
\|m(u)\|_{L^2(0, T)} \leq C_0.
\]

Hence, by (4.2) and the Poincaré inequality, we conclude that

\[
\|u\|_{L^2(0, T; V)} \leq S_0^1.
\]  

(4.10)

**Third a priori estimate in the viscous case.** Estimate (4.2) for $\hat{\phi}(\chi)$ and (H5) yield that

\[
\|\hat{\phi}(\chi)\|_{L^\infty(0, T; L^1(\Omega))} \leq S_0^2.
\]  

(4.11)

Recalling (4.5), we immediately infer that

\[
\|m(u)\|_{L^\infty(0, T)} \leq S_0^3,
\]

(4.12)

whence, again,

\[
\|u\|_{L^2(0, T; V)} \leq S_0^4.
\]  

(4.13)

**Fourth a priori estimate in the non-viscous case.** We preliminarily observe that, thanks to (3.4), equation (3.10) can be rewritten as

\[
A\chi + \beta(\chi) = w + C\hat{\phi}(\chi) \quad \text{a.e. in } \Omega \times (0, T).
\]  

(4.14)

Notice that, in view of (4.6) and (4.10), the right-hand side of (4.14) belongs to $L^2(0, T; L^6(\Omega))$. Hence, we can test (4.14) by $|\beta(\chi)|^2\beta(\chi)$ and easily conclude that

\[
\|A\chi\|_{L^2(0, T; L^4(\Omega))} + \|\beta(\chi)\|_{L^2(0, T; L^6(\Omega))} \leq C_0.
\]

Then, also by standard elliptic regularity results, we find

\[
\|\hat{\phi}(\chi)\|_{L^2(0, T; L^2(\Omega))} + \|\chi\|_{L^2(0, T; W^{1,6}(\Omega))} \leq S_0^2.
\]  

(4.15)

**Fourth a priori estimate in the viscous case.** We combine (4.3) and (4.13) and argue by comparison in (3.19). Relying on (H6) and on the related elliptic regularity estimate, we have

\[
\|\hat{\phi}(\chi)\|_{L^2(0, T; L^4(\Omega))} \leq S_0^5,
\]

(4.16)

as well as an estimate for $A\chi$ in $L^2(0, T; H)$, so that

\[
\|\chi\|_{L^2(0, T; Z)} \leq S_0^6.
\]  

(4.17)
Fifth a priori estimate. It follows from (4.1) and (H1) that
\[ \int_0^T \int_\Omega w^2 |\nabla w|^2 \leq C, \]
whence we conclude that
\[ \| \nabla (|w|^p w) \|_{L^2(0,T;L^2(\Omega))} \leq S^3. \] (4.18)

Sixth a priori estimate in the non-viscous case. From (4.2), (H3), and (4.15), we deduce that
\[ \| \phi(\chi) \|_{L^{2/q}(0,T;L^{2/q}(\Omega)) \cap L^{\infty}(0,T;L^1(\Omega))} \leq C_0. \] (4.19)

Using the interpolation inequality
\[ \forall v \in L^1(\Omega) \cap L^{5/4}(\Omega), \quad \| v \|_{L^{1/4}(\Omega)} \leq \| v \|^\theta_{L^1(\Omega)} \| v \|^{1-\theta}_{L^{5/4}(\Omega)}, \]
we obtain the estimate
\[ \| \phi(\chi) \|_{L^{5/4}(0,T;L^{5/4}(\Omega))} \leq C_0, \quad \text{with} \quad q = \frac{2}{\sigma + 1 - \frac{\sigma}{\sigma - 3}} = \frac{6 - \sigma}{3 - 3\sigma^2}, \] (4.20)
whence a bound for \( \phi(\chi) \) in \( L^{3q}(0,T;L^1(\Omega)) \). Taking into account (4.5), we conclude that
\[ \| m(w) \|_{L^{\infty}(0,T)} \leq C_0, \quad \text{whence} \quad \| |m(w)|^{p+1} \|_{L^{\infty}(0,T;L^{p+1}(\Omega))} \leq C_0. \] (4.21)

On the other hand, applying the nonlinear Poincaré inequality (2.14) with the choices \( X = V \), \( Y = H \), \( Gv = \nabla v \), and \( \Psi(v) = |\Omega|^{1-p} \int_{\Omega} |v|^p |\nabla \Psi(v)|^{p+1} \), we find
\[ \| |w|^p w \|_V \leq K(\| \nabla (|w|^p w) \|_H + |m(w)|^{p+1}). \] (4.22)

Therefore, combining estimate (4.21) for \( |m(w)|^{p+1} \) with (4.18), we finally obtain, owing to the Poincaré inequality (4.22),
\[ \| |w|^p w \|_{L^{\infty}(0,T;L^{p+1}(\Omega))} \leq C_0. \] (4.23)

Using the embedding \( V \subset L^6(\Omega) \) and the growth (3.1) for \( x \), we infer
\[ \| x(w) \|_{L^{5p}(0,T;L^{5p}(\Omega))} \leq S_0^3 \] (4.24a)
(whence we have used the fact that \( \sigma q_x/(2p + 1) \) equals the index \( \eta_x \) defined in (3.6)). Hence, by comparison in (3.9), we also conclude that
\[ \| z_x \|_{L^{5p}(0,T;L^{5p}(\Omega))} \leq S_0^4 \] (4.24b)
(see again (3.6) for the definition of \( \kappa_p \)).
Sixth a priori estimate in the viscous case. Combining (4.12), (4.18) and the Poincaré-type inequality (4.22), we deduce an estimate for $|w|^p w$ in $L^2(0, T; V)$. Then, arguing in the same way as for (4.24a), we have

$$\|z(u)\|_{L^p(0, T; L^p(V))} \leq C_\delta, \quad (4.25)$$

the index $p_\rho$ being defined in (3.6). Now, in view of estimate (4.3) for $\chi$, in $L^2(0, T; H)$, a comparison in (3.18) yields an estimate for $A(z(w))$ in $L^2(0, T; H)$. By elliptic regularity results, we finally conclude that

$$\|z(u)\|_{L^p(0, T; L^p(V))} \leq S_\delta. \quad (4.26)$$

Seventh a priori estimate in the non-viscous case. Our aim is now to show that

$$\|\phi(z)\|_{L^\infty(0, T; L^\infty(\Omega))} \leq S_\delta^5, \quad \text{with } \sigma_\alpha = \frac{6 - \sigma}{3 - 3\sigma} > 2. \quad (4.27)$$

Indeed, again recalling the embedding $V \subset L^6(\Omega)$, we observe that (4.23) yields an estimate for $w$ in $L^{6p}(0, T; L^{6p+6}(\Omega))$. Then, taking into account estimate (4.6) for $\chi$ in $L^\infty(0, T; L^6(\Omega))$, together with the aforementioned elliptic regularity argument, we find estimate (4.27) by a comparison in (4.14).

Seventh a priori estimate in the viscous case. We combine estimate (4.26), the continuous embedding $Z \subset L^\infty(\Omega)$, and the growth condition (3.1) to deduce an estimate for $w$ in $L^{p\sigma(2p+1)}(0, T; L^\infty(\Omega))$, whence

$$\|w\|_{L^{p\sigma(2p+1)}(0, T; L^\infty(\Omega))} \leq S_\delta^8. \quad (4.28)$$

Remark 4.2. Notice that all the a priori estimates for the viscous Problem 2 are in fact rigorously justified on system (3.18)–(3.19). This has significant repercussions on the long-time analysis of Problem 2. Indeed, this allows us to work with the semiflow associated with the solutions to Problem 2 (cf. (3.30)) and prove the existence of a global attractor in the sense of [3]. However, as pointed out in Remark 3.8, if we address further regularity properties of the attractor (e.g., (3.36)), then we need additional estimates which cannot be performed directly on system (3.18)–(3.19), due to insufficient regularity of the solutions. Thus, we have to rely on some approximation. On the one hand, this leads to a smoother attractor $\mathcal{A}_\delta$, but, on the other hand, we lose the concatenation property of the trajectories (cf. [34, 37]); moreover, only trajectories which are limits of the approximation scheme will be attracted by the smoother attractor $\mathcal{A}_\delta$.

We also point out that the viscous system (3.18)–(3.19) cannot be used as an approximation for the non-viscous problem. Indeed, it is not difficult to realize that the fourth a priori estimates (4.14)–(4.15) (yielding a bound for $\phi(\chi)$ which plays a crucial role in the ensuing calculations) are not compatible with the term $\delta_\chi_\alpha$ in (3.19).

This fact seems to suggest the use of two different approximation schemes for Problem 1 and Problem 2, which would lead to cumbersome and repetitious calculations. In order to circumvent this problem, we will construct in Appendix an approximation scheme depending on two distinct parameters and prove the
existence of solutions to Problem 1 by passing to the limit in three steps. Since the (rigorous) proof of existence for Problem 2 can be performed along the very same lines, we have chosen not to detail it in Appendix.

4.2. Proof of Theorem 1

Let \( \{\zeta_n, w_n\} \) be some sequence of approximate solutions to Problem 1. Due to estimates (4.2), (4.6), (4.10), (4.15), and (4.24a), applying standard compactness and weak compactness results (see [38]), we find that there exists a pair \((\zeta, w)\) with the regularities specified by (3.13)–(3.14) such that, along a (not relabeled) subsequence, the following strong, weak, and weak \(^*\) convergences hold as \( n \to +\infty \):

\[
\zeta_n \to \zeta \quad \text{in} \quad L^2(0, T; W^{2-\epsilon, 6}(\Omega)) \cap L^q(0, T; V) \cap C^0([0, T]; H^{1-\epsilon}(\Omega))
\]

for every \( \epsilon > 0 \) and \( 1 \leq q < +\infty \), \( (4.29) \)

\[
\zeta_n \rightharpoonup^* \zeta \quad \text{in} \quad L^2(0, T; W^{2,6}(\Omega)) \cap L^\infty(0, T; V), \quad (4.30)
\]

\[
\zeta_n, t \to \zeta_t \quad \text{in} \quad L^{6q}(0, T; W^{-2,3q}(\Omega)),
\]

\[
w_n \rightharpoonup w \quad \text{in} \quad L^2(0, T; V).
\]

Furthermore, there exists \( \bar{\alpha} \in L^{\sigma q}(0, T; L^{\sigma_\sigma}(\Omega)) \) such that

\[
\nu(w_n) \to \bar{\alpha} \quad \text{in} \quad L^{\sigma q}(0, T; L^{\sigma_\sigma}(\Omega)).
\]

Now, estimate (4.27) in particular yields (recall that \( \sigma q_\sigma > 2 \)) that

the sequence \( \{\phi(\zeta_n)\} \) is uniformly integrable in \( L^2(0, T; H) \). \( (4.34) \)

Furthermore, we have, up to a further subsequence,

\[
\phi(\zeta_n(x, t)) \to \phi(\zeta(x, t)) \quad \text{for a.a.} \quad (x, t) \in \Omega \times (0, T), \quad (4.35)
\]

which is a consequence of the continuity of \( \phi \) and of the pointwise convergence (up to a further subsequence) \( \zeta_n(x, t) \to \zeta(x, t) \) a.e. in \( \Omega \times (0, T) \) (cf. (4.29)). Combining (4.34) and (4.35) and recalling the compactness criterion Theorem 2.1, we conclude that

\[
\phi(\zeta_n) \to \phi(\zeta) \quad \text{in} \quad L^2(0, T; H).
\]

Exploiting (4.29)–(4.36), one easily concludes that the triplet \((\zeta, w, \bar{\alpha})\) satisfies

\[
\zeta_t + A\bar{\alpha} = 0 \quad \text{in} \quad W^{-2,3_q}(\Omega) \quad \text{a.e. in} \quad (0, T),
\]

\[
A\zeta + \phi(\zeta) = w \quad \text{a.e. in} \quad \Omega \times (0, T).
\]

Finally, in order to prove that

\[
\bar{\alpha}(x, t) = \nu(w(x, t)) \quad \text{for a.a.} \quad (x, t) \in \Omega \times (0, T), \quad (4.39)
\]
we test the equation approximating (3.10) by \( w_n \) and integrate in time. We thus have
\[
\lim_{n \to +\infty} \int_0^T \int_{\Omega} |w_n|^2 = \lim_{n \to +\infty} \int_0^T \int_{\Omega} \phi(\chi_n) w_n + \lim_{n \to +\infty} \int_0^T \int_{\Omega} \nabla \chi_n \cdot \nabla w_n
\]
\[
= \int_0^T \int_{\Omega} \phi(\chi) w + \int_0^T \int_{\Omega} \nabla \chi \cdot \nabla w
\]
\[
= \int_0^T \int_{\Omega} |w|^2,
\]
where the second equality follows from convergences (4.29), (4.32), and (4.36), and the last one from (4.38). Hence, we conclude that
\[
w_n \to w \text{ in } L^2(0, T; H), \quad \text{whence } w_n \to w \text{ a.e. in } \Omega \times (0, T)
\]
(the latter convergence holding up to a subsequence). By continuity of \( \alpha \), we also have \( \alpha(w_n) \to \alpha(w) \) a.e. in \( \Omega \times (0, T) \). Estimate (4.24a) (recall (3.8)) and again Theorem 2.1 yield, for instance, that
\[
\alpha(w_n) \to \alpha(w) \text{ in } L^1(0, T; L^1(\Omega)),
\]
whence the desired equality (4.39).

4.3. Proofs of Theorem 2 and Proposition 3.3

Proof of Theorem 2. Let \( \{ (\chi_n, w_n) \} \) be some sequence of approximate solutions to Problem 2. Thanks to estimates (4.2), (4.3), (4.13), (4.17), (4.26), and (4.28), applying standard compactness and weak compactness results (see [38]), we find a triplet \( (\chi, w, \bar{\alpha}) \) such that, along a (not relabeled) subsequence, the following strong, weak, and weak∗ convergences hold as \( n \to +\infty \):
\[
\chi_n \to \chi \text{ in } L^2(0, T; H^{2-\varepsilon}(\Omega)) \cap L^q(0, T; V) \cap C^0([0, T]; H^{1-\varepsilon}(\Omega))
\]
for every \( \varepsilon > 0 \) and \( 1 \leq q < +\infty \),
\[
\chi_n \weak^* \chi \text{ in } L^2(0, T; Z) \cap L^\infty(0, T; V) \cap H^1(0, T; H),
\]
\[
w_n \weak^* w \text{ in } L^2(0, T; V) \cap L^{2p+2}(0, T; L^\infty(\Omega)).
\]
In particular, from (4.41), we deduce that
\[
\mathcal{N}(\chi_n) \rightharpoonup \mathcal{N}(\chi) \text{ in } L^2(0, T; Z).
\]
Furthermore, by (4.25), there exists \( \bar{\alpha} \in L^p(0, T; L^\infty(\Omega)) \) such that
\[
\alpha(w_n) \to \bar{\alpha} \text{ in } L^p(0, T; L^\infty(\Omega)).
\]
Now, up to a subsequence, by the last of (4.40) and by continuity of \( \phi \), we have, for all \( t \in [0, T] \),
\[
\phi(\chi_n(\cdot, t)) \to \phi(\chi(\cdot, t)) \text{ a.e. in } \Omega.
\]
On the other hand, it follows from estimate (4.16) that

the sequence \( \{\phi(\chi_n)\} \) is uniformly integrable in \( L^1(0, T; L^1(\Omega)) \). \hfill (4.46)

Then, by (4.45)–(4.46) and Theorem 2.1, we conclude that, along the same subsequence as in (4.45), \( \phi(\chi_n) \to \phi(\chi) \) in \( L^1(0, T; L^1(\Omega)) \). We then have, up to a subsequence,

\[
\phi(\chi_n(t)) \to \phi(\chi(t)) \quad \text{in} \quad L^1(\Omega) \quad \text{for a.a.} \ t \in (0, T).
\] \hfill (4.47)

Next, using (4.11), we see that \( \phi(\chi_n) \) is uniformly integrable in \( L^r(0, T; L^1(\Omega)) \) for all \( r \in [1, +\infty) \). Applying Theorem 2.1, from (4.47), we deduce that

\[
\phi(\chi_n) \to \phi(\chi) \quad \text{in} \quad L^r(0, T; L^1(\Omega)) \quad \text{for every} \ r \in [1, +\infty).
\] \hfill (4.48)

Collecting (4.40)–(4.44) and (4.48), we conclude that the triplet \( (\chi, w, \tilde{z}) \) satisfies

\[
\chi_t + A \tilde{z} = 0 \quad \text{a.e. in} \ \Omega \times (0, T),
\]

\[
\delta \chi_t + A \chi + \phi(\chi) = w \quad \text{a.e. in} \ \Omega \times (0, T).
\] \hfill (4.49) \hfill (4.50)

It remains to show that \( \tilde{z} \equiv z(w) \). To this aim, we note that \( z \) defines a maximal monotone graph in the duality \( (L^{2p+2}(\Omega \times (0, T)), L^{p}(\Omega \times (0, T))) \) (note that \( p \) and \( 2p + 2 \) are conjugate exponents). Taking into account relations (4.42) and (4.44), and applying a well-known result from the theory of maximal monotone operators in Banach spaces (see [4, Lemma 1.3, p. 42]), it is then sufficient to prove that

\[
\lim \sup_{n \to +\infty} \int_0^T \int_\Omega z(w_n) w_n \leq \int_0^T \int_\Omega \tilde{z} w.
\] \hfill (4.51)

Now,

\[
\int_0^T \int_\Omega z(w_n) w_n = \int_0^T \int_\Omega \left( z(w_n) - m(z(w_n)) \right) w_n + \int_\Omega m(z(w_n)) m(w_n)
\]

\[
= - \int_0^T \int_\Omega w_n N(\chi_{n,t}) + \int_\Omega m(z(w_n)) m(w_n),
\] \hfill (4.52)

where the second equality follows from (3.18). Then, using (2.2) and (3.19), we find the chain of inequalities

\[
\lim \inf_{n \to +\infty} \left( \int_0^T \int_\Omega w_n N(\chi_{n,t}) \right)
\]

\[
\geq \lim \inf_{n \to +\infty} \delta \int_0^T \|\chi_{n,t}\|^2_v + \lim_{n \to +\infty} \int_\Omega \chi_{n,t} \chi_n + \lim_{n \to +\infty} \int_\Omega \phi(\chi_n) N(\chi_{n,t})
\]

\[
\geq \delta \int_0^T \|\chi_t\|^2_v + \int_0^T \int_\Omega \chi_t \chi + \int_\Omega \phi(\chi) N(\chi_t)
\]

\[
= \int_0^T \int_\Omega w N(\chi_t) = - \int_0^T \int_\Omega (\tilde{z} - m(\tilde{z})) w,
\] \hfill (4.53)
where the second inequality follows from convergences (4.40) and (4.41) for \( \zeta_n \) and from combining (4.43) with (4.48), while the subsequent identities are due to (4.49)–(4.50). On the other hand, it follows from (4.44) that
\[
m(\zeta(w_n)) \rightharpoonup m(\tilde{z}) \quad \text{in} \quad L^p(0, T),
\]
whereas, from (4.48), we gather that
\[
m(w_n) = m(\phi(\zeta_n)) \rightarrow m(\phi(\zeta)) = m(w) \quad \text{in} \quad L^{2p+2}(0, T).
\]
Combining (4.54)–(4.55), we conclude that
\[
\lim_{n \to +\infty} \frac{1}{2} \int_\Omega (\frac{1}{2} \int_\Omega |A\zeta|^2) + \delta \int_\Omega |\nabla \zeta|^2 = I_1 + I_2,
\]
with
\[
I_1 := \int_\Omega \nabla w \cdot \nabla \zeta \leq \frac{\delta}{2} \int_\Omega |\nabla \zeta|^2 + \frac{1}{2\delta} \int_\Omega |\nabla w|^2,
\]
\[
I_2 := -\int_\Omega \phi'(\zeta)(\nabla \zeta \cdot \nabla \zeta)
\leq C_{\phi,3} \int_\Omega |\nabla \zeta||\nabla \zeta|(1 + |\zeta|^4)
\leq C \|\nabla \zeta\|_H \|\nabla \zeta\|_{L^4(\Omega)}(\|\nabla \zeta\|_{L^{\frac{12}{5}}(\Omega)} + 1)
\leq \frac{\delta}{4} \|\nabla \zeta\|_H^2 + C(\|\zeta\|_{L^{\frac{12}{5}}(\Omega)} + 1)\|\zeta\|_Z^2.
\]
where the second inequality follows from (3.22), the third one from the Hölder inequality, and the last one by taking into account the continuous embedding $Z \subset W^{1,6}(\Omega)$.

Collecting (4.59)--(4.60), taking into account (4.58), and applying the uniform Gronwall Lemma (see [40, Lemma III.1.1]), we find for every $\tau > 0$ an estimate of the form (3.25) for $\nabla \chi$ in $L^2(\tau; T; H)$ and for $A \chi$ in $L^\infty(\tau; T; H)$, whence

$$\chi \in L^\infty(\tau; T; Z) \cap H^1(\tau; T; V) \quad \text{for all } 0 < \tau < T.$$Then, a comparison in (3.18) also yields a bound for $A(\chi(w))$ in $L^p(\tau; T; V)$, whence an estimate for $\chi(w)$ in $L^p(\tau; T; H^1(\Omega))$, in view of (3.21). Thus, we conclude (3.23)–(3.24), as well as estimate (3.25). □

5. Global Attractor for Problem 2

5.1. Proof of Proposition 3.6

We need two preliminary lemmas. The first one clarifies some properties of the energy functional $\mathcal{E}$.

Lemma 5.1. Assume (H5)–(H6). Then, the functional $\mathcal{E} : X \to \mathbb{R}$ defined by (3.28) is bounded from below, lower-semicontinuous w.r.t. the $H$-topology, and satisfies the chain rule

$$\frac{d}{dt} \mathcal{E}(v(t)) = \int_\Omega v(t)(Av + \phi(v(t))) \quad \text{for a.a. } t \in (0, T).$$

Proof. In order to prove the lower-semicontinuity property, we fix a sequence $\{v_n\}$ converging to some $v$ in $H$ and assume, without loss of generality, that $\sup_n \mathcal{E}(v_n) < +\infty$. Since $\phi$ is bounded from below, we conclude that $\{v_n\}$ is actually bounded in $V$, and thus $v_n \to v$ in $V$, yielding $\int_\Omega |\nabla v|^2 \leq \liminf_n \int_\Omega |\nabla v_n|^2$. On the other hand,

$$\liminf_{n \to +\infty} \int_\Omega \phi(v_n) = \liminf_{n \to +\infty} \int_\Omega \left( \phi(v_n) + \frac{C_{\phi,2}}{2} |v_n|^2 \right) - \frac{C_{\phi,2}}{2} \lim_{n \to +\infty} \int_\Omega |v_n|^2 \geq \int_\Omega \left( \phi(v) + \frac{C_{\phi,2}}{2} |v|^2 \right) - \frac{C_{\phi,2}}{2} \int_\Omega |v|^2,$

the latter inequality following from (3.16) and, for instance, from Ioffe’s Theorem 2.2. Finally, to check the chain rule (5.1), we observe that the functional

$$\mathcal{E}_c(v) := \mathcal{E}(v) + \frac{C_{\phi,2}}{2} \int_\Omega |v|^2 \quad \text{for all } v \in X$$

is convex, thanks to (3.16). Then, (5.1) follows from the chain rule for $\mathcal{E}_c$, see [6, Lemma III.3.3]. □
Lemma 5.2. Assume (H1). Then,

for all \( w \in V \cap L^\infty(\Omega) \), there holds \( \nabla \mathcal{z}(w(x)) = \mathcal{z}'(w(x)) \nabla w(x) \) for a.a. \( x \in \Omega \). (5.3)

Proof. Since \( \Omega \) is smooth, we can take a sequence \( \{ w_k \} \subset C^1(\overline{\Omega}) \) such that \( w_k \to w \) in \( V \cap L^q(\Omega) \) for all \( 1 \leq q < +\infty \). Clearly, for all \( k \in \mathbb{N} \), there holds

\[
\nabla \mathcal{z}(w_k(x)) = \mathcal{z}'(w_k(x)) \nabla w_k(x) \quad \forall x \in \Omega.
\]

Now, since \( \mathcal{z}(r) \) grows like \( |r|^{2p} \) by (H1), we conclude that \( \mathcal{z}'(w_k) \to \mathcal{z}'(w) \) and \( \mathcal{z}(w_k) \to \mathcal{z}(w) \) in \( L^q(\Omega) \) for all \( 1 \leq q < +\infty \). Therefore, \( \nabla \mathcal{z}(w_k) = \mathcal{z}'(w_k) \nabla w_k \to \mathcal{z}'(w) \nabla w \) in \( L^\rho(\Omega) \) for all \( \rho \in [1, 2] \) and (5.3) follows.

Proof of Proposition 3.6. Thanks to Theorem 2, the set \( \mathcal{F} \) complies with the existence axiom (P1) in Definition 2.4. The translation property (P2) is immediate to check. Concerning the concatenation axiom, let \( \chi_1 \) and \( \chi_2 \) be two solutions to Problem 2 on \( (0, +\infty) \), satisfying \( \chi_1(\tau) = \chi_2(0) \) for some \( \tau \geq 0 \), and let the functions \( w_1 \) and \( w_2 \) be such that, for \( i = 1, 2 \), the pairs \( (\chi_i, w_i) \) satisfy equations (3.18)–(3.19), with regularities (3.20) and (3.21). Then, one easily sees that the concatenations (cf. (2.23)) \( \tilde{\chi} \) and \( \tilde{\mathcal{w}} \) of \( \chi_1 \), \( \chi_2 \) and \( w_1 \), \( w_2 \), respectively, satisfy equations (3.18)–(3.19), and still enjoy regularities (3.20) and (3.21), respectively (the fact that \( \chi_1(\tau) = \chi_2(0) \) is crucial for the time-regularity of \( \tilde{\chi} \)).

To prove that all solutions \( \chi \in \mathcal{F} \) are continuous w.r.t. the phase space topology (3.29), let us fix \( \{ t_n \}, t_0 \in [0, +\infty) \), and show that

\[
t_n \to t_0 \Rightarrow \left( \| \chi(t_n) - \chi(t_0) \|_V + \| \hat{\phi}(\chi(t_n)) - \hat{\phi}(\chi(t_0)) \|_{L^1(\Omega)} \right) \to 0 \quad \text{as } n \to +\infty.
\]

Indeed, thanks to regularity (3.20), for all \( T > 0 \), the function \( \chi : [0, T] \to V \) is continuous w.r.t. the weak \( V \)-topology, hence

\[
\chi(t_n) \to \chi(t_0) \quad \text{in } V.
\]

Therefore, by Lemma 5.1, we have

\[
\lim_{n \to +\infty} \mathcal{E}(\chi(t_n)) \geq \mathcal{E}(\chi(t_0)).
\]

Combining this inequality with the continuity of the map \( t \in [0, T] \mapsto \mathcal{E}(\chi(t)) \), one concludes that

\[
\lim_{n \to +\infty} \int_\Omega |\nabla \chi(t_n)|^2 = \int_\Omega |\nabla \chi(t_0)|^2,
\]

and

\[
\lim_{n \to +\infty} \int_\Omega \hat{\phi}(\chi(t_n)) = \int_\Omega \hat{\phi}(\chi(t_0)).
\]

Clearly, (5.6), combined with (5.7a), yields that \( \chi(t_n) \to \chi(t_0) \) in \( V \). In order to prove the additional convergence

\[
\| \hat{\phi}(\chi(t_n)) - \hat{\phi}(\chi(t_0)) \|_{L^1(\Omega)} \to 0 \quad \text{as } n \to +\infty,
\]

(5.8)
we note that the convergence \( \chi(t_n) \to \chi(t_0) \) in \( V \) implies, in particular, that

\[
\hat{\phi}(\chi(\cdot, t_n)) \to \hat{\phi}(\chi(\cdot, t_0)) \quad \text{a.e. in } \Omega. \tag{5.9}
\]

In view of [31, Lemma 4.2], (5.9), combined with (5.7b) and the fact that \( \hat{\phi} \) takes non-negative values, yields (5.8).

The energy identity (3.31) follows by multiplying (3.18) by \( w \) (note that the latter is an admissible test function, thanks to (3.21)), (3.19) by \( \chi \), adding the resulting relations, taking into account the chain rule (5.1) and formula (5.3), and integrating in time.

It remains to prove the upper-semicontinuity with respect to the initial data. To this aim, we will exploit (3.31). Thus, let us fix a sequence of solutions \( \{\chi_n\} \subset \mathcal{F} \) and \( \chi_0 \in X \), with

\[
d_X(\chi_n(0), \chi_0) \to 0 \quad \text{as } n \to +\infty, \quad \text{so that, in particular, } \mathcal{E}(\chi_n(0)) \to \mathcal{E}(\chi_0). \tag{5.10}
\]

Identity (3.31) yields that there exists a constant \( C > 0 \) such that, for all \( n \in \mathbb{N} \),

\[
\delta \int_0^t \int_\Omega |\nabla \chi_n|^2 + \int_0^t \int_\Omega \chi'(w_n) |\nabla w_n|^2 + \mathcal{E}(\chi_n(t)) = \mathcal{E}(\chi_n(0)) \leq C \quad \text{for all } t \geq 0.
\tag{5.11}
\]

Arguing as in Section 4.1, we obtain estimates (4.2), (4.3), (4.13), (4.17), (4.26), and (4.28) for the sequence \( \{\chi_n, w_n\} \), on every interval \( (0, T) \). Therefore, with a diagonalization procedure, we find a subsequence \( \{\chi_{n_k}, w_{n_k}\} \) and functions \( (\chi, w) : (0, +\infty) \to X \times V \) for which (4.40)–(4.42), (4.48), and (4.57) hold on every interval \( (0, T) \), for all \( T > 0 \). Using all the aforementioned relations, we have \( \chi(0) = \chi_0 \) and, arguing as in Section 4.3, we conclude that \( \chi \in \mathcal{F} \). In order to prove that for all \( t \geq 0 \),

\[
(\|\chi_n(t) - \chi(t)\|_V + \|\hat{\phi}(\chi_n(t)) - \hat{\phi}(\chi(t))\|_{L^1(\Omega)}) \to 0 \quad \text{as } k \to +\infty.
\tag{5.12}
\]

we first obtain some enhanced convergence for the sequence \( \{w_{n_k}\} \). To this aim, we note that, for every \( T > 0 \), there holds

\[
c_* \limsup_{k \to +\infty} \int_0^T \int_\Omega |w_{n_k}|^{2p+2} \leq \limsup_{k \to +\infty} \int_0^T \int_\Omega \chi(w_{n_k}) w_{n_k} - \liminf_{k \to +\infty} \int_0^T \int_\Omega \Psi(w_{n_k}) \leq \int_0^T \int_\Omega \chi(w) w - \int_0^T \int_\Omega \Psi(w) = c_* \int_0^T \int_\Omega |w|^{2p+2}.
\]

Indeed, the first inequality follows from (H9), the second one from the second convergence in (4.57), and from (4.42), together with the convexity of \( \Psi \) (thanks to Ioffe’s Theorem [22]), and the third one from (H9) again. Taking into account the fact that

\[
\liminf_{k \to +\infty} \int_0^T \int_\Omega |w_{n_k}|^{2p+2} \geq \int_0^T \int_\Omega |w|^{2p+2},
\]
due to (4.42), we have

\[
w_{n_k} \to w \quad \text{in } L^{2p+2}(0, T; L^{2p+2}(\Omega)) \quad \text{for all } T > 0
\]
and, thus, finally,

\[ w_{n_k} \to w \quad \text{in measure in } \Omega \times (0, T) \text{ for all } T > 0. \]  \hspace{1cm} (5.13)

As a consequence, for all \( t \geq 0 \),

\[ \liminf_{k \to +\infty} \int_0^t \int_\Omega |\partial_t \chi_n|^2 + \int_0^t \int_\Omega |\partial_t \chi_0|^2 \geq \int_0^t \int_\Omega \partial_t w_t |\nabla w|^2, \]  \hspace{1cm} (5.14)

thanks to the convergence in measure (5.13), the weak convergence (4.42) for \( \{\nabla u_{n_k}\} \) in \( L^2(0, \Omega; \mathbb{R}) \) for all \( T > 0 \), and again Ioffe’s Theorem 2.2. Hence, passing to the limit in the energy identity (5.11) (written for the functions \( (\chi_n, u_{n_k}) \)), we infer, for all \( t \geq 0 \),

\[
\delta \int_0^t \int_\Omega |\partial_t \chi|^2 + \int_0^t \int_\Omega |\partial_t \chi_0|^2 + \int_0^t \int_\Omega \partial_t w_t |\nabla w|^2 + \mathcal{E}(\chi) + \mathcal{E}(\chi_0) \\
\leq \liminf_{k \to +\infty} \left( \delta \int_0^t \int_\Omega |\partial_t \chi_n|^2 + \int_0^t \int_\Omega \partial_t w_{n_k} |\nabla w_{n_k}|^2 + \mathcal{E}(\chi_n(t)) \right) \\
\leq \limsup_{k \to +\infty} \left( \delta \int_0^t \int_\Omega |\partial_t \chi_n|^2 + \int_0^t \int_\Omega \partial_t w_{n_k} |\nabla w_{n_k}|^2 + \mathcal{E}(\chi_n(t)) \right) \\
= \lim_{k \to +\infty} \mathcal{E}(\chi_n(0)) = \mathcal{E}(\chi) \\
= \delta \int_0^t \int_\Omega |\partial_t \chi|^2 + \int_0^t \int_\Omega \partial_t w_t |\nabla w|^2 + \mathcal{E}(\chi) + \mathcal{E}(\chi_0), \]  \hspace{1cm} (5.15)

where the first inequality follows from (4.40)–(4.41), (5.14), and the fact that \( \mathcal{E} \) is lower-semicontinuous w.r.t. the \( H \)-topology, the third one from (5.11), the fourth one from (5.10), and the last equality from the energy identity (3.31) satisfied by all solutions in \( \mathcal{F} \). With an elementary argument, we deduce from (5.15) that, for all \( t \geq 0 \),

\[ \int_0^t \int_\Omega |\partial_t \chi_n|^2 \to \int_0^t \int_\Omega |\partial_t \chi|^2, \quad \text{whence } \chi_n \to \chi \text{ in } H^1(0, t; \mathbb{R}), \]

as well as

\[ \mathcal{E}(\chi_n(t)) \to \mathcal{E}(\chi(t)). \]

Arguing in the same way as throughout (5.6)–(5.9) and again invoking [31, Lemma 4.2], we obtain (5.12). This concludes the proof.

### 5.2. Proof of Theorem 3

**Eventual boundedness.** In order to check that \( \mathcal{F} \) is eventually bounded, we fix a ball \( B(0, R) \) centered at 0 of radius \( R \) in \( X \), some initial datum \( \chi_0 \in B_X(0, R) \), namely satisfying (recall that we can assume that \( \hat{\phi} \) is a positive function)

\[ \|\chi_0\|_V + \int_\Omega \hat{\phi}(\chi_0) \leq R. \]  \hspace{1cm} (5.16)
and consider a generic trajectory $\chi \in \mathcal{F}$ starting from $\chi_0$. Recalling the energy identity (3.31), we find, for all $t \geq 0$,

$$
\int \phi(\chi(t)) \leq \mathcal{E}(\chi(t)) \leq \mathcal{E}(\chi_0) \leq R, \quad \int |\nabla \chi(t)|^2 \leq 2R.
$$

(5.17)

Now, taking into account the fact that $m(\chi(t)) = m(\chi_0)$ for all $t \geq 0$ (cf. (4.4)), we deduce from (5.17) a bound for $\|\chi\|_{L^\infty(0, +\infty; \mathcal{F})}$. Hence, there exists $R' > 0$ such that $d_X(\chi(t), 0) \leq R'$ for all $t \geq 0$. Since $\chi_0$ is arbitrary, we conclude that the evolution of the ball $B_X(0, R)$ is contained in the ball $B_X(0, R')$.

**Compactness.** In order to verify that $\mathcal{F}$ is compact, we consider a sequence $\{\chi_n\} \subset \mathcal{F}$ such that $\{\chi_n(0)\}$ is bounded in $X$. We write the energy identity (5.11) and, as in the proof of Proposition 3.6, deduce that there exist a subsequence $\{\{\chi_{n_k}, w_{n_k}\}\}$ and functions $(\chi, w): (0, +\infty) \to X \times V$ for which convergences (4.40)–(4.42), (4.48), and (4.57) hold on every interval $(0, T)$ for all $T > 0$. However, we cannot prove that

$$
(\|\chi_{n_k}(t) - \chi(t)\|_V + \|\hat{\phi}(\chi_{n_k}(t)) - \hat{\phi}(\chi(t))\|_{L^1(\Omega)}) \to 0 \quad \text{for all } t > 0,
$$

(5.18)

arguing in the same way as throughout (5.12)–(5.15), for, in this case, we do not have the convergence of the initial energies $\mathcal{E}(\chi_{n_k}(0))$ at our disposal. Then, we rely on the following procedure (see also [34, 37] for the use of an analogous argument).

First, we apply Helly’s compactness principle (with respect to the pointwise convergence) for monotone functions to the functions $t \mapsto \mathcal{E}(\chi_{n_k}(t))$, which are non-increasing in view of the energy identity (5.11). Thus, up to a (not relabeled) subsequence, there exists a non-increasing function $\mathcal{E} : [0, +\infty) \to \mathbb{R}$ such that

$$
\mathcal{E}(t) = \lim_{k \to +\infty} \mathcal{E}(\chi_{n_k}(t)) \quad \text{for all } t \geq 0.
$$

(5.19)

By the lower-semicontinuity of $\mathcal{E}$ (w.r.t. the $H$-topology), we find

$$
\mathcal{E}(\chi(t)) \leq \mathcal{E}(t) \quad \text{for all } t \geq 0.
$$

(5.20)

On the other hand, (4.40) ensures that, up to a further extraction, for almost all $s \in (0, t)$,

$$
\chi_{n_k}(s) \to \chi(s) \quad \text{in } H^{2-\varepsilon}(\Omega) \text{ for all } \varepsilon > 0, \text{ whence } \chi_{n_k}(s) \to \chi(s) \text{ in } H^1(\Omega) \cap L^\infty(\Omega).
$$

(5.21)

Thus, in particular,

$$
\hat{\phi}(\chi_{n_k}(\cdot, s)) \to \hat{\phi}(\chi(\cdot, s)) \quad \text{a.e. in } \Omega.
$$

(5.22)

Moreover, for every $\varrho \subset \Omega$, there holds

$$
\int_{\varrho} |\hat{\phi}(\chi_{n_k}(s))| \leq |\varrho||\hat{\phi}(0)| + \frac{C_{\phi, 2}}{2} \int_{\varrho} |\chi_{n_k}(s)|^2 + \int_{\varrho} |\phi(\chi_{n_k}(s))||\chi_{n_k}(s)|
\leq C\left(|\varrho| + \int_{\varrho} |\phi(\chi_{n_k}(s))|ight),
$$

(5.23)
where the first inequality follows from (3.17) and the second one from (5.21). Notice that the right-hand side of (5.23) tends to zero as $|\varrho| \to 0$, since the sequence $\{\phi(x_{n_i}(s))\}$ is uniformly integrable in $L^1(\Omega)$ thanks to (4.48). Hence, (5.23) yields that $\{\phi(x_{n_i}(s))\}$ is itself uniformly integrable in $L^1(\Omega)$. Combining this with (5.22), in view of Theorem 2.1 we conclude that $\hat{\phi}(x_{n_i}(s)) \to \hat{\phi}(\chi(s))$ in $L^1(\Omega)$. Finally, we have shown that there exists a negligible set $\mathcal{N} \subset (0, +\infty)$ such that

$$
\mathcal{E}(s) = \lim_{k \to +\infty} \mathcal{E}(x_{n_i}(s)) = \mathcal{E}(\chi(s)) \quad \text{for a.a. } s \in (0, +\infty) \setminus \mathcal{N}.
$$

(5.24)

We are now in a position to carry out the argument for (5.18) (which bypasses the lack of convergence of the initial data in the phase space (3.29)), using the fact that the energy identity (5.11) holds for all $s \in (0, +\infty) \setminus \mathcal{N}$, the map

$$
\phi(x_{n_i}(s)) \to \chi(s)
$$

in view of Theorem 2.1 we conclude that there exists a negligible set $\mathcal{N} \subset (0, +\infty)$ such that

$$
\mathcal{E}(s) = \lim_{k \to +\infty} \mathcal{E}(x_{n_i}(s)) = \mathcal{E}(\chi(s)) \quad \text{for a.a. } s \in (0, +\infty) \setminus \mathcal{N}.
$$

(5.24)

We are now in a position to carry out the argument for (5.18) (which bypasses the lack of convergence of the initial data in the phase space (3.29)), using the fact that the energy identity (5.11) holds for all $t > 0$. Indeed, for every fixed $t > 0$ and for all $s \in (0, t) \setminus \mathcal{N}$, we can pass to the limit in the energy identity (5.11), written for the sequence $(x_{n_i}, w_{n_i})$ on the interval $(s, t)$. Note indeed that convergences (4.40)–(4.42) and (4.48) for $(x_{n_i}, w_{n_i})$ hold on $(s, t)$. Proceeding as above, we then deduce once more that

$$
\lim_{k \to +\infty} \int_s^t \int_\Omega \alpha(w_{n_i}) w_{n_i} = \int_s^t \int_\Omega \alpha(w),
$$

whence $w_{n_i} \to w$ in $L^{2p+2}(s, t; L^{2p+2}(\Omega))$. Therefore, repeating the very same passages as in (5.15) and relying on (5.24), we find

$$
\delta \int_s^t \int_\Omega |\tilde{\varphi}(x)|^2 + \int_s^t \int_\Omega |\tilde{\varphi}'(w)|^2 + \mathcal{E}(\chi(t)) = \lim_{k \to +\infty} \left( \delta \int_s^t \int_\Omega |\tilde{\varphi}(x_{n_i})|^2 + \int_s^t \int_\Omega |\tilde{\varphi}'(w_{n_i})|^2 + \mathcal{E}(x_{n_i}(t)) \right),
$$

which gives

$$
\mathcal{E}(t) = \lim_{k \to +\infty} \mathcal{E}(x_{n_i}(t)) = \mathcal{E}(\chi(t)) \quad \text{for all } t > 0,
$$

and, finally, (5.18).

Lyapunov function and rest points. We now verify that $\mathcal{E}$ acts as a Lyapunov functional for $\mathcal{F}$. Actually, $\mathcal{E}$ clearly is continuous on $X$ and decreasing along all solutions, thanks to the energy identity (3.31). Furthermore, assume that, along some $\chi \in \mathcal{F}$, the map $t \in [0, +\infty) \mapsto \mathcal{E}(\chi(t))$ is constant. Then, in view of (3.31), we find $\nabla w \equiv 0$ and $\chi_t \equiv 0$ a.e. in $(0, +\infty)$, so that $\chi(t) \equiv \chi(0)$ for all $t \in [0, +\infty)$. Analogously, we immediately find that $\bar{\chi} \in X$ is a rest point for $\mathcal{F}$ if and only if it satisfies the stationary system

$$
A(x(\bar{w})) = 0 \quad \text{a.e. in } \Omega,
$$

(5.25a)

$$
A\bar{\chi} + \phi(\bar{\chi}) = \bar{w} \quad \text{a.e. in } \Omega.
$$

(5.25b)

Conclusion of the Proof. We apply Theorem 2.3 and Remark 2.5 with the choice $\mathcal{D} := \mathcal{D}_m$ for some $m_0 > 0$ (cf. (3.32)). Thanks to (4.4) (recall the second a priori estimate in Section 4.1), for all $\chi_0 \in \mathcal{D}_m$, every solution starting from the initial
datum \( x_0 \) remains in \( D_{m_0} \), so that the first condition in (2.28) is satisfied. To check the second one, we fix some \( \bar{z} \in Z(\mathcal{F}) \) with \( |m(\bar{z})| \leq m_0 \). It follows from (5.25a) and (H1) that \( \nabla \bar{w} \equiv 0 \), so that \( \bar{w} \) is constant in \( \Omega \). Hence, we test (5.25b) by \( \bar{z} - m(\bar{z}) \). Since \( \bar{w} = m(\bar{w}) \), we infer that

\[
\| \nabla \bar{z} \|_H^2 + \int_{\Omega} \phi(\bar{z})(\bar{z} - m(\bar{z})) \leq 0.
\]  

(5.26)

On the other hand, (H10) ensures that estimate (3.5) holds, so that there exist constants \( \mathcal{K}_{m_0}, \mathcal{K}_{m_0}^1 > 0 \), only depending on \( m_0 \), such that

\[
\int_{\Omega} |\phi(\bar{z})| \leq \mathcal{K}_{m_0} \int_{\Omega} \phi(\bar{z})(\bar{z} - m(\bar{z})) + \mathcal{K}_{m_0}^1.
\]  

(5.27)

Collecting (5.26) and (5.27), we deduce that

\[
\| \nabla \bar{z} \|_H^2 + \frac{1}{\mathcal{K}_{m_0}} \int_{\Omega} |\phi(\bar{z})| \leq \frac{\mathcal{K}_{m_0}^1}{\mathcal{K}_{m_0}},
\]

whence, in particular,

\[
|m(\bar{w})| = |m(\phi(\bar{z}))| \leq \frac{\mathcal{K}_{m_0}^1}{|\Omega|}.
\]

Taking into account the fact that \( \nabla \bar{w} = 0 \) (so that \( \bar{w} \) is a constant) and that \( |m(\bar{z})| \leq m_0 \), we conclude that

\[
\exists \mathcal{K}_{m_0}^2 > 0 : \forall \bar{z} \in Z(\mathcal{F}) \cap D_{m_0} \quad \| \bar{z} \|_V + |\bar{w}| \leq \mathcal{K}_{m_0}^2.
\]  

(5.28)

Thus, a comparison in (5.25b) and the standard elliptic regularity estimate (cf. also the calculations developed throughout (4.14)–(4.15)) yield

\[
\exists \mathcal{K}_{m_0}^3 > 0 : \forall \bar{z} \in Z(\mathcal{F}) \cap D_{m_0} \quad \| \phi(\bar{z}) \|_{L^4(\Omega)} + \| \bar{z} \|_{W^{2,6}(\Omega)} \leq \mathcal{K}_{m_0}^3.
\]  

(5.29)

whence, in particular, an estimate for \( \bar{z} \) in \( L^\infty(\Omega) \). Then, using (3.17), we readily infer that

\[
\exists \mathcal{K}_{m_0}^4 > 0 : \forall \bar{z} \in Z(\mathcal{F}) \cap D_{m_0} \quad \| \phi(\bar{z}) \|_{L^4(\Omega)} \leq \mathcal{K}_{m_0}^4.
\]  

(5.30)

Finally, (5.28) and (5.30) yield that \( Z(\mathcal{F}) \cap D_{m_0} \) is bounded in the phase space \( X \), and the existence of the global attractor follows from Theorem 2.3.

In fact, with the same calculations as in the above lines, joint with a boot-strap argument, one easily proves that

\[
\forall p \in [1, +\infty) : \exists C_p > 0 \quad \bar{z} \in Z(\mathcal{F}) \cap D_{m_0} \quad \| \bar{z} \|_{W^{2,p}(\Omega)} + \| \bar{z} \|_{L^p(\Omega)} \leq C_p.
\]  

(5.31)

Then, estimate (3.34) is a straightforward consequence of (2.27) and (5.31). \( \square \)
6. Proof of Theorems 3.1 and 3.2

Proof of Theorem 3.1. Within this proof, we denote by $c_\delta$ a positive constant depending on $\delta > 0$ and on quantities (3.26). Referring to the notation of the statement of Theorem 3.1, let us set $Z_0 := \chi_0' - \chi_0^2$, $Z := \chi_1 - \chi_2$, and $w := w_1 - w_2$. The pair $(Z, w)$ obviously satisfies

\begin{align}
Z + A(z(w_1)) - A(z(w_2)) = 0 \quad &\text{a.e. in } \Omega \times (0, T), \\
\delta Z + A_Z + \chi_1 - \chi_2^2 - Z = w \quad &\text{a.e. in } \Omega \times (0, T). 
\end{align}

(6.1) \hspace{1cm} (6.2)

Following the proof of [32, Proposition 2.1], we test (6.1) by $\mathcal{N}(w - m(w))$, (6.2) by $\mathcal{N}(Z) + Z$, add the resulting equations, and integrate over $(0, t), t \in (0, T)$. We refer to the proof of [32, Proposition 2.1] for all the detailed computations, leading to (cf. [32, (3.51)])

\begin{equation}
\int_0^t \|w\|^2_H + \delta \int_0^t \|\mathcal{N}(Z)\|^2_{V} + \delta \|Z(t)\|^2_{H} + \int_0^t \|\nabla Z\|^2_{H} \leq C(\|Z_0\|^2_{H} + \int_0^t \|Z\|^2_{H}). \tag{6.3}
\end{equation}

An easy application of Gronwall’s lemma to the function $t \mapsto \|Z(t)\|^2_{H}$ entails

\begin{equation}
\|Z\|^2_{C^4(\{0, t\}; \mathcal{L}^2(0, r, V))} + \|Z\|^2_{\mathcal{L}^2(0, r, V)} + \|w\|^2_{\mathcal{L}^2(0, r, H)} \leq c_\delta \|Z_0\|^2_{H}. \tag{6.4}
\end{equation}

Furthermore, exploiting (H8) and the above (6.4), it follows from the Hölder inequality that

\begin{align}
\|\phi(Z_1) - \phi(Z_2)\|^2_{\mathcal{L}^2(0, r, H)} \\
\leq C \int_0^t \int_\Omega |Z|^2(\chi_1^2 + \chi_2^2 + 1)^2 \\
\leq C \int_0^t (\|Z_1\|^2_{\mathcal{L}^1(\Omega)} + \|Z_2\|^2_{\mathcal{L}^1(\Omega)}) \|Z\|^2_{\mathcal{L}^1(\Omega)} + C \int_0^t \int_\Omega |Z|^2 \\
\leq C(\|X_1\|^4_{\mathcal{L}^2(\{0, t\}; \mathcal{L}^1(\Omega))} + \|Z_2\|^4_{\mathcal{L}^2(\{0, t\}; \mathcal{L}^1(\Omega))} + 1)\|Z\|^2_{\mathcal{L}^2(0, r, V)} \leq c_\delta \|Z_0\|^2_{H}. \tag{6.5}
\end{align}

Next, we test (6.2) by $Z$, and integrate in time to obtain

\begin{align}
\frac{\delta}{2} \int_0^t \|Z\|^2_H + \frac{1}{2} \|\nabla Z(t)\|^2_H \\
\leq \frac{1}{2} \|\nabla Z_0\|^2_H + c_\delta \left( \int_0^t \|w\|^2_H + \int_0^t \|\phi(Z_1) - \phi(Z_2)\|^2_H + \int_0^t \|Z\|^2_H \right). \tag{6.6}
\end{align}

In view of (6.4)–(6.6), we readily infer the continuous dependence estimate (3.27) for $Z$ in $C^0(\{0, t\}; V) \cap H^1(0, t; H)$. Then, the estimate for $\|Z\|^2_{\mathcal{L}^2(0, r, Z)}$ follows from (6.4)–(6.6) by a comparison argument. \hfill \Box

Proof of Theorem 3.2. Referring to the notation of the proof of Theorem 3.1, we again test (6.1) by $\mathcal{N}(w - m(w))$, (6.2) by $\mathcal{N}(Z) + Z$, add the resulting equations, and integrate over $(0, t), t \in (0, T)$. Developing the same calculations as in the above lines, we note that the chain of inequalities (6.5) is now trivial, since under
the present assumptions the functions $\chi_1$ and $\chi_2$ are estimated in $L^\infty(0, T; Z)$ (see Proposition 3.3). On the other hand, the following term:

$$I := \int_0^t \int_\Omega m(w)(x(w_1) - x(w_2)),$$

which was easily estimated in the proof of Theorem 3.1, now needs to be carefully handled because of the (at most) quadratic controlled growth of $x'$. Indeed, observe that

$$|I| \leq \int_0^t \|m(w)\|_{L^\infty(\Omega)} \|x(w_1) - x(w_2)\|_{L^1(\Omega)}$$

$$\leq C \int_0^t \left( \|m(w)\|_{L^1(\Omega)} \int_\Omega (1 + |w_1|^{2p} + |w_2|^{2p}) w \right)$$

$$\leq C \int_0^t \left( \|x_1 - x_2\|_{L^1(\Omega)} \|1 + \|w_1\|^2_{L^\infty(\Omega)} + \|w_2\|^2_{L^\infty(\Omega)}\|w\|_{L^1(\Omega)} \right)$$

$$\leq C \int_0^t \left( \|x_1 - x_2\|_{L^1(\Omega)} \|1 + \|w_1\|^2_{L^\infty(\Omega)} + \|w_2\|^2_{L^\infty(\Omega)}\|w\|_{L^1(\Omega)} \right)$$

$$\leq \varphi \int_0^t \|w\|^2_{L^2} + C \int_0^t \left( 1 + \|w_1\|^2_{L^\infty(\Omega)} + \|w_2\|^2_{L^\infty(\Omega)} \right) \|Z\|^2_{H}$$

for some $\varphi \in (0, 1)$ and $C > 0$, where the estimate $\|x_1 - x_2\|_{L^1(\Omega)} \leq C \|x\|_{L^1(\Omega)}$ can be obtained arguing as in (6.5) and using the bound for $x_1$ and $x_2$ in $L^\infty(0, T; Z)$.

This modification gives, in place of (6.3),

$$(1 - \varphi) \int_0^t \|w\|^2_{L^2} + \delta \int_0^t \|N(z)\|^2_{L^2} + \|z(t)\|^2_{L^2} + \int_0^t \|\nabla z\|^2_{L^2}$$

$$\leq C \|Z\|^2_{H} + \int_0^t \left( 1 + \|w_1\|^2_{L^\infty(\Omega)} + \|w_2\|^2_{L^\infty(\Omega)} \right) \|Z\|^2_{H}.$$}

Thus, recalling (3.21), we can use Gronwall’s lemma to deduce (6.4). Estimate (6.6) can be obtained by arguing as in the proof of Theorem 3.1, hence the result. \hfill \square

### A. Appendix

We propose the following approximate system for both Problems 1 and 2:

$$\chi_t + A(x_1'(w)) = 0 \quad \text{a.e. in } \Omega \times (0, T), \quad (A.1)$$

$$\delta \chi_t + A\chi + \phi_{\mu}(z) = w \quad \text{a.e. in } \Omega \times (0, T), \quad (A.2)$$

depending on the parameters $\delta, M, \mu > 0$, where

$$x_1'(r) = \begin{cases} x(-M) + C_1(r - M) & \text{if } r < -M, \\ x(r) & \text{if } |r| \leq M, \\ x(M) + C_1(r - M) & \text{if } r > M, \end{cases} \quad (A.3)$$
$C_1$ being the same constant as in (H1), and

$$
\phi_\mu(r) = \begin{cases} 
\phi(r) & \text{if } |\phi(r)| \leq \frac{1}{\mu}, \\
\frac{1}{\mu} \text{sign}(r) & \text{otherwise.}
\end{cases}
$$

(A.4)

It is immediate to check that, for any choice of the approximation parameters $M$ and $\mu$, the functions $x_M$ and $\phi_\mu$ are Lipschitz continuous on $\mathbb{R}$ and that

$$
x_M \to x \quad \text{uniformly on compact subsets of } \mathbb{R} \text{ as } M \not\to +\infty,
$$

$$
\phi_\mu \to \phi \quad \text{uniformly on compact subsets of } \text{dom}(\phi) \text{ as } \mu \not\searrow 0. 
$$

(A.5)

Of course, the Lipschitz constants of $x_M$ and $\phi_\mu$ explode as $M \not\to +\infty$ and $\mu \not\searrow 0$, respectively. Let us also point out that, by construction,

$$
x'_M(r) \geq C_1 > 0 \quad \text{for all } r \in \mathbb{R}, \quad M > 0,
$$

(A.6)

which yields that the inverse $\rho_M : \mathbb{R} \to \mathbb{R}$ of $x_M$ is Lipschitz continuous, with

$$
|\rho_M(x) - \rho_M(y)| \leq \frac{1}{C_1} |x - y| \quad \text{for all } x, y \in \mathbb{R}, \quad M > 0.
$$

(A.7)

What is more, relying on convergence (A.5) of $\phi_\mu$ to $\phi$, one can also check that, for $\mu > 0$ sufficiently small (say $0 < \mu \leq \mu_*$), (3.5) and (H3) hold on this approximate level as well, i.e.,

$$
\forall m \in \text{dom}(\phi) = (a, b) \quad \exists C_m, C'_m > 0 : \forall 0 < \mu \leq \mu_* \forall r \in (a - m, b - m)
$$

$$
|\phi_\mu(r + m)| \leq C_m \phi_\mu(r + m)r + C'_m,
$$

(A.8)

as well as

$$
\exists C > 0 : \forall 0 < \mu \leq \mu_* \forall r \in (a, b) \quad |\phi_\mu(r)|^\sigma \leq C(\phi_\mu(r) + 1),
$$

(A.9)

with $\sigma \in (0, 1)$ as in (H3), in particular, complying with the compatibility condition (H4).

It was proved in [32, Theorem 2.1] that, for every $\delta, M, \mu > 0$, there exists a unique pair $(\chi, w)$, with

$$
\chi \in L^2(0, T; Z) \cap L^\infty(0, T; V) \cap H^1(0, T; H),
$$

$$
w \in L^2(0, T; V),
$$

(A.10)

solving the Cauchy problem for system (A.1)–(A.2), supplemented with some initial datum $\chi^0 \in V$. 
**Problem** $\mathbf{P}_{\delta,M}$ In what follows, we approximate the initial datum $\chi_0 \in V$ in (3.12) by a sequence

$$\{\chi_{0,\mu}\} \subset H^4(\Omega) \text{ with } \chi_{0,\mu} \rightharpoonup \chi_0 \text{ in } V \text{ and } \sup_{\mu > 0} \|\phi_\mu(\chi_{0,\mu})\|_{L^1(\Omega)} < +\infty$$  \hspace{1cm} (A.11)

(for example, we can construct $\{\chi_{0,\mu}\}$ by applying (twice) the elliptic regularization procedure developed in the proof of [5, Proposition 2.6]).

For every $\delta, M, \mu > 0$, we call $\mathbf{P}_{\delta,M,\mu}$ the initial and boundary value problem obtained by supplementing the PDE system (A.1)–(A.2) with the initial condition

$$\chi(0) = \chi_{0,\mu} \text{ in } H^4(\Omega).$$  \hspace{1cm} (A.12)

In the following Section A.1, we will prove some further regularity of the approximate solutions. In this way, we will justify, on the level of the approximate Problem $\mathbf{P}_{\delta,M,\mu}$, the estimates formally performed in Section 4.1. Hence, in Section A.2, we will develop the rigorous proof of Theorem 1 by relying on the aforementioned estimates and by passing to the limit in Problem $\mathbf{P}_{\delta,M,\mu}$, first as $\delta \searrow 0$ for $M, \mu > 0$ fixed, then as $M \nearrow +\infty$ for $\mu > 0$ fixed, and, finally, as $\mu \searrow 0$.

Furthermore, it would be possible to give a rigorous proof of Theorem 2 by passing to the limit in Problem $\mathbf{P}_{\delta,M,\mu}$, first as $M \nearrow +\infty$ for $\mu > 0$ fixed, and then as $\mu \searrow 0$. However, we are not going to enter into the details of the latter procedure, which follows the very same lines as the one for Theorem 1.

**Notation A.1.** In what follows, we denote by $C_{\delta,M,\mu}$ various constants (which can differ from occurrence to occurrence, even in the same line), depending on the parameters $\delta, M$, and $\mu$, and such that $C_{\delta,M,\mu} \nearrow +\infty$ as either $\delta \searrow 0$, or $M \nearrow +\infty$, or $\mu \searrow 0$. The symbols $C_{\delta,\mu}$, $C_{M,\mu}$, and $C_\mu$ have an analogous meaning.

**A.1. Enhanced Regularity Estimates on the Approximate Problem**

**First estimate.** We note that $w \in L^2(0, T; V)$ and that, since $\phi_\mu$ is a Lipschitz continuous function, $\chi \in L^\infty(0, T; V)$ (cf. (A.10)) implies $\phi_\mu(\chi) \in L^\infty(0, T; V)$. Thus, by comparison in (A.2), we have $\delta \chi + A\chi \in L^2(0, T; V)$. Hence, testing (A.2) by $A(\partial_t \chi)$ and using the fact that $\chi(0) = \chi_{0,\mu} \in Z$, we deduce the estimate

$$\|\nabla \partial_t \chi\|_{L^2(0, T; H)} + \|A\chi\|_{L^\infty(0, T; H)} \leq C_{\delta,\mu},$$  \hspace{1cm} (A.13)

whence

$$\chi \in L^\infty(0, T; Z) \cap H^1(0, T; V).$$  \hspace{1cm} (A.14)

**Second estimate.** Since $\varphi_M$ is Lipschitz continuous and $w \in L^2(0, T; V)$, we have $\varphi_M(w) \in L^2(0, T; V)$. Estimate (A.13) and a comparison in (A.1) yield a bound for $A(\varphi_M(w))$ in $L^2(0, T; V)$, whence

$$\varphi_M(w) \in L^2(0, T; H^3(\Omega)) \subset L^2(0, T; W^{1,\infty}(\Omega)).$$
Recalling (A.7) and using the fact that \( w = \rho_m(x_m(w)) \), we readily deduce the estimate

\[
\|w\|_{L^2(0,T,W^{1,\infty}((\Omega)))} \leq C_{\delta,M,\mu},
\]  

(A.15)

**Third estimate.** Using a parabolic regularity argument in (A.2) and relying on regularity (A.11) for the approximate initial datum \( x_{0,\mu} \), we deduce that

\[
\|\partial_t x\|_{L^2(0,T,W^{1,1+\epsilon}(\Omega))} + \|A_x\|_{L^2(0,T,W^{1,1+\epsilon}(\Omega))} \leq C_{\delta,M,\mu},
\]

(A.16)

where \( \epsilon > 0 \) is a suitable number. More precisely, since \( x_{0,\mu} \in H^2(\Omega) \subset W^{1,1+\epsilon}(\Omega) \), the above formula holds for any \( \epsilon \in (0,3] \) (cf. inequality (A.26) below for a justification). Thus, by interpolation, we obtain that \( \nabla x \) belongs to \( H^{1/2}(0,T; W^{1,3+\epsilon}(\Omega)) \) and, recalling the continuous embedding \( W^{1,3+\epsilon}(\Omega) \subset L^{\infty}(\Omega) \), we conclude that

\[
\|\nabla_x\|_{L^{\infty}(0,T;L^{\infty}(\Omega))} \leq C_{\delta,M,\mu},
\]

(A.17)

**Fourth estimate.** Notice that, for almost all \( t \in (0,T) \), the function \( \nabla(|w(t)|^p w(t)) = (p+1)|w(t)|^p \nabla w(t) \) belongs to \( L^2(\Omega) \), thanks to (A.10) and (A.15). Hence, for a.a. \( t \in (0,T) \), we can test (A.2) by \( |w(t)|^p w(t) \), which yields

\[
\int_{\Omega} |w(t)|^{p+2} = \int_{\Omega} \nabla_x(t) \cdot \nabla(|w(t)|^p w(t)) + \int_{\Omega} \phi_\mu(x(t))|w(t)|^p w(t)
+ \delta \int_{\Omega} \partial_t x(t)|w(t)|^p w(t)
= (p+1) \int_{\Omega} |w(t)|^p \nabla_x(t) \cdot \nabla w(t) + \int_{\Omega} \phi_\mu(x(t))|w(t)|^p w(t)
- \delta(p+1) \int_{\Omega} x_m'(w(t))|w(t)|^p |\nabla w(t)|^2,
\]

(A.18)

the second equality following from equation (A.1). We estimate the second term on the right-hand side of the above equality by using the bound for \( \phi_\mu(x) \) in \( L^\infty(0,T;L^{\infty}(\Omega)) \), due to (A.14) and the Lipschitz continuity of \( \phi_\mu \). We deal with the first integral term as follows:

\[
\left| \int_{\Omega} |w(t)|^p \nabla_x(t) \cdot \nabla w(t) \right| \leq \|w(t)|^{p/2} \nabla w(t)\|_{L^2(\Omega)} \|w(t)|^{p/2} \|_{L^2(\Omega)} \| \nabla_x(t) \|_{L^{\infty}}
\leq \rho \int_{\Omega} |w(t)|^2 |\nabla w(t)|^2 + C_{\delta,M,\mu} \int_{\Omega} |w(t)|^p
\]

(A.19)

for some suitable positive constant \( \rho \), where we have also used (A.17). Now, recalling (A.6), we estimate the last summand on the right-hand side of (A.18) by

\[-\delta(p+1) \int_{\Omega} x_m'(w(t))|w(t)|^p |\nabla w(t)|^2 \leq -\delta(p+1)C_1 \int_{\Omega} |w(t)|^p |\nabla w(t)|^2;
\]

and we move the above term to the left-hand side of (A.18). Then, we combine the latter inequality with (A.19), in which we choose \( \rho = \frac{\delta(p+1)}{4}C_1 \). We thus obtain, for
Analysis of the Cahn–Hilliard Equation

A.2. Rigorous Proof of Theorem 1

Within this section, for all \( \delta, \mu > 0 \), we will denote by \( \{ (\chi_{\delta,M,\mu}, u_{\delta,M,\mu}) \}_{\delta,M,\mu} \) the family of solutions to Problem \( P_{\delta,M,\mu} \).

First step. For fixed \( \mu, M > 0 \), we pass to the limit in Problem \( P_{\delta,M,\mu} \) as \( \delta \searrow 0 \). We then perform the same calculations as in Section 4.1 (cf. (4.1)–(4.2), (4.6), (4.7)–(4.10)). Also relying on (A.8)–(A.9), we conclude that

\[
\exists C > 0 : \forall \delta, M, \mu > 0 \quad \| \chi_{\delta,M,\mu} \|_{L^\infty(0,T;Y)} + \| u_{\delta,M,\mu} \|_{L^2(0,T;Y)} + \| \phi_\mu(\chi_{\delta,M,\mu}) \|_{L^\infty(0,T;L^1(\Omega))} + \phi_\mu(\chi_{\delta,M,\mu}) \leq C.
\]  

(A.23)

Recalling the definition of \( \phi_\mu \) and its Lipschitz continuity, we also have

\[
\exists C_\mu > 0 : \forall \delta, M > 0 \quad \| \phi_\mu(\chi_{\delta,M,\mu}) \|_{L^\infty(0,T;V)} \leq C_\mu.
\]  

(A.24)

In the same way, estimate (A.23) for \( u_{\delta,M,\mu} \) and the Lipschitz continuity of \( \chi_{M} \) yield

\[
\exists C_M > 0 : \forall \delta, \mu > 0 \quad \| \chi_{\delta,M,\mu} \|_{L^\infty(0,T;V)} \leq C_M.
\]  

(A.25)

Next, set \( \ell_{\delta,M,\mu} := u_{\delta,M,\mu} - \phi_\mu(\chi_{\delta,M,\mu}) \). Then, (3.19) can be rewritten as the heat equation

\[
\ell_{\delta,M,\mu} + A\chi_{\delta,M,\mu} = \ell_{\delta,M,\mu} \quad \text{a.e. in } \Omega \times (0,T).
\]

A comparison argument and the maximal parabolic regularity result from [21] yield

\[
c(\delta) \int_0^T \| \ell_{\delta,M,\mu} \|_{L^2(\Omega)}^2 + \int_0^T \| A\chi_{\delta,M,\mu} \|_{L^2(\Omega)}^2 \leq C \int_0^T \| \ell_{\delta,M,\mu} - A\chi_{\delta,M,\mu} \|_{L^2(\Omega)}^2.
\]  

(A.26)

In view of estimates (A.23) for \( u_{\delta,M,\mu} \), (A.24) for \( \phi_\mu(\chi_{\delta,M,\mu}) \) in \( L^\infty(0,T;V) \), and (A.11) for \( \{ \ell_{0,\mu} \} \), we conclude that

\[
\| \ell_{\delta,M,\mu} \|_{L^2(0,T;L^2(\Omega))} \leq C_\mu.
\]
Therefore, (A.26) gives
\[ \exists C_\mu > 0 : \forall \delta, M > 0 \quad \| \partial_t x_{\delta, M, \mu} \|_{L^2(0, T; W^{1,6}(\Omega))} \leq C_\mu. \]  
(A.27)

On the other hand, estimate (A.25) and a comparison in (A.1) imply
\[ \exists C_M > 0 : \forall \delta, \mu > 0 \quad \| \partial_t x_{\delta, M, \mu} \|_{L^2(0, T; V')} \leq C_M. \]  
(A.28)

On behalf of the above estimates and arguing in the very same way as in Section 4.2, we see that, for every fixed \( M > 0 \) and \( \mu > 0 \), there exist a sequence \( \delta_k \downarrow 0 \) (for notational simplicity, we do not highlight its dependence on the parameters \( M \) and \( \mu \)) and functions \((x_{M, \mu}, w_{M, \mu}, \overline{z}_{M, \mu})\) such that the sequence \( \{(x_{h_k, M, \mu}, w_{h_k, M, \mu})\} \) converges to \((x_{M, \mu}, w_{M, \mu})\), as \( k \to +\infty \), in the sense specified by (4.29)–(4.30), (4.32), as well as
\[ \partial_t x_{h_k, M, \mu} \to \partial_t x_{M, \mu} \quad \text{in} \ L^2(0, T; V'), \]
\[ \delta_k^{1/2} \partial_t x_{h_k, M, \mu} \to 0 \quad \text{in} \ L^2(0, T; H), \]
\[ x_{M}(w_{h_k, M, \mu}) \to \overline{z}_{M, \mu} \quad \text{in} \ L^2(0, T; V). \]

Next, arguing similarly to the (formal) proof of Theorem 1, we conclude that
\[ \phi_{\mu}(x_{h_k, M, \mu}) \to \phi_{\mu}(x_{M, \mu}) \quad \text{in} \ L^2(0, T; H). \]  
(A.29)

Finally, we use (A.29) in the very same way as in Section 4.2 to infer
\[ \overline{z}_{M, \mu} = z_{M}(w_{M, \mu}) \]
and
\[ z_{M}(w_{h_k, M, \mu}) \to z_{M}(w_{M, \mu}) \quad \text{in} \ L^2(0, T; H). \]

Therefore, we conclude that the pair \((x_{M, \mu}, w_{M, \mu})\) is a solution to the PDE system
\[ x_t + A(z_{M}(w)) = 0 \quad \text{a.e. in} \ \Omega \times (0, T), \]  
(A.30)
\[ A\chi + \phi_{\mu}(\chi) = w \quad \text{a.e. in} \ \Omega \times (0, T), \]  
(A.31)
supplemented with the initial condition (A.12).

Second step. We now take the limit \( M \uparrow +\infty \) in (the Cauchy problem for) (A.30)–(A.31). Estimates (A.23) and (A.24) hold for the sequence of solutions \((x_{M, \mu}, w_{M, \mu})\)_M as well. Furthermore, using a lower-semicontinuity argument, we also deduce from (A.27) that
\[ \| x_{M, \mu} \|_{L^2(0, T; W^{1,6}(\Omega))} \leq C_\mu \quad \text{for all} \ M > 0. \]  
(A.32)

Now, we point out that (A.23) entails
\[ \int_0^T \int_\Omega x_{M}(w_{M, \mu})|\nabla w_{M, \mu}|^2 \leq C \quad \text{for all} \ M > 0. \]  
(A.33)
Let us denote by $\overline{\mathcal{T}}_M$ the truncation operator at level $M$ and define

$$
\tau_M := \overline{\mathcal{T}}_M (w_{M, \mu}) := \begin{cases} 
-M & \text{if } w_{M, \mu} < -M, \\
w_{M, \mu} & \text{if } |w_{M, \mu}| \leq M, \quad \text{a.e. } t \in \Omega \times (0, T) \\
M & \text{if } w_{M, \mu} > M,
\end{cases}
$$

(A.34)

(to simplify, we omit the index $\mu$ in the notation for $\tau_M$). For later use, we also introduce for a.e. $t \in (0, T)$ the sets

$$
\begin{align*}
\mathcal{J}_M & := \{(x, t) \in \Omega \times (0, T) : |w_{M, \mu}(x, t)| \leq M\}, \\
\mathcal{E}_M & := \{(x, t) \in \Omega \times (0, T) : |w_{M, \mu}(x, t)| > M\}, \\
\mathcal{E}_M^t & := \{x \in \Omega : (x, t) \in \mathcal{E}_M\}.
\end{align*}
$$

(A.35)

From (A.33), we also infer

$$
\int_0^T \int_\Omega \nabla \tau_M \cdot \nabla \tau_M \leq C \quad \text{for all } M > 0,
$$

whence, in view of (H1),

$$
\|\tau_M\|_{L^2(0, T; \mathbb{R})} \leq C \quad \text{for all } M > 0.
$$

(A.36)

Now, in order to reproduce estimates (4.23)–(4.24b) in the present approximate setting, we test (A.31) by $|\tau_M(t)|^p \tau_M(t)$ for a.e. $t \in (0, T)$. Clearly,

$$
\int_\Omega w_{M, \mu}(t)|\tau_M(t)|^p \tau_M(t) \geq \int_\Omega |\tau_M(t)|^{p+2},
$$

so that we have (cf. also (A.18))

$$
\int_\Omega |\tau_M(t)|^{p+2} \leq (p + 1) \int_\Omega |\tau_M(t)|^p \nabla \tau_M(t) \cdot \nabla \tau_M(t) + \int_\Omega \phi_{\mu}(x, t, \tau_M(t)) |\tau_M(t)|^p \tau_M(t) \leq (p + 1) \|\tau_M(t)|^p \nabla \tau_M(t)\|_H \|\nabla \tau_M(t)\|_H + C_\mu \int_\Omega |\tau_M(t)|^{p+1}
\leq C\|\tau_M(t)|^p \nabla \tau_M(t)\|_H + \frac{1}{2} \int_\Omega |\tau_M(t)|^{p+2} + C_\mu,
$$

(A.37)

where the second inequality follows from estimate (A.24) and the last one from (A.23) and Young’s inequality. Therefore, combining (A.36) and (A.37), we find an estimate for $\|\tau_M\|_{L^{p+2}(\Omega)}$ in $L^2(0, T)$ with some constant $C_\mu > 0$ which is independent of $M > 0$. On behalf of (A.34)–(A.35), from the latter bound, we infer (recall that $| \cdot |$ also denotes the Lebesgue measure)

$$
C_\mu \geq \int_0^T \left( \int_{\mathcal{E}_M} |M|^{p+2} \, dx \right)^2 \, dt = M^{2p+4} \int_0^T |\mathcal{E}_M^t| \, dt \\
\geq \frac{M^{2p+4}}{T} \|\tau_M\|_H^2 \quad \text{for all } M > 0,
$$

(A.38)
where the last inequality is a direct consequence of Jensen’s inequality. Next, we apply the nonlinear Poincaré inequality (2.15) to $|\tau_M|^p \tau_M$, thus obtaining (cf. (4.22))

$$\|\tau_M|^p \tau_M\|_V \leq K(\|\nabla (|\tau_M|^p \tau_M)\|_H + |m(\tau_M)|^{p+1}).$$

In view of (A.36) and of the definition of $\tau_M$, we find an estimate for $|\tau_M|^p \tau_M$ in $L^2(0, T; V)$, again with some constant $C_\mu$ which is independent of $M > 0$. Hence, using the fact that $V \subset L^2(\Omega)$ and the growth condition (H1) for $x$, we conclude that

$$\|x(\tau_M)\|_{L^{\rho_0}(0, T; L^\rho(\Omega))} \leq C_\mu \text{ for all } M > 0 \tag{A.39}$$

(where the indexes $\rho_0$ and $\kappa_0$ are as in (3.6): in particular, $1 < \rho_0 < 2$). Therefore, we have

$$\int_0^T \int_\Omega |x_M(w_{M,\mu})|^\rho \leq \int_0^T \int_\Omega |x(\tau_M)|^\rho + 2^{\rho-1} \int_0^T \int_{\partial\Omega} |x(M)|^\rho + 2^{\rho-1} C_\mu \int_0^T \int_{\partial\Omega} |w_{M,\mu} - M|^\rho$$

$$\leq 2^{\rho-1} \int_0^T \int_\Omega |x(\tau_M)|^\rho + C \|w_{M,\mu}\|_{L^\rho(0, T; L^\rho(\Omega))}^\rho + CM^\rho \|\Theta_M\|$$

$$\leq C_\mu + C + C \frac{M^\rho}{M^{p+2}},$$

where the first inequality follows from the very definition (A.3) of $x_M$, the second one from trivial calculations, and the last one from estimates (A.23) for $|\Theta_M|$, and (A.39) for $x(\tau_M)$. Note that, since $\rho_0 < 2$, we have $M^\rho / M^{p+2} \to 0$ as $M \to +\infty$.

Altogether, we find

$$\|x_M(w_{M,\mu})\|_{L^\rho(0, T; L^\rho(\Omega))} \leq C_\mu \text{ for all } M > 0, \tag{A.40}$$

which yields, by comparison in (A.30),

$$\|\tilde{e}_t x_M\|_{L^\rho(0, T; W^{-2,\rho}(\Omega))} \leq C_\mu \text{ for all } M > 0, \tag{A.41}$$

$W^{-2,\rho}(\Omega)$ denoting here the standard negative order Sobolev space.

Collecting estimates (A.23), (A.24), (A.32), and (A.40)–(A.41), we then argue in the same way as in Section 4.2. Thus, we conclude that there exist a subsequence $M_k \to +\infty$ as $k \to +\infty$ (whose dependence on the index $\mu > 0$ is not highlighted) and functions $(x_\mu, w_\mu)$ fulfilling (3.13)–(3.14) such that the functions $(x_{M_k,\mu}, w_{M_k,\mu})$ converge, as $k \to +\infty$, to $(x_\mu, w_\mu)$ in the same sense as in (4.29)–(4.30) and (4.32), while, in place of (4.31), we only have

$$\tilde{e}_t x_{M_k,\mu} \to \tilde{e}_t x_\mu \text{ in } L^\rho(0, T; W^{-2,\rho}(\Omega)),$$

which is, anyway, sufficient for what follows. Furthermore, there exists some $\tilde{x}_\mu \in L^\rho(0, T; L^\rho(\Omega))$ such that

$$x_M(w_{M,\mu}) \to \tilde{x}_\mu \text{ in } L^\rho(0, T; L^\rho(\Omega)).$$
Again, we prove that
\[ \phi_{\mu}(x_{M_k}\mu) \rightarrow \phi_{\mu}(x_\mu) \quad \text{in} \ L^2(0, T; H) \]  
(A.42)
and, proceeding as in Section 4.2, with (A.42) we show that \( x_\mu \approx x(w_\mu) \) and
\[ x_{M_k}(w_{M_k}\mu) \rightarrow x(w_\mu) \quad \text{in} \ L^1(0, T; L^1(\Omega)). \]
Having this, we conclude that the pair \((x_\mu, w_\mu)\) is solution to the PDE system
\[ \chi_t + A(x(w)) = 0 \quad \text{a.e. in} \ \Omega \times (0, T), \]  
(A.43)
\[ A\chi + \phi_{\mu}(x) = w \quad \text{a.e. in} \ \Omega \times (0, T), \]  
(A.44)
supplemented with the initial condition (A.12).

**Third step.** Finally, we take the limit \( \mu \downarrow 0 \) in (the Cauchy problem for) (A.43)–(A.44). Estimate (A.23), with \( x_M \) replaced by \( x \), holds for the sequence \( \{(x_\mu, w_\mu)\}_\mu \) for a constant \( C > 0 \) which is independent of the parameter \( \mu > 0 \).

Furthermore, using the fact that system (A.43)–(A.44) has the same structure as (3.18)–(3.19), we argue as in (4.14)–(4.15) and conclude that
\[ \exists C > 0 \ \forall \mu > 0 : \quad \|x_\mu\|_{L^2(0, T; W^{2,s}(\Omega))} + \|\phi_{\mu}(x_\mu)\|_{L^2(0, T; L^2(\Omega))} \leq C. \]
From the bound for \( (x'(w_\mu))^{1/2} \nabla w_\mu \) in \( L^2(0, T; H) \) (which follows from (A.33) by applying once more Ioffe’s theorem), developing the very same calculations as throughout (4.19)–(4.24b), we find
\[ \exists C > 0 \ \forall \mu > 0 : \quad \|\partial_t x_\mu\|_{L^p(0, T; \gamma''^{-2,2,2_s}(\Omega))} + \|x_\mu\|_{L^p(0, T; L^p(\Omega))} \]
\[ + \|\phi_{\mu}(x_\mu)\|_{L^\infty(0, T; L^1(\Omega))} \leq C \]  
(A.45)
(where the indexes \( \eta_\mu \) and \( q_\sigma \) are as in (3.6) and (4.20), respectively).

Thanks to the above estimates, we conclude that there exist a vanishing sequence \( \mu_t \downarrow 0 \) and functions \((x, w)\) satisfying (3.13)–(3.14) such that \( (x_{\mu_k}, w_{\mu_k}) \) converges to \((x, w)\) in the topologies of (4.29)–(4.33). We then pass to the limit as \( k \rightarrow +\infty \) in (A.11) and, also in view of (A.12), infer that \( x \) complies with the initial condition (3.15). Furthermore, we deduce from the strong convergence of \( x_{\mu_k} \) to \( x \) in \( L^2(0, T; H) \) that \( x_{\mu_k} \rightarrow x \) almost everywhere in \( \Omega \times (0, T) \). Using the uniform convergence (A.5) of \( \{(\phi_{\mu_k})\} \) to \( \phi \), we infer that
\[ \phi_{\mu_k}(x_{\mu_k}(x, t)) \rightarrow \phi(x(x, t)) \quad \text{for a.a.} \ (x, t) \in \Omega \times (0, T). \]
Then, taking into account the uniform integrability of \( \{\phi_{\mu}(x_{\mu_k})\} \) in \( L^2(0, T; H) \) (which follows from (A.45), noting that \( \sigma q_{\sigma} > 2 \), in view of Theorem 2.1 we obtain
\[ \phi_{\mu_k}(x_{\mu_k}) \rightarrow \phi(x) \quad \text{in} \ L^2(0, T; H). \]  
(A.46)
Then, we again argue as in Section 4.2 and use (A.46) to prove that
\[ x(w_{\mu_k}) \rightarrow x(w) \quad \text{in} \ L^1(0, T; L^1(\Omega)). \]
Having this, we conclude that the pair \((\chi, w)\) is solution to Problem 1, which finishes the proof.

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References

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