

BV functions and variational models in plasticity

(Maria Giovanna Mora, Enrico Vitali – Pavia)

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- ▶ Basic properties of the space BV of *functions with bounded variation* and of the space BD of *functions with bounded deformation*.

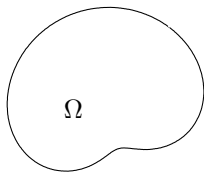
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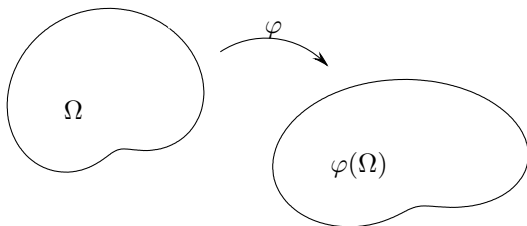
- ▶ Basic properties of the space BV of *functions with bounded variation* and of the space BD of *functions with bounded deformation*.
- ▶ Analysis of a variational model in plasticity (in the functional framework introduced in the first part).

A sketch of the main motivating problem



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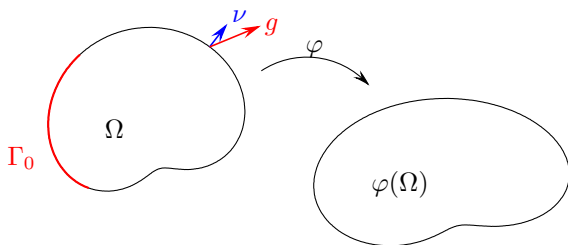
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+ **B.C.** (u prescribed on Γ_0 and external force prescribed on the complement)

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Assumption: $\mathbb{K} = K + \mathbb{R}I$, with K convex, compact neighbourhood of 0 in $M_D^{n \times n}$.

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The variational approach involves the energy functional

$$F(u) = \frac{1}{2} \int_{\Omega} Q(e) \, dx + \int_{\Omega} H(p) \, dx + \int_{\partial\Omega \setminus \Gamma_0} g(x) u(x) \, d\mathcal{H}^{n-1}$$

where:

Q : positive definite quadratic form
(elastic energy $\mathbb{C}e : e$)

H : positively 1-homogeneous convex function.
(H is the support function of K).

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Key fact: since H has linear growth, the minimization problem for F has, in general, no solution in Sobolev spaces; in the natural weak formulation, plastic deformations are allowed to take **measure values**. This agrees with the points of view of mechanics: shear deformations concentrates, and shear bands can be thought of as sharp discontinuities of the displacement.

This naturally leads to the space of functions with bounded deformation

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Thus, it looks quite natural the ‘preliminary’ study of the space of **functions with bounded variation**:

$$BV(\Omega) = \{u \in L^1(\Omega; \mathbb{R}^n) : \nabla u \text{ bounded} \\ \text{(matrix-valued) Radon measure}\}$$

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On the other hand, we point out the a wide classical literature makes the space BV a relevant functional space in modern variational analysis.

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For each given time discretization \mathcal{T}^k of an interval $[0, T]$

$$0 = t_k^k < t_1^k < \dots < t_k^k = T \quad (\max |t_i^k - t_{i-1}^k| \xrightarrow{k} 0)$$

we define a piecewise-constant evolution by minimizing iteratively

$$\frac{1}{2} \int_{\Omega} Q(e) \, dx + \int_{\Omega} H(p - p_{i-1}^k) \, dx + \int_{\partial\Omega \setminus \Gamma_0} g(t_i^k, x) u(x) \, d\mathcal{H}^{n-1}$$

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The relevant result is now passing to the limit (as $k \rightarrow \infty$) in order to get a **time-continuous** evolution.

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Sede: Pavia

Orario: 28-32 ore, 4 ore/settimana (eventualmente 2+2 matt.+pom.)
15 aprile – 15 giugno (approssimativamente)