PDEs for multiphase advanced materials Cortona, Arezzo, Italy

Existence for the steady problem of a mixture of two power-law fluids¹

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- Isothermal flows of viscous incompressible (and homogeneous) fluids in stationary regime:
 - Conservation of mass

$$\operatorname{div} \mathbf{u} = 0 \quad \text{in} \quad \Omega \subset \mathbb{R}^N, \tag{1}$$

• Conservation of linear momentum

$$\operatorname{div}(\mathbf{u}\otimes\mathbf{u})=\mathbf{f}-\nabla\rho+\operatorname{div}\mathbf{S}\quad\text{in}\quad\Omega; \tag{2}$$

• Deviatoric part of the Cauchy stress tensor

$$\mathbf{S} = \left(\mu_1 |\mathbf{D}|^{\gamma-2} + \mu_2 |\mathbf{D}|^{q(\mathbf{x})-2}\right) \mathbf{D}, \qquad \mathbf{D} = \frac{1}{2} \left(\nabla \mathbf{u} + \nabla \mathbf{u}^{\mathsf{T}}\right); \qquad (3)$$

Boundary conditions

$$\mathbf{u} = \mathbf{0}$$
 on $\partial \Omega$. (4)

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- Unknowns: $\mathbf{u} \in \mathbb{R}^N$ velocity field; $p \in \mathbb{R}^N$ pressure;
- Problem data: $\mathbf{f} \in \mathbb{R}^N$;
- Remark: Dimensions of interest in the applications are N = 2, N = 3

• The simplest model of Fluid Mech. is the Newtonian fluid: Stokes (1845)

$$\mathbf{S}=2\mu\mathbf{D},\quad \mu=\mathit{Const.}>0;$$

- Examples: water solutions, gasoline, vegetal and mineral oils, ...;
- Inadequate to model fluids that exhibit varying viscosities;
- Real fluids: μ may depend on temperature, shear rate $|\mathbf{D}|$, time, pressure;

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- Real fluids: μ may depend on temperature, shear rate $|\mathbf{D}|$, time, pressure;
- Ostwald (1925) de Waele (1923) simplest non-Newtonian model:

$$\mathbf{S} = \mu |\mathbf{D}|^{n-1} \mathbf{D} \equiv \mu |\mathbf{D}|^{\gamma-2} \mathbf{D} \Rightarrow \begin{cases} \text{Bingham (1921)} & n = 0 & \Leftrightarrow & \gamma = 1, \\ \text{pseudo-plastic} & 0 < n < 1 & \Leftrightarrow & 1 < \gamma < 2, \\ \text{Newtonian} & n = 1 & \Leftrightarrow & \gamma = 2, \\ \text{dilatant} & n > 1 & \Leftrightarrow & \gamma > 2, \end{cases}$$

- Examples: **Bingham** toothpaste, mayonnaise; **Pseudo-plastic** milk fluids, varnishes, shampoo, blood; **Dilatant** polar ice, volcano lava, wet sand .
- The viscosity depends on the shear stress (generalized Newtonian fluids);
- Proposed for modeling pseudo-plastic fluids; it has been used also for dilatant;
- Fails at high shear rates where the viscosity must ultimately be a constant;

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- Proposed for modeling pseudo-plastic fluids; it has been used also for dilatant;
- Fails at high shear rates where the viscosity must ultimately be a constant;
- The Sisko (1958) model: rectifies the failure of the Ostwald-de Waele

$$\mathbf{S} = \left(\mu_1 + \mu_2 |\mathbf{D}|^{\gamma-2} \right) \mathbf{D}$$

 It was originally proposed for high shear-rate measurements on some comercial greases (mixtures of petroleum with thickening agents).

- Cannot be cataloged into a single class.
- Ability to achieve a wide range of viscosity in a fraction of millisecond.
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• Typical MRF: made of very small solid particles that are suspended in a liquid (see e.g. *Magnetorheological fluids* by Henrie and Carlson (2002)).

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- Are being used: nanometer-sized particles dispersed in liquids (see e.g. Nanofluids: Science and Technology by Das, Choi, Yu and Pradeep (2007)).
- Applications: automobile industry, e.g. clutches (ERF) and shock absorbers (MRF), and modeling e.g. the cooling process of volcano lava flow (TRF).

• Trembling Sisko model:

$$\mathbf{S} = \left(\mu_1 + \mu_2 |\mathbf{D}|^{q(\mathbf{x})-2}\right) \mathbf{D}.$$
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• Justification of the model:

- The object of superposition of generalized fluids is to produce flow patterns similar to those of practical interest;
- The best example are polymer solutions in which the polymer segments tend to repel each other, since they prefer contact the solvent molecules rather then among themselves (see e.g. *Rheophysics* by P. Oswald (2009));
- Superposition of fluids is justified, in the light of theoretical mechanics, as a
 powerful tool to replace the Boltzman superposition principle² in the case of
 materials with nonlinear behavior (see e.g. *Nonlinear vsicoelasticity* by
 J.M. Dealy (2009)).
- Sisko's model has been checked experimentally to fit accurately the viscosity data of many mixtures (see e.g. *An introduction to rheology* by Barnes, Hutton and Walters (1993));

²In the linear viscoelastic regime the stress responses to successive deformations are additive. $\Box \rightarrow \langle \overline{\sigma} \rangle \land \overline{z} \rightarrow \langle \overline{z} \rangle$

- $\mathcal{P}(\Omega)$ the set of all measurable functions $q:\Omega o [1,\infty];$
- $L^{\hat{q}(\cdot)}(\Omega)$ the space of all functions $f \in \mathcal{P}(\Omega)$ such that

$$A_{q(\cdot)}(f) := \int_{\Omega} |f(x)|^{q(x)} dx < \infty, \quad \|f\|_{\mathrm{L}^{q(\cdot)}(\Omega)} := \inf\left\{\kappa > 0 : A_{q(\cdot)}\left(\frac{f}{\kappa}\right) \le 1\right\};$$

- $W^{1,q(\cdot)}(\Omega) := \{ f \in \mathrm{L}^{q(\cdot)}(\Omega) : \mathrm{D}^{\alpha} f \in \mathrm{L}^{q(\cdot)}(\Omega), \ 0 \le |\alpha| \le 1 \} ;$
- Inherit almost properties of classical Lebesgue and Sobolev spaces, provided

$$1 < \alpha := \operatorname{ess\,inf} q(\cdot) \le q(\cdot) \le \operatorname{ess\,sup} q(\cdot) := \beta < \infty; \tag{7}$$

• Orlicz-Sobolev space with zero boundary values:

$$W_0^{1,q(\cdot)}(\Omega) := \overline{\left\{f \in W^{1,q(\cdot)}(\Omega) : \mathrm{supp}\; f \subset \subset \Omega
ight\}} \stackrel{\|\cdot\|_{W^{1,q(\cdot)}(\Omega)}}{=}$$

One problem:

 $C_0^\infty(\Omega)$ is not necessarily dense in $W_0^{1,q(\cdot)}(\Omega)$

- The closure of $\mathrm{C}^{\infty}_{0}(\Omega)$ in $\mathrm{W}^{1,q(\cdot)}(\Omega)$ is strictly contained in $\mathrm{W}^{1,q(\cdot)}_{0}(\Omega)$;
- A necessary condition for the equality is the globally log-H continuity for $g = \frac{1}{q}$ (locally log-H continuous + log-H decay):

$$|g(\mathbf{x}) - g(\mathbf{y})| \leq \frac{C_1}{|\mathsf{n}(e+1/|\mathsf{x}-\mathsf{y}|)}, \quad |g(\mathbf{x}) - q_\infty| \leq \frac{C_2}{|\mathsf{n}(e+|\mathsf{x}|)} \quad \forall \ \mathsf{x}, \ \mathsf{y} \in \Omega.$$
(8)

- Spaces of Fluid Mechanics
 - $\mathcal{V} := \{ \mathbf{v} \in \mathbf{C}_0^\infty(\Omega) : \operatorname{div} \mathbf{v} = 0 \};$
 - $\mathbf{V}_{\gamma} := \text{closure of } \mathcal{V} \text{ in } \mathbf{W}^{1,\gamma}(\Omega)$. The power-law index $\gamma = \text{Const.}$; $\mathbf{V}_{q(\cdot)} := \text{closure of } \mathcal{V} \text{ in } \mathbf{W}^{1,q(\cdot)}(\Omega)$. Requires (8);

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Weak Formulation

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- $W_{q(\cdot)} := \text{closure of } \mathcal{V} \text{ in the } \|D(v)\|_{L^{q(\cdot)}(\Omega)} \text{ norm.}$

Definition

Let Ω be a bounded domain of \mathbb{R}^N , with $N \geq 2$. Assume that $\mathbf{f} \in \mathbf{L}^1(\Omega)$, γ is a constant such that $1 < \gamma < \infty$ and $q \in \mathcal{P}(\Omega)$ is a variable exponent satisfying to (7). A vector field \mathbf{u} is a (very) weak solution to the problem (1)-(3), if:

•
$$\mathbf{u} \in \mathbf{W}_{q(\cdot)} \cap \mathbf{V}_{\gamma};$$

• For every
$$arphi \in {\sf W}_{{m q}(\cdot)} \cap {\sf V}_\gamma$$
 (For every $arphi \in \mathcal{V})$

$$\int_{\Omega} \left(\mu_1 |\mathsf{D}(\mathsf{u})|^{\gamma-2} + \mu_2 |\mathsf{D}(\mathsf{u})|^{q(\mathsf{x})-2} - \mathsf{u} \otimes \mathsf{u} \right) : \mathsf{D}(\varphi) \, d\mathsf{x} = \int_{\Omega} \mathsf{f} \cdot \varphi \, d\mathsf{x}.$$

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• Remark: Note that if $\alpha \geq \gamma$, then $\mathbf{W}_{q(\cdot)} \hookrightarrow \mathbf{V}_{\gamma}$ and therefore it is enough to look for weak solutions in the class $\mathbf{W}_{q(\cdot)}$ and if $\gamma \geq \beta$, then $\mathbf{V}_{\gamma} \hookrightarrow \mathbf{W}_{q(\cdot)}$ and therefore it is enough to look for weak solutions in the class V_{γ} .

Historical background - existence for constant power-law indexes

- Navier-Stokes : Hopf (1951) (Leray (1934) for the Cauchy problem).
- Ladyzhenskaya (1967), Lions (1969): $\mathbf{f} \in \mathbf{V}'_{\gamma}$ and

$$\gamma \ge \frac{3N}{N+2}.$$
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- Ladyzhenskaya: $\mathbf{S} = \left(\mu_1 + \mu_2 |\mathbf{D}|^{\gamma-2}\right) \mathbf{D}$ and N = 3, and Lions: $\mathbf{S} = \mu |\mathbf{D}|^{\gamma-2} \mathbf{D}$
- Proof: Theory of monotone operators together with compactness arguments,
- The lower bound: $\gamma \geq \frac{3N}{N+2} \Rightarrow \mathbf{u} \otimes \mathbf{u} : \mathbf{D}(\varphi) \in \mathbf{L}^1(\Omega)$ for $\mathbf{u}, \ \varphi \in \mathbf{V}_{\gamma}$.

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- Frehse, Málek and Steinhauer (1997): $\mathbf{f} \in \mathbf{L}^{\gamma'}(\Omega)$; Ružička (1997): $\mathbf{f} \in \mathbf{V}'_{\gamma}$,

$$\gamma \ge \frac{2N}{N+1}.\tag{10}$$

- Proof: In addition, it was used the L^{∞} -truncation method.
- The lower bound: $\gamma \geq \frac{2N}{N+1} \Rightarrow (\mathbf{u} \cdot \nabla) \mathbf{u} \cdot \varphi \in \mathsf{L}^1(\Omega)$ for $\mathbf{u} \in \mathbf{V}_{\gamma}$ and $\varphi \in \mathcal{V}$.
- Frehse, Málek and Steinhauer (2003): $\mathbf{f} \in \mathbf{L}^{\gamma'}(\Omega)$ and

$$\gamma > \frac{2N}{N+2}.\tag{11}$$

- Proof: It was used the Lipschitz-truncation method instead.
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- The strict inequality $\gamma > \frac{2N}{N+2}$ is due to $V_{\gamma} \hookrightarrow \sqcup L^{2}(\Omega)$.
- Open problem: $1 < \gamma \leq \frac{2N}{N+2}$ and N > 2.

• Ružička (2000): $\mathbf{f} \in \mathbf{V}'_{lpha}$ and

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- Huber (2011): $\mathbf{f} \in (\mathbf{W}_0^{1,q(\cdot)}(\Omega))'$ and

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- The solution $\mathbf{u} \in \mathbf{V}_{q(\cdot)}$ (requires (8)) and the test function $\varphi \in \mathcal{V}$;
- Proof: combines Bogowski (1979) results on divergence problems in Orlicz-Sobolev spaces with the L^{∞} -truncation method.

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- Diening, Málek and Steinhauer (2008): the same assumptions of Huber,

$$\alpha > \frac{2N}{N+2}.$$
(14)

• The solutions satisfies to the energy relation:

$$\int_{\Omega} \left(\mathbf{S}(\mathbf{D}(\mathbf{u})) - \mathbf{u} \otimes \mathbf{u} \right) : \mathbf{D}(\varphi) \, d\mathbf{x} = \int_{\Omega} p \operatorname{div}\varphi \, d\mathbf{x} + \int_{\Omega} \mathbf{f} \cdot \varphi \, d\mathbf{x} \qquad \forall \, \varphi \in \mathbf{W}_{0}^{1,\infty}(\Omega)$$
(15)
• Proof: uses Lipschitz-truncations of functions in Orlicz-Sobolev spaces.

First Result

Theorem

Let Ω be a bounded domain in \mathbb{R}^N , $N \ge 2$, with a Lipschitz-continuous boundary $\partial \Omega$. Assume that $1 < \gamma < \infty$, $q \in \mathcal{P}(\Omega)$ satisfies to (7) and $\mathbf{f} \in (\mathbf{V}_{\gamma} \cap \mathbf{W}_{q(\cdot)})'$. Then, if

$$\min\left\{\gamma,\alpha\right\} \geq \frac{3N}{N+2}$$

there exists a weak solution to the problem (1)-(3).

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Remarks

- If γ = 2, it extends the existence result established by Ladyzhenskaya (1967) to the case of a variable exponent q;
- Since $V_{q(\cdot)} \subsetneq W_{q(\cdot)}$, this result is obtained in a larger class.

Main Result

Theorem

Let Ω be a bounded domain in \mathbb{R}^N , $N \geq 2$, with a Lipschitz-continuous boundary $\partial \Omega$. Assume that $q \in \mathcal{P}(\Omega)$ satisfies to (7) and $\mathbf{f} \in (\mathbf{V}_{\gamma} \cap \mathbf{W}_{q(\cdot)})'$. Then, if for any $\delta > 0$

$$\gamma \ge \max\left\{\frac{2N}{N+2} + \delta, \beta\right\},\tag{16}$$

there exists a very weak solution to the problem (1)-(3).

• For the trembling Sisko model we have existence of very weak solutions

$$\mathbf{S} = \left(\mu_1 + \mu_2 |\mathbf{D}|^{q(\mathbf{x})-2}\right) \mathbf{D} \quad \text{for } 1 < \alpha \le \beta \le 2.$$
 (17)

Main Result

Theorem

Let Ω be a bounded domain in \mathbb{R}^N , $N \ge 2$, with a Lipschitz-continuous boundary $\partial \Omega$. Assume that $q \in \mathcal{P}(\Omega)$ satisfies to (7) and $\mathbf{f} \in (\mathbf{V}_{\gamma} \cap \mathbf{W}_{q(\cdot)})'$. Then, if for any $\delta > 0$

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 (17)

In order to make the proof as transparent as possible, we shall assume that

$$\mathbf{f} = -\mathbf{div} \, \mathbf{F}, \quad \mathbf{F} \in \mathbb{M}_{\mathrm{sym}}^{N}, \quad \mathbf{F} \in \mathbf{L}^{q'(\cdot)}(\Omega).$$
 (18)

• The assumption (18) does not restrict the result's extent, because $\mathbf{f} = -\operatorname{div} \mathbf{F}$ and $\mathbf{F} \in \mathsf{L}^{q'(\cdot)}(\Omega)$ implies that $\mathbf{f} \in \mathsf{W}'_{q(\cdot)}$, and $\mathsf{W}'_{q(\cdot)} \hookrightarrow (\mathsf{V}_{\gamma} \cap \mathsf{W}_{q(\cdot)})'$.

• The assumption $\mathbf{F} \in \mathbb{M}_{\mathrm{sym}}^{N}$ is made in order to avoid unnecessary calculus.

• Let $\Phi \in C^{\infty}([0,\infty))$ be a non-increasing: $0 \le \Phi \le 1$ in $[0,\infty)$, $\Phi \equiv 1$ in [0,1], $\Phi \equiv 0$ in $[2,\infty)$ and $0 \le -\Phi' \le 2$. For $\epsilon > 0$, we set

$$\Phi_{\epsilon}(s) := \Phi(\epsilon s), \quad s \in [0, \infty).$$
 (19)

We consider the following regularized problem in Ω :

$$\operatorname{div} \mathbf{u}_{\epsilon} = \mathbf{0},\tag{20}$$

$$\begin{aligned} \mathsf{div}(\mathbf{u}_{\epsilon} \otimes \mathbf{u}_{\epsilon} \Phi_{\epsilon}(|\mathbf{u}_{\epsilon}|)) &= \mathbf{f} - \nabla p_{\epsilon} + \mathsf{div} \left[\left(\mu_{1} | \mathbf{D}(\mathbf{u}_{\epsilon})|^{\gamma-2} + \mu_{2} | \mathbf{D}(\mathbf{u}_{\epsilon})|^{q(\mathbf{x})-2} \right) \mathbf{D}(\mathbf{u}_{\epsilon}) \right], \end{aligned}$$

$$\begin{aligned} \mathbf{u}_{\epsilon} &= \mathbf{0} \quad \text{on} \quad \partial \Omega. \end{aligned}$$

$$\begin{aligned} (21) \\ (22) \end{aligned}$$

Proposition

... Then, for each $\epsilon > 0$, there exists a weak solution $\mathbf{u}_{\epsilon} \in \mathbf{V}_{\gamma}$ to the problem (20)-(22). In addition, every weak solution satisfies to the following energy equality:

$$\int_{\Omega} \left(\mu_1 | \mathbf{D}(\mathbf{u}_{\epsilon})|^{\gamma} + \mu_2 | \mathbf{D}(\mathbf{u}_{\epsilon})|^{q(\mathbf{x})} \right) d\mathbf{x} = \int_{\Omega} \mathbf{F} : \mathbf{D}(\mathbf{u}_{\epsilon}) d\mathbf{x}.$$
(23)

• The proof is based on Schauder's fixed point theorem.

• From (23), we can prove that

$$\int_{\Omega} \left(|\mathbf{D}(\mathbf{u}_{\epsilon})|^{\gamma} + |\mathbf{D}(\mathbf{u}_{\epsilon})|^{q(\mathbf{x})} \right) d\mathbf{x} \leq C.$$
(24)

• By Sobolev's inequality, and due to the definition of Φ_ϵ , we have

$$\|\mathbf{u}_{\epsilon}\otimes\mathbf{u}_{\epsilon}\Phi_{\epsilon}(|\mathbf{u}_{\epsilon}|)\|_{\mathsf{L}^{\frac{\gamma^{*}}{2}}(\Omega)}\leq C.$$
(25)

• From (24)-(25), there exists $\epsilon_m>0$ such that $\epsilon_m o 0$, as $m o\infty$, and

$$\mathbf{u}_{\epsilon_{\boldsymbol{m}}} o \mathbf{u}$$
 weakly in \mathbf{V}_{γ} , as $\boldsymbol{m} o \infty$, (26)

$$|\mathbf{D}(\mathbf{u}_{\epsilon_{m}})|^{\gamma-2}\mathbf{D}(\mathbf{u}_{\epsilon_{m}}) \to \mathbf{S}_{1} \quad \text{weakly in} \quad \mathbf{L}^{\gamma'}(\Omega), \quad \text{as} \quad m \to \infty,$$
(27)

$$|\mathsf{D}(\mathbf{u}_{\epsilon_m})|^{q(\mathbf{x})-2}\mathsf{D}(\mathbf{u}_{\epsilon_m})\to\mathsf{S}_2 \quad \text{weakly in} \quad \mathsf{L}^{\gamma'}(\Omega), \quad \text{as} \quad m\to\infty, \quad (28)$$

$$\mathbf{u}_{\epsilon_m} \otimes \mathbf{u}_{\epsilon_m} \Phi_{\epsilon_m}(|\mathbf{u}_{\epsilon_m}|) \to \mathbf{G} \quad \text{weakly in } \mathbf{L}^{\frac{\gamma}{2}}(\Omega), \text{ as } m \to \infty.$$
(29)

• Using (27)-(29), we can pass to the limit $m \to \infty$ in $\int_{\Omega} \left(\mu_1 |\mathbf{D}(\mathbf{u}_{\epsilon_m})|^{\gamma-2} + \mu_2 |\mathbf{D}(\mathbf{u}_{\epsilon_m})|^{q(\mathbf{x})-2} \right) \mathbf{D}(\mathbf{u}_{\epsilon_m}) : \mathbf{D}(\varphi) \, d\mathbf{x} = \int_{\Omega} \left[\mathbf{u}_{\epsilon_m} \otimes \mathbf{u}_{\epsilon_m} \Phi_{\epsilon_m}(|\mathbf{u}_{\epsilon_m}|) + \mathbf{F} \right] : \mathbf{D}(\varphi)$ (30)

valid for all
$$\varphi \in \mathcal{V}$$
, to obtain

$$\int_{\Omega} (\mu_1 \mathbf{S}_1 + \mu_2 \mathbf{S}_2 - \mathbf{G} - \mathbf{F}) : \mathbf{D}(\varphi) \, d\mathbf{x} = 0 \quad \forall \ \varphi \in \mathcal{V}. \tag{31}$$

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• Due to (26), the application of Sobolev's compact imbedding theorem implies

 $\mathbf{u}_{\epsilon_m} \to \mathbf{u}$ strongly in $\mathsf{L}^{\kappa}(\Omega)$, as $m \to \infty$, for any $\kappa : 1 \le \kappa < \gamma^*$. (32)

• Since (16) implies $2 < \gamma^*$, it follows from (32) that

$$\mathbf{u}_{\epsilon_{\boldsymbol{m}}} o \mathbf{u}$$
 strongly in $\mathsf{L}^2(\Omega)$, as $m o \infty$. (33)

• Using (19)) and the result (33), we can prove that

$$\mathbf{u}_{\epsilon_{\boldsymbol{m}}} \otimes \mathbf{u}_{\epsilon_{\boldsymbol{m}}} \Phi_{\epsilon_{\boldsymbol{m}}}(|\mathbf{u}_{\epsilon_{\boldsymbol{m}}}|) \to \mathbf{u} \otimes \mathbf{u} \quad \text{strongly in } \mathbf{L}^{1}(\Omega), \quad \text{as } \boldsymbol{m} \to \infty.$$
(34)

- Then gathering the information of (29) and (34), we see that $\mathbf{G} = \mathbf{u} \otimes \mathbf{u}$.
- Now in the limit $(m \to \infty)$ of the integral equation, we have

$$\int_{\Omega} (\mu_1 \mathbf{S}_1 + \mu_2 \mathbf{S}_2 - \mathbf{u} \otimes \mathbf{u} - \mathbf{F}) : \mathbf{D}(\varphi) \, d\mathbf{x} = 0 \quad \forall \ \varphi \in \mathcal{V}.$$
(35)

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- Since we shall use test functions which are not divergence free, we first have to determine the approximative pressure from the weak formulation (30).
- First, let ω' be a fixed but arbitrary open bounded subset of Ω such that

$$\omega' \subset \subset \Omega$$
 and $\partial \omega'$ is Lipschitz (36)

 We use a version of de Rham's Theorem³ (Bogovskii (1980) and Pileckas (1983)) to prove the existence of a unique function

$$p_{\epsilon_{m}} \in \mathbf{L}^{r'}(\omega'), \quad 1 < r \le r_{0} := \min\left\{\gamma', \frac{\gamma^{*}}{2}\right\}, \quad \text{with} \quad \int_{\omega'} p_{\epsilon_{m}} d\mathbf{x} = 0$$
 (37)

and such that (for all $arphi \in \mathbf{W}^{1,r'}_0(\omega'))$

$$\begin{split} &\int_{\omega'} \left(\mu_1 | \mathbf{D}(\mathbf{u}_{\epsilon_m}) |^{\gamma-2} + \mu_2 | \mathbf{D}(\mathbf{u}_{\epsilon_m}) |^{q(\mathbf{x})-2} \right) \mathbf{D}(\mathbf{u}_{\epsilon_m}) : \mathbf{D}(\varphi) \, d\mathbf{x} = \\ &\int_{\omega'} \mathbf{F} : \mathbf{D}(\varphi) \, d\mathbf{x} + \int_{\omega'} \mathbf{u}_{\epsilon_m} \otimes \mathbf{u}_{\epsilon_m} \Phi_{\epsilon_m}(|\mathbf{u}_{\epsilon_m}|) : \mathbf{D}(\varphi) \, d\mathbf{x} + \int_{\omega'} p_{\epsilon_m} \operatorname{div} \varphi \, d\mathbf{x} \, . \end{split}$$

• Passing to the limit $m \to \infty$, we obtain (for all $\varphi \in \mathbf{W}_0^{1,r'}(\omega')$)

$$\int_{\omega'} (\mu_1 \mathbf{S}_1 + \mu_2 \mathbf{S}_2 - \mathbf{u} \otimes \mathbf{u} - \mathbf{F}) : \mathbf{D}(\varphi) \, d\mathbf{x} = \int_{\omega'} p_0 \operatorname{div} \varphi \, d\mathbf{x} \,. \tag{38}$$

³de Rham (1931): $\mathbf{g} = \nabla p$ for some p iff $\int_{\Omega_{-}} \mathbf{g} \cdot \mathbf{v} \, d\mathbf{x} dt = 0$ for all \mathbf{v} : $\operatorname{div} \mathbf{v} = 0$ and $\mathbf{v} = 0$. The solution of the second seco

• Let ω be a fixed but arbitrary domain such that

$$\omega \subset \subset \omega' \subset \subset \Omega \quad \text{and} \quad \partial \omega \text{ is } C^2. \tag{39}$$

By Simader and Sohr (1996) and Wolf (2007), there exist unique functions

$$p_{\epsilon_{\boldsymbol{m}}}^{1} \in \mathcal{A}^{\gamma'}(\omega), \quad p_{\epsilon_{\boldsymbol{m}}}^{2} \in \mathcal{A}^{\frac{\gamma^{*}}{2}}(\omega),$$
 (40)

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where $A^{s}(\omega) := \{a \in L^{s}(\omega) : a = \triangle u, \quad u \in W_{0}^{2,s}(\omega)\}$ such that

$$\|\boldsymbol{\rho}_{\boldsymbol{\epsilon}_{\boldsymbol{m}}}^{1}\|_{\mathrm{L}^{\gamma'}(\omega)} \leq C_{1} \||\mathbf{D}(\mathbf{u}_{\boldsymbol{\epsilon}_{\boldsymbol{m}}})|^{\gamma-2}\mathbf{D}(\mathbf{u}_{\boldsymbol{\epsilon}_{\boldsymbol{m}}}) - \mathbf{S}_{1}\|_{\mathbf{L}^{\gamma'}(\omega)} + C_{2} \||\mathbf{D}(\mathbf{u}_{\boldsymbol{\epsilon}_{\boldsymbol{m}}})|^{q(\mathbf{x})-2}\mathbf{D}(\mathbf{u}_{\boldsymbol{\epsilon}_{\boldsymbol{m}}}) - \mathbf{S}_{2}\|_{\mathbf{L}^{\gamma'}(\omega)},$$

$$(41)$$

$$\|\boldsymbol{p}_{\epsilon_{\boldsymbol{m}}}^{2}\|_{\mathrm{L}^{\frac{\gamma^{*}}{2}}(\omega)} \leq C_{3} \|\boldsymbol{u}_{\epsilon_{\boldsymbol{m}}} \otimes \boldsymbol{u}_{\epsilon_{\boldsymbol{m}}} \Phi_{\epsilon_{\boldsymbol{m}}}(|\boldsymbol{u}_{\epsilon_{\boldsymbol{m}}}|) - \boldsymbol{u} \otimes \boldsymbol{u}\|_{\mathrm{L}^{\frac{\gamma^{*}}{2}}(\omega)}.$$
 (42)

and

$$p_{\epsilon_{\boldsymbol{m}}} - p_0 = p^1_{\epsilon_{\boldsymbol{m}}} + p^2_{\epsilon_{\boldsymbol{m}}}$$

Then

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• Using the Hardy-Littlewood maximal operator, we can prove that for all $m \in \mathbb{N}$ and all $j \in \mathbb{N}_0$ there exists $\lambda_{m,j} \in \left[2^{2^j}, 2^{2^{j+1}}\right)$ such that

$$\mathcal{L}_{N}\left(F_{m,j}\right) \leq 2^{-j}\lambda_{m,j}^{-\kappa} \|\mathbf{w}_{\epsilon_{m}}\|_{\mathsf{L}^{\kappa}(\mathbb{R}^{N})}, \quad \text{for any } \kappa : 1 \leq \kappa < \gamma^{*}, \qquad (44)$$

$$\mathcal{L}_{N}\left(G_{m,j}\right) \leq 2^{-j} \lambda_{m,j}^{-\gamma} \|\nabla \mathbf{w}_{\epsilon_{m}}\|_{\mathbf{L}^{\gamma}(\mathbb{R}^{N})},\tag{45}$$

where

$$\begin{split} \mathcal{F}_{m,j} &:= \left\{ \mathbf{x} \in \mathbb{R}^N : \mathcal{M}(|\mathbf{w}_{\epsilon_m}|)(\mathbf{x}) > 2\lambda_{m,j} \right\}, \\ \mathcal{G}_{m,j} &:= \left\{ \mathbf{x} \in \mathbb{R}^N : \mathcal{M}(|\nabla \mathbf{w}_{\epsilon_m}|)(\mathbf{x}) > 2\lambda_{m,j} \right\}. \end{split}$$

$$\mathcal{M}(|\mathbf{w}_{\epsilon_{m}}|)(\mathbf{x}) := \sup_{0 < R < \infty} \frac{1}{\mathcal{L}_{N}(B_{R}(\mathbf{x}))} \int_{B_{R}(\mathbf{x})} |\mathbf{w}_{\epsilon_{m}}(\mathbf{y})| d\mathbf{y},$$
$$\mathcal{M}(|\nabla \mathbf{w}_{\epsilon_{m}}|)(\mathbf{x}) := \sup_{0 < R < \infty} \frac{1}{\mathcal{L}_{N}(B_{R}(\mathbf{x}))} \int_{B_{R}(\mathbf{x})} |\nabla \mathbf{w}_{\epsilon_{m}}(\mathbf{y})| d\mathbf{y}.s$$

• Setting $R_{m,j} := F_{m,j} \cup G_{m,j}$, we can prove that

$$\limsup_{m \to \infty} \mathcal{L}_N(R_{m,j}) \le \limsup_{m \to \infty} C 2^{-j} \lambda_{m,j}^{-\gamma}.$$
(46)

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Proof: 7th step - Lipschitz truncation

• By Acerbi and Fusco (1988), there exists

$$\mathbf{z}_{m,j} \in \mathbf{W}^{1,\infty}(\mathbb{R}^N), \qquad \mathbf{z}_{m,j} = \begin{cases} \mathbf{w}_{\epsilon_m} & \text{in } \omega \setminus A_{m,j} \\ \mathbf{0} & \mathbb{R}^N \setminus \omega \end{cases},$$
(47)

$$A_{m,j} := \{ \mathbf{x} \in \omega : \mathbf{z}_{m,j}(\mathbf{x}) \neq \mathbf{w}_{\epsilon_m}(\mathbf{x}) \},$$
(48)

such that

$$\|\mathbf{z}_{m,j}\|_{\mathbf{L}^{\infty}(\omega)} \le 2\lambda_{m,j},\tag{49}$$

$$\|\nabla \mathbf{z}_{m,j}\|_{\mathbf{L}^{\infty}(\omega)} \leq C\lambda_{m,j}, \quad C = C(N,\omega).$$
(50)

By Landes (1996),

$$A_{m,j} \subset \omega \cap R_{m,j}.$$
 (51)

As a consequence,

$$\limsup_{m \to \infty} \mathcal{L}_{N} \left(A_{m,j} \right) \le \limsup_{m \to \infty} C 2^{-j} \lambda_{m,j}^{-\gamma}.$$
(52)

ullet We can prove, successively, that for any $j\in\mathbb{N}_0$

$$\mathbf{z}_{m,j} \to \mathbf{0}$$
 weakly in $\mathbf{W}_0^{1,\gamma}(\omega)$, as $m \to \infty$, (53)

$$\begin{aligned} \mathbf{z}_{m,j} &\to \mathbf{0} \text{ strongly in } \mathbf{L}^{\kappa}(\omega), \text{ as } m \to \infty, \text{ for any } \kappa : 1 \leq \kappa < \gamma^{*}, \\ \mathbf{z}_{m,j} &\to \mathbf{0} \text{ strongly in } \mathbf{L}^{s}(\omega), \text{ as } m \to \infty, \text{ for any } s : 1 \leq s < \infty, \end{aligned}$$
(54)
$$\begin{aligned} \mathbf{z}_{m,j} &\to \mathbf{0} \text{ weakly in } \mathbf{W}_{\mathbf{0}}^{1,s}(\omega), \text{ as } m \to \infty, \text{ for any } s : 1 \leq s < \infty. \end{aligned}$$
(55)

• We prove that

$$\mu_{1} \int_{\omega} \left(|\mathbf{D}(\mathbf{u}_{\epsilon_{m}})|^{\gamma-2} \mathbf{D}(\mathbf{u}_{\epsilon_{m}}) - |\mathbf{D}(\mathbf{u})|^{\gamma-2} \mathbf{D}(\mathbf{u}) \right) : \mathbf{D}(\mathbf{z}_{m,j}) \, d\mathbf{x} + \mu_{2} \int_{\omega} \left(|\mathbf{D}(\mathbf{u}_{\epsilon_{m}})|^{q(\mathbf{x})-2} \mathbf{D}(\mathbf{u}_{\epsilon_{m}}) - |\mathbf{D}(\mathbf{u})|^{q(\mathbf{x})-2} \mathbf{D}(\mathbf{u}) \right) : \mathbf{D}(\mathbf{z}_{m,j}) \, d\mathbf{x} = \mu_{1} \int_{\omega} \left(\mathbf{S}_{1} - |\mathbf{D}(\mathbf{u})|^{\gamma-2} \mathbf{D}(\mathbf{u}) \right) : \mathbf{D}(\mathbf{z}_{m,j}) \, d\mathbf{x} + \mu_{2} \int_{\omega} \left(\mathbf{S}_{2} - |\mathbf{D}(\mathbf{u})|^{q(\mathbf{x})-2} \mathbf{D}(\mathbf{u}) \right) : \mathbf{D}(\mathbf{z}_{m,j}) \, d\mathbf{x} + \int_{\omega} \rho_{\epsilon_{m}}^{1} \operatorname{div} \mathbf{z}_{m,j} \, d\mathbf{x} + \int_{\omega} \rho_{\epsilon_{m}}^{1} \operatorname{div} \mathbf{z}_{m,j} \, d\mathbf{x} + \int_{\omega} \left(\mathbf{u}_{\epsilon_{m}} \otimes \mathbf{u}_{\epsilon_{m}} \Phi_{\epsilon_{m}}(|\mathbf{u}_{\epsilon_{m}}|) - \mathbf{u} \otimes \mathbf{u} + \rho_{\epsilon_{m}}^{2} \mathbf{I} \right) : \mathbf{D}(\mathbf{z}_{m,j}) \, d\mathbf{x} \\ := J_{m,j}^{1} + J_{m,j}^{2} + J_{m,j}^{3} + J_{m,j}^{4} \leq C2^{-\frac{1}{\gamma}} \text{ (as } m \to \infty).$$

• Using an argument of Dal Maso and Murat (1998), we start by proving, for any $\theta \in (0, 1)$, that

$$\limsup_{m \to \infty} \int_{\omega} g_{\epsilon_{m}}^{\theta} \, d\mathbf{x} \le C_{1} 2^{-\theta \frac{j}{\gamma}} + C_{2} 2^{-\theta \frac{j}{\gamma} - (1-\theta)j} \to 0 \, \left(\text{as } j \to \infty \right), \quad (57)$$

$$\begin{split} g_{\epsilon_{\boldsymbol{m}}} &:= \mu_1 \left| |\mathsf{D}(\mathsf{u}_{\epsilon_{\boldsymbol{m}}})|^{\gamma-2} \mathsf{D}(\mathsf{u}_{\epsilon_{\boldsymbol{m}}}) - |\mathsf{D}(\mathsf{u})|^{\gamma-2} \mathsf{D}(\mathsf{u}) \right| + \\ & \mu_2 \left| |\mathsf{D}(\mathsf{u}_{\epsilon_{\boldsymbol{m}}})|^{q(\mathsf{x})-2} \mathsf{D}(\mathsf{u}_{\epsilon_{\boldsymbol{m}}}) - |\mathsf{D}(\mathsf{u})|^{q(\mathsf{x})-2} \mathsf{D}(\mathsf{u}) \right|, \end{split}$$

• Then for any $heta \in (0,1)$

$$\limsup_{m\to\infty}\int_{\omega}g^{\theta}_{\epsilon_{m}}\,d\mathbf{x}=0.$$

Passing to a subsequence,

$$g_{\epsilon_{m}} \to 0$$
 a.e. in ω , as $m \to \infty$. (58)

Using the monotonicity and continuity on D(u),

$$D(\mathbf{u}_{\epsilon_m}) \to D(\mathbf{u})$$
 a.e. in ω , as $m \to \infty$. (59)

• Vitali's theorem allow us to conclude that $S_1 = |D(u)|^{\gamma-2}D(u)$ and $S_2 = |D(u)|^{q(x)-2}D(u)$.

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