

Weierstrass Institute for Applied Analysis and Stochastics



Compressible Phase Change Flows and the Existence of Transition Profiles

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Content

1 General Model

2 Compressible / Incompressible Model



1 General Model

- Mass and Momentum Conservation
- Evolution of the Phase Parameter
- Thermodynamical Correctness, Entropy Principle

2 Compressible / Incompressible Model



Mass and Momentum Conservation - Equations

Two mass densities ϱ_{δ}^1 , ϱ_{δ}^2 , $\partial_t \varrho_{\delta}^1 + \operatorname{div}(\varrho_{\delta}^1 v) = + \boldsymbol{\tau}_{\delta}$ $\partial_t \varrho_{\delta}^2 + \operatorname{div}(\varrho_{\delta}^2 v) = - \boldsymbol{\tau}_{\delta}$ $\partial_t (\varrho v) + \operatorname{div}(\varrho v \otimes v + T_{\delta}) = 0$, where the total mass $\varrho := \varrho_{\delta}^1 + \varrho_{\delta}^2$

Reaction rate
$$\boldsymbol{\tau}_{\delta}$$
: $\varrho_{\delta}^{1} \xrightarrow{} \boldsymbol{\varphi}_{\delta}^{2} \qquad \varrho_{\delta}^{1} \xleftarrow{} \boldsymbol{\varphi}_{\delta}^{2}$

Tension tensor T_{δ} consists of pressure tensor P_{δ} and stress tensor S $T_{\delta} = P_{\delta} - S$, P_{δ} from the entropy principle, $S \equiv S(\varrho, \varphi) = \nu_1(\varrho, \varphi) \text{div } v \,\mathbb{I} + \nu_2(\varrho, \varphi) \left(\frac{1}{2} (\nabla v + (\nabla v)^T) - \frac{1}{n} \text{div } v \,\mathbb{I}\right)$.

$$\begin{split} \varphi &:= \varrho_{\delta}^2 / \varrho \text{ phase parameter - represents mass fraction} \\ &- \boldsymbol{\tau}_{\delta} = \partial_t \varrho_{\delta}^2 + \operatorname{div}\left(\varrho_{\delta}^2 v\right) = \partial_t (\varphi \varrho) + \operatorname{div}\left(\varphi \varrho \, v\right) = \varrho \big(\partial_t \varphi + v \cdot \nabla \varphi \big) \end{split}$$

$$\Longrightarrow \quad \partial_t \varrho + \operatorname{div} (\varrho v) = 0 \\ \varrho (\partial_t \varphi + v \cdot \nabla \varphi) = -\boldsymbol{\tau}_{\delta} \\ \partial_t (\varrho v) + \operatorname{div} (\varrho v \otimes v + T_{\delta}) = 0$$



Aim

Derive a Diffuse Interface Model which approximates a Sharp Interface Model consisting of Compressible / Incompressible Flow

Free Energy Density $\varepsilon > 0, \, \delta > 0,$ later ε as function of δ

$$f_{\delta}(\varrho,\varphi,\nabla\varphi) := \frac{1}{\varepsilon} W^{\varepsilon}(\varrho,\varphi) + \frac{1}{\delta} W^{\delta}(\varrho,\varphi) + \delta h(\varrho) \frac{\left|\nabla\varphi\right|^{2}}{2} + U(\varrho,\varphi) \,,$$

where W^{δ} double-well potential, local minima $m_1 = 0$ and $m_2 = 1$ and $h(\rho) > 0$ is an arbitrary function,

 $W^{\varepsilon} := (\rho - \rho^{\star})^2 \varphi^2$ $\rho^{\star} = \text{constant} > 0$ (Incompressible density)

U Free energy of the bulk phases

$$\begin{split} \varphi &:= \varrho_{\delta}^2 / \varrho \text{ mass fraction}, \quad \boldsymbol{\tau}_{\delta} &:= \eta_{\delta}(\varrho, \varphi) \mu, \quad \eta_{\delta}(\varrho, \varphi) > 0, \quad \mu \text{ chemical potential} \\ \implies \qquad \varrho \big(\partial_t \varphi + v \cdot \nabla \varphi \big) = -\eta_{\delta}(\varrho, \varphi) \mu \end{split}$$
For example
$$\mu := \frac{\delta f_{\delta}}{\delta \varphi} \quad \text{or} \quad \mu := -\Delta \frac{\delta f_{\delta}}{\delta \varphi}$$







Thermodynamical Correctness, Entropy Principle

[Alt 2009], Objectivity

Isothermal case: entropy principle is equivalent to the free energy inequality;

 $\begin{array}{ll} \text{Total free energy density:} \quad f_{\text{tot}} = f_{\delta} + \frac{1}{2} \varrho |v|^2 \,, \qquad \qquad f_{\delta} = f_{\delta}(\varrho, \varphi, \nabla \varphi) \\ \text{Free energy flux:} \qquad \psi_{\text{tot}} = f_{\text{tot}} v + T_{\delta}^{\text{T}} v + \psi \,, \qquad \text{where} \quad \psi = -(\partial_t \varphi + v \cdot \nabla \varphi) f_{\delta | \nabla \varphi} \,, \end{array}$

the solution (ϱ, v, φ) of the system satisfy the inequality

$$\begin{aligned} \partial_t f_{\text{tot}} + \operatorname{div}(f_{\text{tot}}v + T_{\delta}^{\Gamma}v + \psi) &= \partial_t f_{\delta} + \operatorname{div}(f_{\delta}v + \psi) + Dv \cdot T_{\delta} \\ &= -\frac{1}{\varrho} \eta_{\delta}(\varrho, \varphi) \Big(\frac{\delta f_{\delta}}{\delta \varphi}\Big)^2 - Dv \cdot S \quad \leq \quad 0 \,. \end{aligned}$$

as usual,
$$\nu_1, \nu_2 > 0$$
, so that $Dv \cdot S \ge 0$; $\eta_{\delta} > 0$;
and where Pressure tensor P_{δ} :

$$\begin{split} P_{\delta} &\equiv P_{\delta}(\varrho, \varphi, \nabla \varphi) = (-f_{\delta} + \varrho f_{\delta|\varrho}) \,\mathbb{I} + \nabla \varphi \otimes f_{\delta|\nabla\varphi} \\ &= \Big(\frac{1}{\varepsilon} p_{W^{\varepsilon}}(\varrho, \varphi) + \frac{1}{\delta} p_{W^{\delta}}(\varrho, \varphi) + p_{U}(\varrho, \varphi) + \delta p_{h}(\varrho) \frac{\left|\nabla\varphi\right|^{2}}{2}\Big) \,\mathbb{I} + \,\delta h(\varrho) \,\nabla\varphi \otimes \nabla\varphi \\ \text{with} \qquad p_{U}(\varrho, \varphi) &:= -U(\varrho, \varphi) + \varrho U_{|\varrho}(\varrho, \varphi), \quad p_{W^{\delta}}, \ p_{h} \text{ dito} \end{split}$$

the last two summands (terms with $\nabla \varphi$) stand for the 'surface tension' between the different phases;

Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 6 (18)



1 General Model

2 Compressible / Incompressible Model

- Diffusive Interface Model
- Sharp Interface Model Bulk Region
- Sharp Interface Model Interface
- Interfacial Profile



Diffusive Interface Model

 $\begin{array}{ll} \text{Assume:} & W^{\delta}(\varrho,\varphi) := \varrho W(\varphi), \quad W(m_1) \neq W(m_2) \\ & \eta_{\delta} = 1/\delta, \quad W^{\varepsilon}(\varrho,\varphi) := (\varrho - \varrho^{\star})^2 \varphi^2 \end{array}$

Connection of both parameters

$$\delta \equiv \delta(\varepsilon) = \varepsilon^2$$

The incompressible limes slower than the sharp interface limes

$$\partial_t \varrho + \operatorname{div}(\varrho v) = 0$$
, (1)

$$\partial_t(\varrho v) + \operatorname{div}(\varrho v \otimes v) + \nabla \left(\frac{1}{\varepsilon} p_{W^{\varepsilon}}(\varrho, \varphi) + \frac{1}{\varepsilon^2} p_{\varrho W}(\varrho, \varphi) + p_U(\varrho, \varphi)\right)$$
(2)

$$+ \varepsilon^2 \operatorname{div} \left(p_h(\varrho) \frac{\left| \nabla \varphi \right|^2}{2} \mathbb{I} + h(\varrho) \nabla \varphi \otimes \nabla \varphi \right) = \operatorname{div} (S) ,$$

$$\delta \varrho(\partial_t \varphi + v \cdot \nabla \varphi) = -\frac{1}{\varepsilon} W^{\varepsilon}_{|\varphi}(\varrho, \varphi) - \frac{1}{\varepsilon^2} \varrho W'(\varphi) - U_{|\varphi}(\varrho, \varphi) + \varepsilon^2 \operatorname{div}(h(\varrho) \nabla \varphi),$$
(3)

where

$$p_{W^{\varepsilon}}(\varrho,\varphi) = (\varrho - \varrho^{\star})(\varrho + \varrho^{\star})\varphi^{2}$$

Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 8 (18)



Asymptotic Expansion

Formal Matched Asymptotic Expansion in ε

 $\varepsilon \searrow 0$

'Low Mach Number Limit' as $\varepsilon\searrow 0$, then $\delta=\varepsilon^2\searrow 0$,

$$\begin{aligned} \text{Outer Expansion} \quad \varrho(t,x) &= \varrho_0(t,x) + \varepsilon \varrho_1(t,x) + \delta \varrho_2(t,x) + \mathcal{O}(\varepsilon^2) \\ \quad v(t,x) &= v_0(t,x) + \varepsilon v_1(t,x) + \delta v_2(t,x) + \mathcal{O}(\varepsilon^2) \\ \quad \varphi(t,x) &= \varphi_0(t,x) + \varepsilon \varphi_1(t,x) + \delta \varphi_2(t,x) + \mathcal{O}(\varepsilon^2) \end{aligned}$$

Interfacial Expansion $arrho(t,y+\delta rec{n}_{\Gamma}(t,y))=R(t,y,r)$

$$\begin{aligned} \varrho(t,x) &= R(t,y,r) = R_0(t,y,r) + \varepsilon R_1(t,y,r) + \delta R_2(t,y,r) + \mathcal{O}(\varepsilon^2) \\ v(t,x) &= V(t,y,r) = V_0(t,y,r) + \varepsilon V_1(t,y,r) + \delta V_2(t,y,r) + \mathcal{O}(\varepsilon^2) \\ \varphi(t,x) &= \Phi(t,y,r) = \Phi_0(t,y,r) + \varepsilon \Phi_1(t,y,r) + \delta \Phi_2(t,y,r) + \mathcal{O}(\varepsilon^2) \end{aligned}$$



 $\varrho_1, v_1,$ and φ_1 are perturbations in the bulk regions

 $R_1,V_1,$ and Φ_1

are perturbations in the interfacial regions



Sharp Interface Model - Bulk Region

For t > 0, there is an unknown free interface Γ_t , $\Omega = \Omega_t^1 \cup \Gamma_t \cup \Omega_t^2$,

Bulk Region: Compressible / Incompressible Navier-Stokes system

$$\begin{split} \partial_t \varrho^1 + \operatorname{div}(\varrho^1 v^1) &= 0 , & \text{in } \Omega^1_t \\ \partial_t (\varrho^1 v^1) + \operatorname{div}(\varrho^1 v^1 \otimes v^1 + T^1(\varrho^1, m_1)) &= 0 , \\ \\ \end{array} \\ \\ \hline \operatorname{div} v^2 &= 0 , & \text{in } \Omega^2_t \\ \varrho^* \left(\partial_t v^2 + \operatorname{div}(v^2 \otimes v^2) \right) + \operatorname{div} T^2(\varrho^*, m_2) &= 0 , \end{split}$$

$$\begin{split} & T^k = p^k \, \mathbb{I} - s^k \; \text{tension tensor}, \quad p^k \; \text{scalar pressure}, \quad s^k \; \text{stress tensor}, \\ & \text{in } \Omega_t^1: \quad \varphi = 0 \\ & p^1 \equiv p_U(\varrho^1, m_1) \; , \\ & s^1 \equiv s(\varrho^1, m_1) = \nu_1(\varrho^1, m_1) \text{div} \, v^1 \, \mathbb{I} + \nu_2(\varrho^1, m_1) \Big(\frac{1}{2} (\nabla v^1 + (\nabla v^1)^T) - \frac{1}{n} \text{div} \, v^1 \, \mathbb{I} \Big) \\ & \frac{1}{\text{in } \Omega_t^2: \quad \varphi = 1} \\ & p^2 \; \text{unknown} \; , \\ & s^2 \equiv s(\varrho^*, m_2) = \tilde{\nu}(\varrho^*, m_2) \triangle v^2 \end{split}$$

Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 10 (18)



Sharp Interface Model - Bulk Region

Energy-Inequality

$$\int_0^t \int_\Omega \frac{1}{\varepsilon} (\varrho - \varrho^\star)^2 \varphi^2 dx dt \le C_{\text{data}} \quad \Rightarrow \quad \varrho = \varrho^\star \quad \text{in } \ \Omega_t^2 \qquad \text{for } \ \varepsilon \searrow 0$$

Then in
$$\Omega_t^2$$
 $\varrho(t,x) \approx \varrho_0(t,x) + \varepsilon \varrho_1(t,x)$

Comparison order ε^0

$$\partial_t \varrho_0 + \operatorname{div}(\varrho_0 v_0) = 0 \,,$$

$$\begin{aligned} \partial_t(\varrho_0 v_0) + \operatorname{div}(\varrho_0 v_0 \otimes v_0) + \nabla \left(p_U(\varrho_0, \varphi_0) + 2\varrho_0 |\varphi_0|^2 \varrho_1 + 2(\varrho_0 - \varrho^\star)(\varrho_0 + \varrho^\star)\varphi_0 \varphi_1 \right) \\ &= \operatorname{div} \left(\nu_1(\varrho_0, \varphi_0) \operatorname{div} v_0 \,\mathbb{I} + \nu_2(\varrho_0, \varphi_0) \Big(\frac{1}{2} (\nabla v_0 + (\nabla v_0)^{\mathrm{T}}) - \frac{1}{n} \operatorname{div} v_0 \,\mathbb{I} \Big) \Big) \,. \end{aligned}$$

and
$$\varrho_0(t,x) = \varrho^\star, \varphi_0 = 1$$
 and $\varphi_1 = 0$, then

$$\Rightarrow \quad \varrho^{\star} \operatorname{div}(v_0) = 0 \,, \qquad \varrho^{\star} \left(\partial_t v_0 + \operatorname{div}(v_0 \otimes v_0) \right) + \nabla \left(2 \varrho^{\star} \varrho_1 \right) = \tilde{\nu} \triangle v_0$$
$$\Rightarrow \quad p(t, x) = 2 \varrho^{\star} \varrho_1(t, x) \,, \qquad \gamma := \frac{1}{2 \varrho^{\star}}$$

that means in $\Omega_t^2 \qquad \qquad \varrho(t,x)\approx \varrho^\star + \varepsilon \gamma p(t,x)$



Different Jump conditions on $\Gamma := \{(t, x) : x \in \Gamma_t\}$: $[v]_{\Gamma} \neq 0$ and $[\varrho]_{\Gamma} \neq 0$ Relative interface velocity in normal direction $\lambda := (v_{\Gamma} - v) \cdot \vec{n}_{\Gamma}$

 $v_{\Gamma}\cdot \vec{n}_{\Gamma}$ normal interface velocity of Γ , κ curvature

Interface Conditions

$$\begin{split} & [\varrho\lambda]_{\Gamma} = 0 , & \text{on } \Gamma , \\ & -\varrho\lambda[v]_{\Gamma} + [T^{k}\vec{n}_{\Gamma}]_{\Gamma} = \operatorname{div}_{y}^{\Gamma}(\pmb{\gamma}(\mathbb{I} - \vec{n}_{\Gamma} \otimes \vec{n}_{\Gamma})) = \pmb{\gamma}\kappa \cdot \vec{n}_{\Gamma} \, \vec{n}_{\Gamma} + \nabla^{\Gamma}\pmb{\gamma} \,, & \text{on } \Gamma \,, \\ & [v]_{\Gamma} = \pmb{\omega} \, \vec{n}_{\Gamma} \,, & \text{on } \Gamma \,, \\ & G(\varrho^{1}, \varrho^{\star}) = 0 \,, & \text{on } \Gamma \,, \end{split}$$

where $\Phi = m_1$ in Ω_t^1 and $\Phi = m_2$ in Ω_t^2 , and γ surface tension, ω capillarity force,

the two mass densities of the bulk phases are connected by G

$$\begin{split} \boldsymbol{\omega} &= \boldsymbol{\omega}[\varrho\lambda] := \int_{m_1}^{m_2} \frac{e_h(R)}{\tilde{\mu}(R,s)} \left\{ \frac{1}{2} \frac{1}{h(R)} \sqrt{2 \int_{m_1}^s h(R) R W' d\bar{s}} \right\} ds ,\\ \boldsymbol{\gamma} &= \boldsymbol{\gamma}[\varrho\lambda] := \int_{m_1}^{m_2} \left(1 - \frac{1}{2} \frac{\mu_2(R,s)}{\tilde{\mu}(R,s)} \frac{e_h(R)}{h(R)} \right) \sqrt{\int_{m_1}^s 2 h(R) R W' d\bar{s}} ds . \end{split}$$

Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 12 (18)



Mass flux $M:=\lambda^1\varrho^1=\lambda^2\varrho^2.$ The function R is the solution of the

Inner Interface Problem

$$M^{2}\partial_{s}\left(\left|h(R) g(R, .)\partial_{s}\left(\frac{1}{R}\right)\right|^{2}\right) = 2 h(R) R \partial_{s} W$$

$$\partial_{s} R(m_{1}) = 0, \qquad \partial_{s} R(m_{2}) = 0.$$

where $g = \tilde{\nu}/e_h$, $e_h(z) = [z h(z)]'$ energetic part, and $e_h \gtrless 0$.

Theorem We consider

$$W(\varphi) := W_0(\varphi) + \varepsilon W_1(\varphi)$$
.

 W_0 and W_1 double-well potentials, twice continuously differentiable functions in φ , local minima on m_1 and m_2 , and local maximum on $s_a = (m_1 + m_2)/2$. $W_0(m_1) = W_0(m_2)$ and symmetric function on $\varphi = s_a$, $W_1(m_1) \neq W_1(m_2)$, $h \equiv 1$.

Then, there is a $\varepsilon_0 \in \mathbb{R}_+$ and for each $M \in \mathbb{R} \setminus \{0\}$ has the Inner Interface Problem a solution $R \in C^1([m_1, m_2]) \cap C^2((m_1, m_2))$ as $0 < \varepsilon < \varepsilon_0$.





Let $h\equiv 1$ and $\widetilde{\mu}\equiv 1,$ then g(R,.)=1. Then

$$M^2 \partial_s \left(\left| \partial_s \left(\frac{1}{R} \right) \right|^2 \right) = 2 R \partial_s W \qquad \partial_s R(m_1) = 0 \,, \qquad \partial_s R(m_2) = 0 \,.$$

Then

$$\begin{split} \partial_s \Big(\frac{1}{R} \Big) &= \frac{1}{|M|} \sqrt{\int_{m_1}^s 2RW' d\bar{s}} \quad \text{and} \\ 0 &= \partial_s \Big(\frac{1}{R} \Big) (m_2) = \frac{1}{|M|} \sqrt{\int_{m_1}^{m_2} 2RW' d\bar{s}} \quad , \end{split}$$

that is

$$\partial_s \left(\frac{1}{R} \right) = \frac{1}{|M|} \sqrt{\int_{m_1}^s 2RW' d\bar{s}} , \qquad \int_{m_1}^{m_2} RW' d\bar{s} = 0$$



Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 14 (18)

Fixed point operator

Let $B \subset C^0([m_1,m_2])$ closed with

$$B := \Big\{ u \in C^0([m_1, m_2]) : 0 < c_k \le u \le C_g, \int_{m_1}^{m_2} \frac{W'}{u} ds = 0, u \text{ monotone increasing} \Big\}.$$

We introduce the operator

$$F: B \to C^0([m_1, m_2]), \quad u_1 \in B \mapsto u_3 = F(u_1) \in C^0([m_1, m_2]),$$

where
$$\begin{array}{|c|c|c|c|c|c|} u_2(s) = \frac{1}{|M|} \int_{m_1}^s \sqrt{\int_{m_1}^{\bar{s}} \frac{2W'}{u_1} d\bar{s}} \ d\bar{s} \\ u_3(s) = u_2(s) + C(u_2) \ , \qquad \mbox{with} \quad \int_{m_1}^{m_2} \frac{W'}{u_2 + C(u_2)} ds = 0 \ . \end{array}$$

- **1.** Existence of $C(u_2)$ intermediate value theorem
- **2.** F is a non-expanding map by choosing c_k and C_g
- 3. F is a contraction for a weighted norm, Banach fixed point theorem



$$f_{\delta}(\varrho,\varphi,\nabla\varphi) := \frac{1}{\varepsilon} W^{\varepsilon}(\varrho,\varphi) + \frac{1}{\delta} W^{\delta}(\varrho,\varphi) + \delta h(\varrho) \frac{\left|\nabla\varphi\right|^{2}}{2} + U(\varrho,\varphi) + \delta h(\varphi) + \delta h(\varrho) \frac{\left|\nabla\varphi\right|^{2}}{2} + U(\varrho,\varphi) + \delta h(\varphi) + \delta h(\varrho) + \delta h(\varrho) + \delta h(\varphi) + \delta h$$

Generalization to $h\not\equiv 1$

1. The function h fulfills a special growth condition

$$h(z_2)z_2^{\frac{2-n}{n}} \le h(z_1)z_1^{\frac{2-n}{n}} \quad \ \ {\rm for \ all} \quad z_1 \le z_2 \ , \ \ z_1, z_2 \in \mathbb{R}_+ \ ,$$

Then, $e_h(z)
eq 0$ for all $z \in \mathbb{R}$ and surface tension $oldsymbol{\gamma} > 0$

2. h > 0 is an arbitrary continuously differentiable function and bounded from below, that is $h(z) \ge h_s > 0$ for all $z \in \mathbb{R}$

Theorem

Let $W(m_1) \neq W(m_2)$. Then, it exists G with $\mathbf{G}(\boldsymbol{\varrho}^1, \boldsymbol{\varrho}^*) = \mathbf{0}$. Definition: The function G is defined by solution R = R[M] with $R[M(t,y)](m_1) = \boldsymbol{\varrho}^1(t,y)$, $R[M(t,y)](m_2) = \boldsymbol{\varrho}^*(t,y)$.



Perturbations

Incompressible limes is a singular limit,

On Ω^1 : compressible

$$\begin{aligned} \partial_t \varrho'_1 + \operatorname{div}(\varrho'_1 v_1 + \varrho_1 v'_1) &= 0, \\ \partial_t (\varrho'_1 v_1 + \varrho_1 v'_1) + \operatorname{div}(\varrho'_1 v_1 \otimes v_1 + \varrho_1 v'_1 \otimes v_1 + \varrho_1 v_1 \otimes v'_1) + \nabla \big(p_{U_1|\varrho}(\varrho_1, m_1)\varrho'_1 \big) \\ &= \operatorname{div}(\operatorname{Lin} S) \end{aligned}$$

On Ω^2 : incompressible

 $\begin{aligned} \partial_t \varrho_2' + \operatorname{div}(\varrho_2' v_2 + \varrho^* v_2') &= 0 , \\ \partial_t (\varrho_2' v_2 + \varrho^* v_2') + \operatorname{div}(\varrho_2' v_2 \otimes v_2) + \varrho^* \operatorname{div}(v_2' \otimes v_2 + v_2 \otimes v_2') + \nabla p' &= \operatorname{div}(\operatorname{Lin} S) \end{aligned}$

- In compressible flows the sound velocity is finite, there are wave solutions for small perturbations
- In incompressible flows the sound velocity is infinite, but $\varepsilon > 0$ consider $\varrho = \varrho^{\star} + \varepsilon \gamma p$



Thank you for your attention !



Compressible Phase Change Flows · WIAS, September 18, 2012 · Page 18 (18)