Phase change models
E. Rocca

The model
Free-energy
functional
Pseudo-Potential of dissipation
Macroscopic motion Microscopic motion Internal energy balance

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## Phase transitions and phase-field models

Assume that the two phases can coexist at every point: a parameter $\chi$ characterizes the different phases, e.g. the concentration or the local proportion of one of the two phases in a point.

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- $\chi=0$ in the solid (non viscous) phase and
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- The internal energy balance ruling the evolution of the absolute temperature $\vartheta$ of the system
with a proper choice of the internal energy functional (depending on the state variables) and of the pseudo-potential of dissipation (depending on the dissipative variables).

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## The free-energy functional

We take into account of elasticity effects by choosing

$$
\begin{aligned}
\frac{\Psi(\vartheta, \varepsilon(\mathbf{u}), \chi, \nabla \chi)}{} & =c_{\nu} \vartheta(1-\log \vartheta)-\frac{\lambda}{\vartheta_{c}}\left(\vartheta-\vartheta_{c}\right) \chi \\
& +\frac{(1-\chi) \varepsilon(\mathbf{u}) \mathcal{R}_{e} \varepsilon(\mathbf{u})}{2}+W(\chi)+\frac{\nu}{2}|\nabla \chi|^{2}
\end{aligned}
$$

- $\varepsilon(\mathbf{u})$ the linearized symmetric strain tensor, namely $\varepsilon_{i j}(\mathbf{u}):=\left(u_{i, j}+u_{j, i}\right) / 2, i, j=1,2,3$
- $(1-\chi)$ the local proportion of the non viscous phase, e.g. the solid phase in solid-liquid phase transitions
- $\mathcal{R}_{e}$ a symmetric positive definite elasticity tensor (set $\mathcal{R}_{e} \equiv \mathbb{I}$ )
- $c_{V}, \vartheta_{c}, \lambda$ and $\nu(>0)$ the specific heat, the equilibrium temperature, the latent heat of the system, and the interfacial energy coefficient (set $c_{V}=\lambda / \vartheta_{c}=1$ )
- $W(\chi)+(\nu / 2)|\nabla \chi|^{2}$ a mixture or interaction free-energy


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## Free-energy <br> functional

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## The Pseudo-Potential of dissipation

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## The equation of macroscopic motion

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## The equation of macroscopic motion

The equation of macroscopic motion is the following stress-strain relation, taking into account of accelerations:

$$
\mathbf{u}_{t t}-\operatorname{div} \sigma=\mathbf{0} \quad \text { in } \Omega \times(0, T)
$$

where $\sigma$ represents the stress tensor. Using the constitutive law

$$
\sigma=\sigma^{n d}+\sigma^{d}=\frac{\partial \Psi}{\partial \varepsilon(\mathbf{u})}+\frac{\partial \Phi}{\partial \varepsilon\left(\mathbf{u}_{t}\right)}
$$

the tensor $\sigma$ can be written as

$$
\sigma=(1-\chi) \varepsilon(\mathbf{u})+\chi \varepsilon\left(\mathbf{u}_{t}\right) \quad \text { in } \Omega \times(0, T)
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$$

We treat here a pure displacement boundary value problem for $\mathbf{u}$

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\mathbf{u}=\mathbf{0} \quad \text { on } \partial \Omega \times(0, T)
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However, our analysis carries over to other kinds of boundary conditions on $\mathbf{u}$ like a pure traction problem or a displacement-traction problem.

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## The equation of microscopic motion

If the volume amount of mechanical energy provided by the external actions is zero, the generalized principle of virtual power by [Frémond, '02] gives

$$
B-\operatorname{div} \mathbf{H}=0 \quad \text { in } \Omega \times(0, T), \quad \mathbf{H} \cdot \mathbf{n}=0 \quad \text { on } \partial \Omega \times(0, T)
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where $B$ and H represent the internal microscopic forces responsible for the mechanically induced heat sources.

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where $B$ and H represent the internal microscopic forces responsible for the mechanically induced heat sources. From the constitutive relations

$$
\begin{aligned}
& B=\frac{\partial \Psi}{\partial \chi}+\frac{\partial \Phi}{\partial \chi_{t}}=-\vartheta+\vartheta_{c}-\frac{|\varepsilon(\mathbf{u})|^{2}}{2}+W^{\prime}(\chi)+\mu \chi_{t} \\
& \mathbf{H}=\frac{\partial \Psi}{\partial \nabla \chi}=\nu \nabla \chi
\end{aligned}
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\end{aligned}
$$

we derive the phase equation

$$
\mu \chi_{t}-\nu \Delta \chi+W^{\prime}(\chi)=\vartheta-\vartheta_{c}+\frac{|\varepsilon(\mathbf{u})|^{2}}{2} \quad \text { in } \Omega \times(0, T)
$$

coupled with the B.C. $\partial_{\mathbf{n}} \chi=0$ on $\partial \Omega \times(0, T)$.

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## The internal energy balance

The first principle of thermodynamics can be expressed as

$$
e_{t}+\operatorname{div} \mathbf{q}=\sigma: \varepsilon\left(\mathbf{u}_{t}\right)+B \chi_{t}+\mathbf{H} \cdot \nabla \chi_{t}
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where

- $e$ is the (density of) internal energy:

$$
e=\Psi-\vartheta \frac{\partial \Psi}{\partial \vartheta}=\vartheta+\lambda \chi+\frac{(1-\chi)|\varepsilon(\mathbf{u})|^{2}}{2}+W(\chi)+\frac{\nu}{2}|\nabla \chi|^{2} ;
$$

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- the heat flux is $\mathbf{q}=-\vartheta \frac{\partial \Phi}{\partial \nabla \vartheta}=-h(\vartheta) \nabla \vartheta$;

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- the heat flux is $\mathbf{q}=-\vartheta \frac{\partial \Phi}{\partial \nabla \vartheta}=-h(\vartheta) \nabla \vartheta$;
- on the right-hand side: the mechanically induced heat sources, related to macroscopic and microscopic stresses:

$$
\begin{gathered}
\sigma: \varepsilon\left(\mathbf{u}_{t}\right)+B \chi_{t}+\mathbf{H} \cdot \nabla \chi_{t}=\chi\left|\varepsilon\left(\mathbf{u}_{t}\right)\right|^{2}+(1-\chi) \varepsilon(\mathbf{u}) \varepsilon\left(\mathbf{u}_{t}\right)-\vartheta \chi_{t} \\
\quad+\mu\left|\chi_{t}\right|^{2}+\lambda \chi_{t}-\frac{|\varepsilon(\mathbf{u})|^{2} \chi_{t}}{2}+W^{\prime}(\chi) \chi_{t}+\nu \nabla \chi \nabla \chi_{t}
\end{gathered}
$$

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\end{gathered}
$$

Due to the cancellations of the blue terms, we get

$$
\vartheta_{t}+\vartheta \chi_{t}-\operatorname{div}(h(\vartheta) \nabla \vartheta)=\chi\left|\varepsilon\left(\mathbf{u}_{t}\right)\right|^{2}+\mu\left|\chi_{t}\right|^{2}
$$

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## The thermodynamical consistency

Our model complies with the Second Principle of Thermodynamics:

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## The thermodynamical consistency

Our model complies with the Second Principle of Thermodynamics: in fact, the following form of the Clausius-Duhem inequality

$$
s_{t}+\operatorname{div}\left(\frac{\mathbf{q}}{\vartheta}\right) \geq 0
$$

holds true.

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holds true.

- It is sufficient to note that the internal energy balance can be expressed in terms of the entropy $s=-\frac{\partial \Psi}{\partial \vartheta}$ in this way:

$$
\vartheta\left(s_{t}+\operatorname{div}\left(\frac{\mathbf{q}}{\vartheta}\right)\right)=\sigma^{\mathrm{d}}: \varepsilon\left(\mathbf{u}_{t}\right)+B^{\mathrm{d}} \chi_{t}-\frac{\mathbf{q}}{\vartheta} \cdot \nabla \vartheta
$$

$B^{\text {d }}$ being the dissipative part of $B$

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$B^{\mathrm{d}}$ being the dissipative part of $B$

- The right-hand side turns out to be non negative because $\left(\sigma^{\mathrm{d}}, B^{\mathrm{d}},-\mathbf{q} / \vartheta\right) \in \partial \Phi\left(\mathbf{u}_{t}, \chi_{t}, \nabla \vartheta\right)$, and $\Phi$ is convex in all of its variables


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- Therefore, the Clausius-Duhem inequality ensues from the positivity of $\vartheta$


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## The resulting PDE system

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## The literature on the full phase change system

$\checkmark$ The corresponding 3D problem was solved (locally in time) in [E.R., R. Rossi, J. Differential Equations (2008)] under the small perturbation assumptions, i.e. with

$$
\vartheta_{t}+\vartheta \chi_{t}-\Delta \vartheta=0
$$

in place of the internal energy balance

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## The literature on the full phase change system

$\checkmark$ The corresponding 3D problem was solved (locally in time) in [E.R., R. Rossi, J. Differential Equations (2008)] under the small perturbation assumptions, i.e. with

$$
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$\checkmark$ A more complex model is considered in [P. Krejčí, J. Sprekels, U. Stefanelli, Adv. Math. Sci. Appl. (2003)], in the frame of nonlinear thermoviscoplasticity: in the 1D (in space) case, they get global well-posedness of a PDE system, incorporating both hysteresis effects and modelling phase change. It does not display a degenerating character

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$\checkmark$ Degenerating stress-strain relations appear in models for damaging phenomena coupling $\chi$ and $\mathbf{u}$ equations (cf., e.g., [Bonetti, Schimperna, Segatti (2004-2005)]). The phase variable $\chi$ is related to the local proportion of damaged material ( $\chi=0$ when the body is completely damaged). Local (in time) well-posedness is proved

## The literature for the $[\vartheta+\chi]$-equations

$\checkmark$ So far Frémond's models of phase change do not take into account the different properties of the viscous and elastic parts of the system (cf., e.g., Colli, Bonfanti, Laurençot, Luterotti, Schimperna, Stefanelli (2000-2006)): the u-equation is usually neglected

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$\checkmark$ Due to the presence of the term $\chi_{t} \vartheta$ in the internal energy balance, no global-in-time well-posedness result has yet been obtained for Frémond's phase-field model in the 3D case, even neglecting the $\mathbf{u}$-equation and the higher order dissipative contributions on the r.h.s. in the internal energy balance

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$\checkmark$ A 1D global result is proved in [Luterotti, Stefanelli, ZAA (2002)]

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## Our aim

## Problem 1 (Joint work with Riccarda Rossi)

1) To prove the well-posedness on $[0, T]$ for the full PDE system in the 1D (in space) case and for the standard Fourier heat flux law ( $h \equiv 1$ in the $\vartheta$-equation)

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Problem 1 (Joint work with Riccarda Rossi)

1) To prove the well-posedness on $[0, T]$ for the full PDE system in the 1D (in space) case and for the standard Fourier heat flux law ( $h \equiv 1$ in the $\vartheta$-equation)
2) To study the long-time behavior of solutions of 1 ) in case

$$
\vartheta_{t}+\vartheta \chi_{t}-\Delta \vartheta=0
$$

replaces the internal energy balance

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## Formulation of Problem 1 (The case $h \equiv 1$ - Fourier heat flux)

Find functions $\vartheta, \chi: \Omega \times[0, T] \rightarrow \mathbb{R}$ such that

$$
\chi(x, t) \in \operatorname{dom}(W) \text { and } \vartheta(x, t)>0 \text { a.e. in } \Omega \times(0, T)
$$

and $\mathrm{u}: \Omega \times[0, T] \rightarrow \mathbb{R}^{3}$ fulfilling the initial conditions:

$$
\begin{equation*}
\vartheta(0)=\vartheta_{0}, \quad \chi(0)=\chi_{0}, \quad \mathbf{u}(0)=\mathbf{u}_{0}, \quad \mathbf{u}_{t}(0)=\mathbf{v}_{0} \quad \text { in } \Omega, \tag{IC1}
\end{equation*}
$$

the equations a.e. in $\Omega \times(0, T)$ :

$$
\begin{align*}
& \vartheta_{t}+\chi_{t} \vartheta-\Delta \vartheta=\mu\left|\chi_{t}\right|^{2}+\chi\left|\varepsilon\left(\mathbf{u}_{t}\right)\right|^{2}  \tag{P1a}\\
& \mu \chi_{t}-\nu \Delta \chi+W^{\prime}(\chi)=\vartheta-\vartheta_{c}+\frac{|\varepsilon(\mathbf{u})|^{2}}{2}  \tag{P1b}\\
& \mathbf{u}_{t t}-\operatorname{div}\left((1-\chi) \varepsilon(\mathbf{u})+\chi \varepsilon\left(\mathbf{u}_{t}\right)\right)=\mathbf{0} \tag{P1c}
\end{align*}
$$

and the boundary conditions:

$$
\begin{equation*}
\partial_{\mathbf{n}} \vartheta=0, \quad \partial_{\mathbf{n}} \chi=0, \quad \mathbf{u}=\mathbf{0} \quad \text { on } \partial \Omega \times(0, T) . \tag{BC1}
\end{equation*}
$$

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## Formulation of Problem 2 (The case $\varepsilon(\mathbf{u})=$ const)

Find functions $\vartheta, \chi: \Omega \times[0, T] \rightarrow \mathbb{R}$ such that

$$
\chi(x, t) \in \operatorname{dom}(W) \text { and } \vartheta(x, t)>0 \text { a.e. in } \Omega \times(0, T)
$$

and fulfilling the equations a.e. in $\Omega \times(0, T)$ :

$$
\begin{align*}
& \vartheta_{t}+\vartheta \chi_{t}-\operatorname{div}(h(\vartheta) \nabla \vartheta)=\mu\left|\chi_{t}\right|^{2}  \tag{P2a}\\
& \mu \chi_{t}-\nu \Delta \chi+W^{\prime}(\chi)=\vartheta-\vartheta_{c} \tag{P2b}
\end{align*}
$$

and the initial and boundary conditions:

$$
\begin{align*}
& \vartheta(0)=\vartheta_{0}, \quad \chi(0)=\chi_{0} \quad \text { in } \Omega  \tag{IC2}\\
& \partial_{\mathbf{n}} \vartheta=0, \quad \partial_{\mathbf{n}} \chi=0 \quad \text { on } \partial \Omega \times(0, T) . \tag{BC2}
\end{align*}
$$

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## Relations between Problem 2 and the "classical" models

- The Sfefan problem. If $\mu=\nu=0, h \equiv 1$ and $W^{\prime}=\partial I_{[0,1]}+\vartheta_{c}$ the system (P2a-P2b) reduces to

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\begin{aligned}
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entailing the weak formulation of the two-phase Stefan problem:

$$
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& \vartheta_{t}+\vartheta_{c} \chi_{t}-\Delta \vartheta=0 \\
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\end{aligned}
$$

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- The phase-relaxation. If $\nu=0, h \equiv 1 W^{\prime}=\partial I_{[0,1]}+\vartheta_{c}$ and multiplying (P2b) by $\chi_{t}$, the system (P2a-P2b) reduces to


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$$
\begin{aligned}
& \vartheta_{t}+\vartheta_{c} \chi_{t}-\Delta \vartheta=0 \\
& \mu \chi_{t}+\partial I_{[0,1]}(\chi) \ni\left(\vartheta-\vartheta_{c}\right)
\end{aligned}
$$

which is the phase relaxation model introduced by Visintin.

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## The global results

Joint work with R. Rossi. For Problem 1 in 1D:

- well-posedness for the full system (P1a-BC1) on $[0, T]$;
- analysis of the associated $\omega$-limit of trajectory for the system coupling (IC1), (P1b-BC1) with the simplified internal energy equation:

$$
\begin{equation*}
\vartheta_{t}+\vartheta \chi_{t}-\Delta \vartheta=0 \tag{P1a'}
\end{equation*}
$$

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\vartheta_{t}+\vartheta \chi_{t}-\Delta \vartheta=0 \tag{P1a'}
\end{equation*}
$$

Joint work with E. Feireisl, H. Petzeltová. For Problem 2 in 3D:

- existence of regular solutions and uniqueness in case $h(\vartheta)=h_{0}+\varepsilon k(\vartheta)$ and $k(\vartheta) \geq c_{k} \vartheta^{p}$ with $\varepsilon>0, p \in[3,+\infty)$;


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- existence of regular solutions and uniqueness in case $h(\vartheta)=h_{0}+\varepsilon k(\vartheta)$ and $k(\vartheta) \geq c_{k} \vartheta^{p}$ with $\varepsilon>0, p \in[3,+\infty)$;
- existence of weak solutions in case $h(\vartheta)=h_{0}$ (Fourier heat flux law), obtained as a limit for $\varepsilon \searrow 0$ of the previous one and satisfying (P2b-BC2), an entropy inequality and the total energy conservation in a suitable sense.

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## Hypothesis 1 (To solve Problem 1)

(i) $\Omega=(0, \ell)$, for some $\ell>0$
(ii) $W=\widehat{\beta}+\widehat{\gamma}$, where $\widehat{\gamma} \in \mathrm{C}^{2}([0,1])$, with derivative $\gamma:=\widehat{\gamma}^{\prime}$
(iii) $\overline{\operatorname{dom}(\widehat{\beta})}=[0,1]$
$\widehat{\beta}: \operatorname{dom}(\widehat{\beta}) \rightarrow \mathbb{R}$ I.s.c., convex, differentiable in $(0,1)$
the graph $\beta=\widehat{\beta}^{\prime}$ satisfies the "coercivity" conditions:

$$
\lim _{x \rightarrow 0^{+}} \beta(x)=-\infty, \quad \lim _{x \rightarrow 1^{-}} \beta(x)=+\infty
$$

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and, for all $\rho>0, \beta$ is a Lipschitz continuous function on $[\rho, 1-\rho]$

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and, for all $\rho>0, \beta$ is a Lipschitz continuous function on $[\rho, 1-\rho]$
(iii) the data satisfy:

$$
\begin{aligned}
& \mathbf{u}_{0} \in H_{0}^{2}(0, \ell), \quad \mathbf{v}_{0} \in H_{0}^{1}(0, \ell) \\
& \vartheta_{0} \in H^{1}(0, \ell) \quad \text { and } \quad \min _{x \in[0, \ell]} \vartheta_{0}(x)>0, \quad \chi_{0} \in H_{N}^{2}(\Omega)
\end{aligned}
$$

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\begin{aligned}
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& \vartheta_{0} \in H^{1}(0, \ell) \quad \text { and } \quad \min _{x \in[0, \ell]} \vartheta_{0}(x)>0, \quad \chi_{0} \in H_{N}^{2}(\Omega)
\end{aligned}
$$

(iv) the datum $\chi_{0}$ is "separated from the potential barriers":

$$
\min _{x \in \bar{\Omega}} \chi_{0}(x)>0, \quad \max _{x \in \bar{\Omega}} \chi_{0}(x)<1
$$

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## Theorem 1 (Well-posedness for Problem 1 on $[0, T]$ )

Fix $T>0$ and assume Hypothesis 1 .

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## Theorem 1 (Well-posedness for Problem 1 on $[0, T]$ )

Fix $T>0$ and assume Hypothesis 1. Then
$\diamond$ there exist $\delta \in(0,1)$ - depending on the potential $W$ and on the initial datum $\chi_{0}$,
$\diamond$ there exist $\zeta_{T} \in(0,1)$ - depending on the potential $W$, on the initial datum $\chi_{0}$, and on the final time $T$,
$\diamond$ there exist $\theta_{T}^{*}>0$ - depending on $T$ and on the problem data,
$\diamond$ and there exist a unique triple $(\vartheta, \chi, \mathbf{u})$ solving Problem 1 and complying with

$$
\begin{aligned}
& \vartheta \in L^{2}\left(0, T ; H_{N}^{2}(\Omega)\right) \cap L^{\infty}\left(0, T ; H^{1}(0, \ell)\right) \cap H^{1}\left(0, T ; L^{2}(\Omega)\right) \\
& \cap W^{1, \infty}\left(0, T ; H^{1}(0, \ell)^{\prime}\right) \\
& \chi \in L^{\infty}\left(0, T ; H_{N}^{2}(\Omega)\right) \cap H^{1}\left(0, T ; H^{1}(0, \ell)\right) \cap W^{1, \infty}\left(0, T ; L^{2}(\Omega)\right) \\
& \mathbf{u} \in H^{1}\left(0, T ; H_{0}^{2}(0, \ell)\right) \cap W^{1, \infty}\left(0, T ; H_{0}^{1}(0, \ell)\right) \cap H^{2}\left(0, T ; L^{2}(\Omega)\right)
\end{aligned}
$$

and such that the following separation inequalities hold true:

$$
\vartheta(x, t) \geq \theta_{T}^{*}, \quad \delta \leq \chi(x, t) \leq \zeta_{T} \quad \forall(x, t) \in[0, \ell] \times[0, T]
$$

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## Theorem 2 (Long-time behavior of solution to Problem 1)

We consider Problem 1, where (P1a) is replaced (within the framework of small perturbation assumptions) with

$$
\begin{equation*}
\vartheta_{t}+\vartheta \chi_{t}-\Delta \vartheta=0 \quad \text { a.e. in }(0, \ell) \times(0, T) . \tag{P1a'}
\end{equation*}
$$

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\end{equation*}
$$

Then, the nonempty $\omega$-limit set:

$$
\begin{aligned}
\omega\left(\vartheta_{0}, \chi_{0}, \mathbf{u}_{0}\right):= & \left\{\left(\vartheta_{\infty}, \chi_{\infty}, \mathbf{u}_{\infty}\right) \in H^{1}(0, \ell) \times H^{1}(0, \ell) \times H_{0}^{1}(0, \ell):\right. \\
& \exists t_{n} \nearrow \infty:\left(\vartheta\left(t_{n}\right), \chi\left(t_{n}\right), \mathbf{u}\left(t_{n}\right)\right) \rightarrow\left(\vartheta_{\infty}, \chi_{\infty}, \mathbf{u}_{\infty}\right) \\
& \text { in } \left.H^{1-\nu}(0, \ell) \times H^{1-\nu}(0, \ell) \times H_{0}^{1-\nu}(0, \ell) \forall \nu \in(0,1)\right\}
\end{aligned}
$$

is compact and connected in $H^{1-\nu}(0, \ell) \times H^{1-\nu}(0, \ell) \times H_{0}^{1-\nu}(0, \ell)$ for all $\nu \in(0,1)$.

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$$

is compact and connected in $H^{1-\nu}(0, \ell) \times H^{1-\nu}(0, \ell) \times H_{0}^{1-\nu}(0, \ell)$ for all $\nu \in(0,1)$. Moreover, $\exists \zeta_{\infty} \in(0,1):$ all $\left(\vartheta_{\infty}, \chi_{\infty}, \mathbf{u}_{\infty}\right) \in \omega\left(\vartheta_{0}, \chi_{0}, \mathbf{u}_{0}\right)$ solves the stationary problem in $(0, \ell)$ :

$$
-\Delta \vartheta_{\infty}=0, \quad-\Delta \chi_{\infty}+\beta\left(\chi_{\infty}\right)+\gamma\left(\chi_{\infty}\right)=\vartheta_{\infty}, \quad \mathbf{u}_{\infty}=0
$$

and fulfils

$$
\vartheta_{\infty}(x) \geq 0, \quad \min _{x \in[0, e]} \chi_{\infty}(x) \geq \delta, \quad \max _{x \in[0, e]} \chi_{\infty}(x) \leq \zeta_{\infty} .
$$

In particular, $\exists \bar{\vartheta}_{\infty} \in[0,+\infty): \vartheta_{\infty}(x)=\bar{\vartheta}_{\infty}$ for all $x \in[0, \ell]$.

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## Remarks on Theorem 2

$\checkmark$ In addition to Theorem 2, if

$$
W^{\prime}=\beta+\gamma \text { is strictly increasing in }(0,1)
$$

for every $\left(\vartheta_{\infty}, \chi_{\infty}, 0\right) \in \omega\left(\vartheta_{0}, \chi_{0}, \mathbf{u}_{0}\right)$, the component $\chi_{\infty}$ is also constant on $(0, \ell)$ and

$$
\chi_{\infty}(x)=(\beta+\gamma)^{-1}\left(\bar{\vartheta}_{\infty}\right) \quad \forall x \in[0, \ell] .
$$

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$$

$\checkmark$ A crucial step: the first separation inequality extends to $(0,+\infty)$

$$
\chi(x, t) \geq \delta \quad \forall(x, t) \in[0, \ell] \times[0,+\infty) .
$$

(Sep0)
Instead, the separation from 1 does not hold globally on $(0,+\infty)$.

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Instead, the separation from 1 does not hold globally on $(0,+\infty)$.
$\checkmark$ In order to prove the existence of the global attractor for bundle of trajectories we would need to strengthen our large-time a priori estimates on $\mathbf{u}$. However, it seems to us that better large-time estimates on $\mathbf{u}$ cannot be obtained, if one relies on the sole (Sep0).

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Instead, the separation from 1 does not hold globally on $(0,+\infty)$.
$\checkmark$ In order to prove the existence of the global attractor for bundle of trajectories we would need to strengthen our large-time a priori estimates on $\mathbf{u}$. However, it seems to us that better large-time estimates on $\mathbf{u}$ cannot be obtained, if one relies on the sole (Sep0). The same technical drawback makes it difficult to implement Łojasiewicz-Simon procedures to prove the convergence as $t \rightarrow+\infty$ of the whole trajectories $(\vartheta(t), \chi(t), u(t))_{t \in(0,+\infty)}$ to the elements of their $\omega$-limit.

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## Recall: Problem 2 (The case $\varepsilon(\mathbf{u})=$ const)

Find functions $\vartheta, \chi: \Omega \times[0, T] \rightarrow \mathbb{R}$ such that

$$
\chi(x, t) \in \operatorname{dom}(W) \text { and } \vartheta(x, t)>0 \text { a.e. in } \Omega \times(0, T)
$$

fulfilling the equations a.e. in $\Omega \times(0, T)$ :

$$
\begin{align*}
& \vartheta_{t}+\vartheta \chi_{t}-\operatorname{div}(h(\vartheta) \nabla \vartheta)=\mu\left|\chi_{t}\right|^{2}  \tag{P2a}\\
& \mu \chi_{t}-\nu \Delta \chi+W^{\prime}(\chi)=\vartheta-\vartheta_{c} \tag{P2b}
\end{align*}
$$

and the initial and boundary conditions:

$$
\begin{align*}
& \vartheta(0)=\vartheta_{0}, \quad \chi(0)=\chi_{0} \quad \text { in } \Omega  \tag{BC2}\\
& \partial_{\mathbf{n}} \vartheta=0, \quad \partial_{\mathbf{n}} \chi=0 \quad \text { on } \partial \Omega \times(0, T) . \tag{IC2}
\end{align*}
$$

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## Theorem 3 (Well-posedness for Problem 2 in case $\varepsilon>0$ ).

Fix $T>0$ and assume Hypothesis 2. Suppose that $W$, satisfies

- either the regularity assumption

$$
W \in C^{2}(\mathbb{R}), \quad\left|W^{\prime \prime}(r)\right| \leq c_{L i p} \quad \forall r \in \mathbb{R}
$$

for some positive constant $c_{\text {Lip }}$

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$$
\lim _{x \rightarrow 0^{+}} \beta(x)=-\infty, \quad \lim _{x \rightarrow 1^{-}} \beta(x)=+\infty
$$

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\min _{x \in \bar{\Omega}} \chi_{0}(x)>0, \quad \max _{x \in \bar{\Omega}} \chi_{0}(x)<1
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the datum $\chi_{0}$ is separated from 0 and 1 :

$$
\min _{x \in \bar{\Omega}} \chi_{0}(x)>0, \quad \max _{x \in \bar{\Omega}} \chi_{0}(x)<1
$$

Then, there exist a unique solution $(\vartheta, \chi)$ to Problem 2 such that it complies with the following regularity properties:

$$
\begin{aligned}
& \vartheta \in C^{0, \sigma}\left(\bar{Q}_{T}\right) \cap C^{0}\left((0, T] ; H^{2}(\Omega)\right) \cap C^{1}\left((0, T] ; C^{0, \sigma}(\bar{\Omega})\right) \\
& \chi \in C^{0, \sigma}\left(\bar{Q}_{T}\right) \cap C^{0}\left((0, T] ; H^{2}(\Omega)\right) \cap C^{1}\left((0, T] ; C^{0, \sigma}(\bar{\Omega})\right) .
\end{aligned}
$$

## Theorem 4 (Existence for Problem 2 in case $\varepsilon=0$ )

Fix $T>0$ and assume Hypothesis 2 . Let $s \in(13 / 8,11 / 6)$ in the 3D case, $s \in(5 / 3,2)$ in the 2D case.

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Fix $T>0$ and assume Hypothesis 2. Let $s \in(13 / 8,11 / 6)$ in the 3D case, $s \in(5 / 3,2)$ in the 2D case. Then there exists at least one pair $(\vartheta, \chi)$ with the regularities

$$
\begin{aligned}
& \vartheta \in L^{\infty}\left(0, T ; L^{1}(\Omega)\right) \cap L^{s}\left(Q_{T}\right) \\
& \quad \vartheta(x, t)>0 \quad \text { a. e. in } Q_{T} \\
& \log (\vartheta) \in L^{\infty}\left(0, T ; L^{1}(\Omega)\right) \cap L^{2}\left(0, T ; H^{1}(\Omega)\right) \\
& \chi \in C^{0}\left([0, T] ; H^{1}(\Omega)\right) \cap L^{s}\left(0, T ; W^{2, s}(\Omega)\right), \quad \chi_{t} \in L^{s}\left(Q_{T}\right)
\end{aligned}
$$

satisfying the entropy inequality $\left(\forall \varphi \in \mathcal{D}\left(\bar{Q}_{T}\right), \varphi \geq 0\right)$ :

$$
\begin{aligned}
\int_{0}^{T} \int_{\Omega}((\log \vartheta+\chi) & \left.\partial_{t} \varphi+\nabla \log \vartheta \cdot \nabla \varphi\right) d x d t \\
& \leq \int_{0}^{T} \int_{\Omega} \frac{1}{\vartheta}\left(-\mu\left|\chi_{t}\right|^{2}+\nabla \log \vartheta \cdot \nabla \vartheta\right) \varphi d x d t
\end{aligned}
$$

equation (P2b), initial and boundary conditions (BC2-IC2), and the total energy conservation
$E(t)=E(0) \quad$ a.e. in $[0, T], \quad$ where $E \equiv \int_{\Omega}\left(\vartheta+W(\chi)+\frac{\nu}{2}|\nabla \chi|^{2}\right) d x$.

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## Remarks on Theorems 3 and 4

- The energy estimate on Problem $2\left[(\mathrm{P} 2 \mathrm{a}) \times 1+(\mathrm{P} 2 \mathrm{~b}) \times \chi_{t}\right]$ gives $\vartheta$ bdd only in $L^{\infty}\left(0, T ; L^{1}(\Omega)\right)$
- The crucial estimate leading to the existence of strong solutions (cf. Theorem 3) is (P2a) $\times 1 / \vartheta$ leading to

$$
\varepsilon^{1 / 2}\left|\nabla \vartheta^{p / 2}\right|_{L^{2}(\Omega \times(0, T))} \leq c
$$

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$$
\varepsilon^{1 / 2}\left|\nabla \vartheta^{p / 2}\right|_{L^{2}(\Omega \times(0, T))} \leq c
$$

- In case $\varepsilon>0$ this lead us to improve the regularity of $\vartheta$ (and hence of $\chi$ ) by means of regularity results for semi-linear parabolic equations


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- The energy estimate on Problem $2\left[(\mathrm{P} 2 \mathrm{a}) \times 1+(\mathrm{P} 2 \mathrm{~b}) \times \chi_{t}\right]$ gives $\vartheta$ bdd only in $L^{\infty}\left(0, T ; L^{1}(\Omega)\right)$
- The crucial estimate leading to the existence of strong solutions (cf. Theorem 3) is (P2a) $\times 1 / \vartheta$ leading to

$$
\varepsilon^{1 / 2}\left|\nabla \vartheta^{p / 2}\right|_{L^{2}(\Omega \times(0, T))} \leq c
$$

- In case $\varepsilon>0$ this lead us to improve the regularity of $\vartheta$ (and hence of $\chi$ ) by means of regularity results for semi-linear parabolic equations
- The existence of weak solutions in case $\varepsilon=0$ (cf. Theorem 4) is obtained by passing to the limit as $\varepsilon \searrow 0$ and using convexity and semi-continuity arguments


## E. Rocca

Free-energy
functional
Pseudo-Potential of dissipation
Macroscopic motion Microscopic motion Internal energy balance

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- It is easy to check that the entropy inequality and the energy conservation in Theorem 4, together with equation (P2b) give rise to the standard energy balance (P2a) in case the solution is sufficiently smooth


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