

# Fatigue accumulation in oscillating thermoelastoplastic structures with hysteresis part I (modelling)

**Michela Eleuteri**

*Università degli Studi di Milano*

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**EQUADIFF13** - Prague, August 29th, 2013

# Plan of the talk

- Theory of hysteresis operators powerful tool for solving mathematical problems in various applications (solid mechanics, material fatigue, ferromagnetism, phase transitions)

## Elasto-plastic oscillations of beams and plates with material fatigue

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M. ELEUTERI, J. KOPFOVÁ AND P. KREJČÍ, submitted.

- Main modeling assumption: proportionality between fatigue rate and dissipation rate
- Influence of energy dissipation (due to material softening on the damage increase) taken into account - fatigue accumulation accelerated - a singularity (material failure) may develop in finite time
- Account also for *decreasing fatigue rate* (phase parameter  $\chi$ )
- Discuss thermodynamic consistency of the model with a proper choice of the evolution equation for the fatigue parameter  $m$

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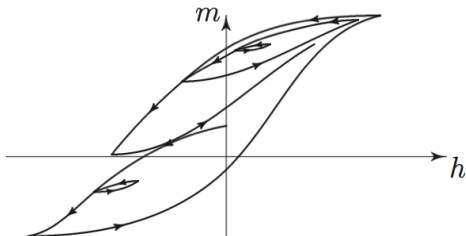
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# Hysteresis: a rate-independent memory effect

- **Hysteresis:** a rate-independent memory effect (multidisciplinary character)



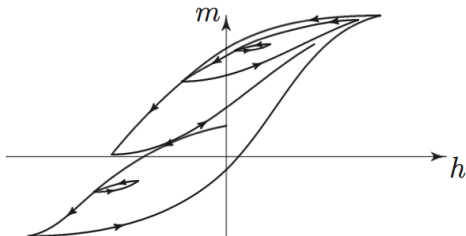
Typical hysteresis diagram in ferromagnetism ( $h$  magnetic field,  $m$  magnetization).

- **Phase transitions and hysteresis:** P. Krejčí, J. Sprekels (NA, 2000; JMAA 2000; M2AS 2002; AMSA 2004); G. Gilardi, P. Krejčí, J. Sprekels (M2AS, 2000); P. Krejčí, J. Sprekels, Z. Songmu (JDE, 2001); P. Krejčí, J. Sprekels, U. Stefanelli (SIMA 2002; AMSA 2003)



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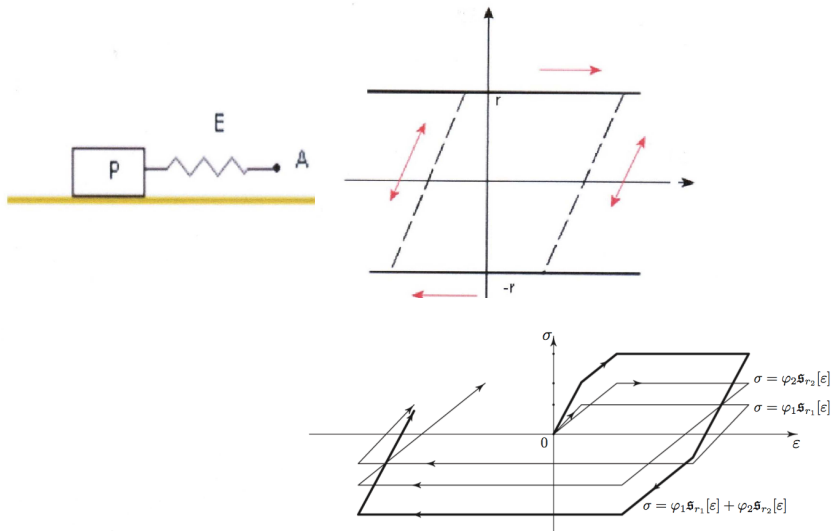
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# The stop and the Prandtl-Ishlinskii operators



# A classical hysteresis-type model for 1D elastoplasticity

- Introduced by L. Prandtl and A. Yu. Ishlinskii (extensions to the multidimensional case are possible)
- The relation between (one-dimensional) strain  $\varepsilon$  and stress  $\sigma$  is given in the form of the so-called Prandtl-Ishlinskii operator

$$\sigma = \mathcal{P}[\varepsilon](t) = \int_0^\infty \mathfrak{s}_r[\varepsilon](t) \varphi(r) dr$$

for all  $\varepsilon \in W^{1,1}(0, T)$ . Here  $\varphi > 0$  is a nonnegative weight function not known a priori and  $\mathfrak{s}_r$  represents the **one-dimensional elastic-ideally plastic element or stop operator**, with the threshold  $r > 0$

- Prandtl-Ishlinskii description of elastoplasticity: a superposition of infinitely many stop operators having different thresholds (very imaginative and easily understood) BUT engineers very often prefer classical engineering approaches like the three-dimensional von Mises or Tresca models
- Motivation: the disadvantage that the weight function  $\varphi$  is not known a priori and must be identified

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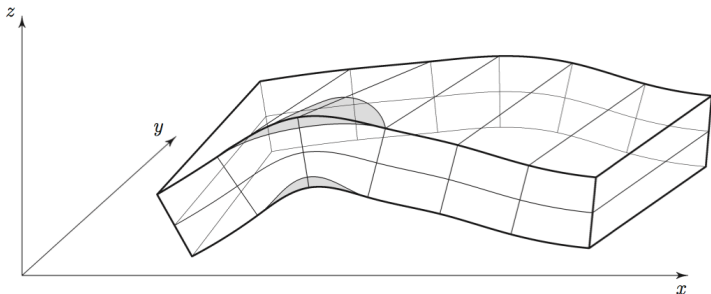
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# New theory of oscillating elastoplastic beams and plates

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- **Key point:** the 3D single-yield von Mises criterion leads after a dimensional reduction to a multi-yield Prandtl-Ishlinskii operator where the weight function  $\varphi$  **can be explicitly determined!**



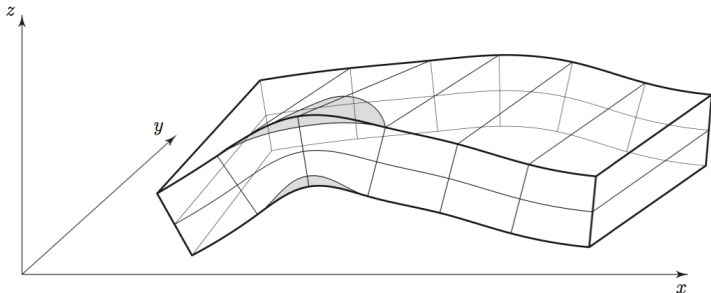
A plate section with grey plasticized zone.

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# Motivation for material fatigue

- Plastic deformations lead to energy dissipation and material fatigue, manifested by material softening, heat release, material failure in finite time
- Very important: take into account the effects of energy exchange and estimating the lifetime of oscillating thermoelastoplastic structures under material fatigue
- **Aim:** develop a thermodynamically consistent theory of oscillating thermoelastoplastic plates under material fatigue (dynamic approach - different from literature)
- The resulting system from the theory developed by Krejčí & al:

$$\partial_t w - \partial_{tt} \Delta w + \mathbf{D}_2^* \sigma = g,$$

$$\sigma = \mathbf{B} \varepsilon + \int_0^\infty s_{rZ}[\varepsilon](t) \varphi(r) dr$$

$$\varepsilon = \mathbf{D}_2 w$$

- We introduce  $\theta > 0$  (absolute temperature) and  $m(x, t) \geq 0$  (material fatigue)

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- We introduce  $\theta > 0$  (absolute temperature) and  $m(x, t) \geq 0$  (material fatigue); **aim:** get an evolution equation for  $m$  consistent from the thermodynamic point of view



# Evolution equation for the fatigue

- **Main assumption:** proportionality between rate of fatigue  $\partial_t m$  and

$$\begin{aligned}\mathcal{D} &= \langle \sigma, \partial_t \varepsilon \rangle - \partial_t \theta \mathcal{S}[\theta, \varepsilon] - \partial_t \mathcal{F}[\theta, \varepsilon] \\ &= -\frac{1}{2} \langle \mathbf{B}'(m) \varepsilon, \varepsilon \rangle \partial_t m + \int_0^\infty \langle \partial_t (\varepsilon - s_{rZ}[\varepsilon]), s_{rZ}[\varepsilon] \rangle \varphi(\theta, r) dr\end{aligned}$$

where  $\mathcal{F}$  is the **specific free energy** and  $\mathcal{S}$  is the **specific entropy**

- Justified by the so-called **rainflow method for cyclic fatigue accumulation** in uniaxial processes (counts closed hysteresis loops in the loading history - mechanism of energy dissipation)
- In multiaxial loading processes? Experimental measurements at the point of material failure: strong temperature increase, manifested by energy dissipation peak (temperature tests are in engineering practice for damage analysis in high frequency regimes (e.g. in aircraft industry))

$$\left( \frac{1}{C(\theta)} + \frac{1}{2} \langle \mathbf{B}'(m) \varepsilon, \varepsilon \rangle \right) \partial_t m = \int_0^\infty \langle \partial_t (\varepsilon - s_{rZ}[\varepsilon]), s_{rZ}[\varepsilon] \rangle \varphi(\theta, r) dr$$

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$$\begin{aligned}\mathcal{D} &= \langle \sigma, \partial_t \varepsilon \rangle - \partial_t \theta \mathcal{S}[\theta, \varepsilon] - \partial_t \mathcal{F}[\theta, \varepsilon] \\ &= -\frac{1}{2} \langle \mathbf{B}'(m) \varepsilon, \varepsilon \rangle \partial_t m + \int_0^\infty \langle \partial_t (\varepsilon - \varepsilon_{rZ}[\varepsilon]), \varepsilon_{rZ}[\varepsilon] \rangle \varphi(\theta, r) dr\end{aligned}$$

where  $\mathcal{F}$  is the **specific free energy** and  $\mathcal{S}$  is the **specific entropy**

- Justified by the so-called **rainflow method for cyclic fatigue accumulation** in uniaxial processes (counts closed hysteresis loops in the loading history - mechanism of energy dissipation)
- In multiaxial loading processes? Experimental measurements at the point of material failure: strong temperature increase, manifested by energy dissipation peak (temperature tests are in engineering practice for damage analysis in high frequency regimes (e.g. in aircraft industry))

$$\left( \frac{1}{C(\theta)} + \frac{1}{2} \langle \mathbf{B}'(m) \varepsilon, \varepsilon \rangle \right) \partial_t m = \int_0^\infty \langle \partial_t (\varepsilon - \varepsilon_{rZ}[\varepsilon]), \varepsilon_{rZ}[\varepsilon] \rangle \varphi(\theta, r) dr$$

- $\mathbf{B}'(m) \leq 0$  softening  $\Rightarrow$  **singularity!** Material failure in finite time!

# The model with phase transition

- **Motivation:**

- possibility to account also for decreasing fatigue rate (in view of engineering applications)
- the material can be partially repaired by local melting

- **How to achieve this goal:**

- Phase transition equation in the form of melting-solidification law

$$\alpha \chi_t \in -\partial_{\chi} \mathcal{F}[c, \theta, \chi] \quad \chi \in [0, 1]$$

$\chi_0 \in [0, 1]$  some initial condition,  $A(x, t) := \int_0^t \frac{1}{\alpha} \left( \frac{1}{\theta_c} (\theta - \theta_c) \right) (x, \tau) d\tau$

$$(\chi_t - A_t)(z - \chi) \geq 0 \text{ for all } z \in [0, 1]$$

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- **How to achieve this goal:**

• consider a phase transition in a material  
• mechanical loading  $\sigma$  depends on melting  
• the damage  $\chi$  of the material can be affected  
• possibly considering a sufficiently large time interval of observation (small  
increments of time) to avoid solution of the constitutive PDEs  
• system can be local

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- **How to achieve this goal:**

- account for phase transition in the model
- as material fatigue and  $\chi$  degree of melting
- the evolution of  $\chi$  is modeled by a PDE, possibly considering a nonlinear dependence of the fatigue damage on the temperature, possibly depending on the local solution of the constitutive PDEs
- $\chi$  can be bounded

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- the time of failure of the material can be shifted
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$$\chi \in \mathfrak{s}_{[0,1]}[\chi_0, A]$$

$\mathfrak{s}_{[0,1]}$  is a shifted stop

# Thermodynamical consistency

- If we introduce  $\mathcal{F}[\varepsilon, \theta, \chi]$  **specific free energy**,  $\mathcal{S}[\varepsilon, \theta, \chi]$  **specific entropy** and  $\mathcal{U}[\varepsilon, \theta, \chi]$  **internal energy** we are able to show that the first and second principles of thermodynamics are satisfied

$$\frac{\partial}{\partial t} \mathcal{U}[\varepsilon, \theta, \chi] + \operatorname{div} \mathbf{q} = \langle \sigma, \varepsilon_t \rangle \quad (\text{energy conservation})$$

$$\frac{\partial}{\partial t} \mathcal{S}[\varepsilon, \theta, \chi] + \operatorname{div} \frac{\mathbf{q}}{\theta} \geq 0, \quad (\text{Clausius-Duhem inequality})$$

- **Evolution equation for  $m$ :**

$$(C + \mathcal{K}[m, \theta, \varepsilon]) m_t = -h(\chi_t) + \mathcal{D}[m, \theta, \varepsilon]$$

- where

$$\mathcal{D}[m, \theta, \varepsilon] := \int_0^\infty \varphi(m, \theta, r) \langle \mathbf{K} s_{rZ}[\varepsilon], (\varepsilon - s_{rZ}[\varepsilon])_t \rangle dr$$

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- allow the possibility of decreasing rate (i.e.  $m_t < 0$ ) but only in the case if  $\chi$  grows faster than the plastic dissipation rate (strong melting)

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# Conclusion

- Rainflow method for fatigue evaluation in elastoplastic materials (uniaxial cyclic loading) allow to consider dissipated energy as a measure for fatigue
- The solution cannot be expected to exist globally: singularities (thermal shocks) occur in finite time
- Phase transition in the model accounts also for decreasing fatigue rate
- The time of failure can be shifted and considering a sufficiently large time interval of observation (usual engineering viewpoint) a global solution of the corresponding PDEs system can be found
- The resulting full system of energy and momentum balance equations is consistent with the first and the second principles of thermodynamics; mathematical analysis of the model is work in progress

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