

On Local refinement for IGA

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Outline

- 1 Isogeometric Analysis: Basics
- 2 IGA: local refinement
 - T-mesh, spline space and dimension
 - spline with hierarchical structure
 - T-splines and Analysis-suitable T-splines

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B-splines

Knot vector $\Xi = \{u_0, u_1, \dots, u_m\}$;

B-splines:

$$N_i^0 = \begin{cases} 1, & u_i \leq u < u_{i+1}; \\ 0, & \text{otherwise.} \end{cases}$$

$$N_i^p(u) = \frac{u - u_i}{u_{i+p} - u_i} N_i^{p-1}(u) + \frac{u_{i+p+1} - u}{u_{i+p+1} - u_{i+1}} N_{i+1}^{p-1}(u).$$

Tensor-product NURBS:

$$R_{i,j}(u, v) = \frac{N_i^p(u) N_j^q(v) \omega_{i,j}}{\sum_{i,j} N_i^p(u) N_j^q(v) \omega_{i,j}}.$$

Geometric map: $F(u, v) = \sum C_{i,j} R_{i,j}(u, v)$,

What is IGA

IGA [T. Hughes et al, 2005]

Use the spline basis $R_{i,j} \circ F^{-1}$ which describes the geometry as a basis for Galerkin projection.

- no meshing;
- exact geometric description at all refinement levels;
- high order smooth functions;
- easy mesh refinement;
- global refinement;

What is IGA

IGA [T. Hughes et al, 2005]

Use the spline basis $R_{i,j} \circ F^{-1}$ which describes the geometry as a basis for Galerkin projection.

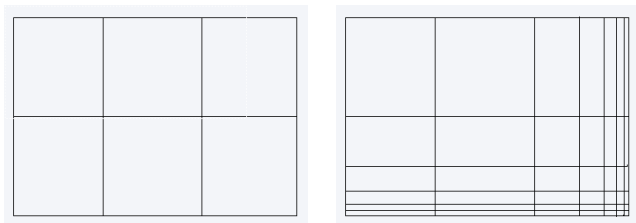
- no meshing;
- exact geometric description at all refinement levels;
- high order smooth functions;
- easy mesh refinement;
- global refinement;

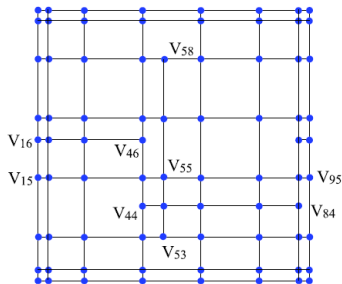
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Tensor-product mesh

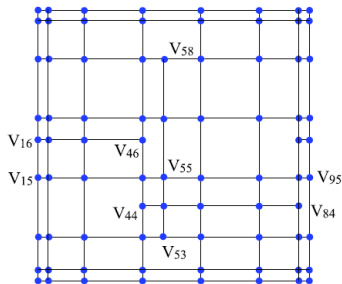
- The knot vectors define a rectangle tiling;
- Refinement where you really don't need it





Bi-degree: (d_1, d_2) , Smoothness: α, β :

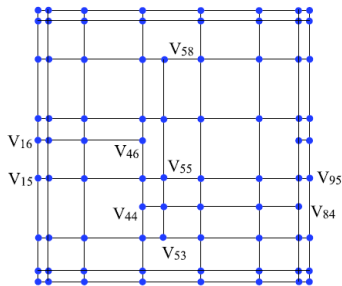
$$\mathcal{S}(d_1, d_2, \alpha, \beta, \mathcal{T}) := \left\{ f(x, y) \in C^{\alpha, \beta}(\Omega) \mid f|_{\phi} \in \mathbb{P}_{d_1 d_2}, \forall \phi \in \mathcal{F} \right\},$$



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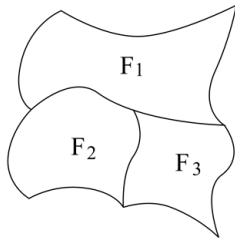
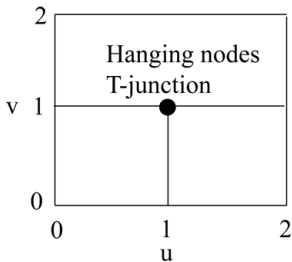
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Understand the space



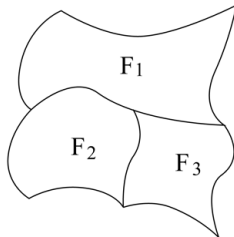
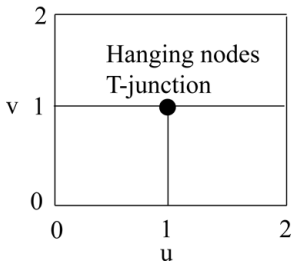
- Linear space;
- Dimension?
- Basis functions?

T-junction



- Three maps $F_i(u, v)$ meet at a T-junction (hanging node)

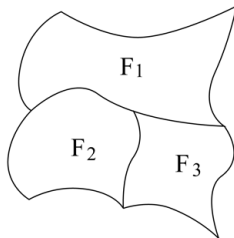
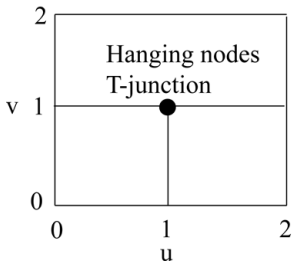
T-junction



C^0 continuity:

$$F_1(u, 1) = \begin{cases} F_2(u, 1), & 0 \leq u < 1; \\ F_3(u, 1), & 1 \leq u < 2. \end{cases} \quad (1)$$

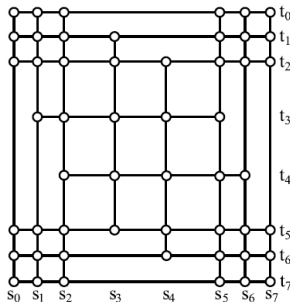
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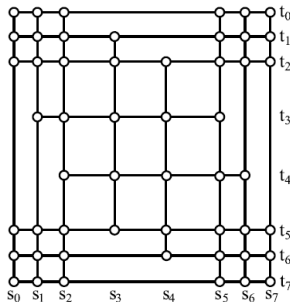
$$F_{1,v}(u, 1) = \begin{cases} F_{2,v}(u, 1), & 0 \leq u < 1; \\ F_{3,v}(u, 1), & 1 \leq u < 2. \end{cases} \quad (2)$$

Dimension: why is hard?



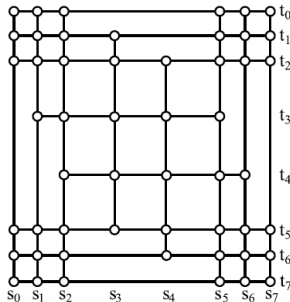
- Bi-cubic with C^2 , knots: $s_j = i$ and $t_j = i$
- Dimension = 65.

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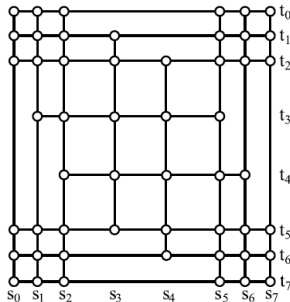
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Instability [X. Li and F. Chen, 2011]



- Bi-cubic with C^2 , knots: $s_j = j$ and $t_j = j$ except $s_3 = 2.999999$.
- Dimension = 64.

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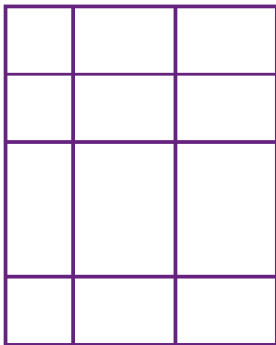


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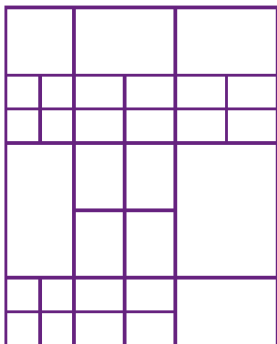
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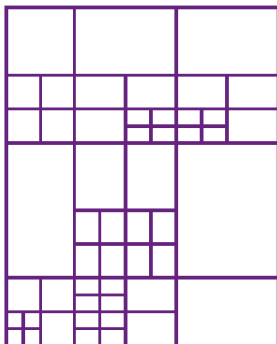
Hierarchical T-mesh



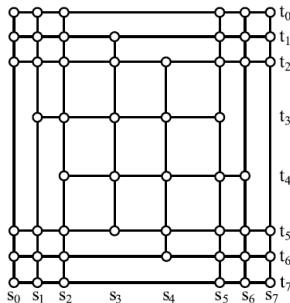
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Hierarchical T-mesh

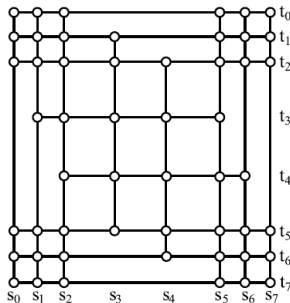


Reduce Regularity [J. Deng et al 2008]



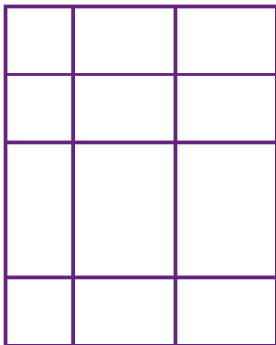
- In case of $d_1 \geq 2\alpha + 1$ and $d_2 \geq 2\beta + 1$,
- Dimension = $4 \times (V^+ + V^b)$ for $\mathcal{S}(3, 3, 1, 1, \mathcal{T})$.
- 176 in the above example.

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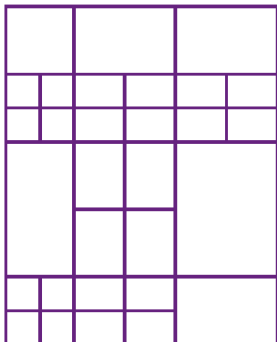
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Basis functions



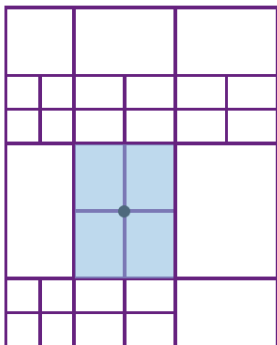
- Each knots has multiple two.
- Each vertex corresponds four basis functions.

Basis functions



- Origin cross vertices are kept;

Basis functions

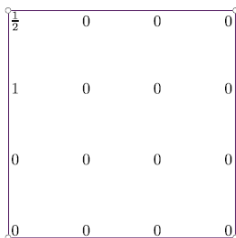


- Origin cross vertices are kept;
- Each vertex is a center of a rectangle and corresponds to four basis function.

Basis functions

- Linear independency: Trivial;
- Positivity: trivial;
- perfect local refinement;
- Positivity;
- affine invariance: No;

Basis functions



- Origin basis function;

Basis functions

$\frac{1}{2}$	$\frac{1}{4}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	0	0	0
$\frac{3}{4}$	$\frac{3}{8}$	$\frac{3}{16}$	$\frac{3}{32}$	$\frac{3}{32}$	0	0	0
$\frac{5}{8}$	$\frac{5}{16}$	$\frac{5}{32}$	$\frac{5}{64}$	$\frac{5}{64}$	0	0	0
$\frac{7}{16}$	$\frac{7}{32}$	$\frac{7}{64}$	$\frac{7}{128}$	$\frac{7}{128}$	0	0	0
$\frac{7}{16}$	$\frac{7}{32}$	$\frac{7}{64}$	$\frac{7}{128}$	$\frac{7}{128}$	0	0	0
$\frac{1}{4}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{32}$	$\frac{1}{32}$	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- Redefine the origin basis function in the new T-mesh;

Basis functions

$\frac{1}{2}$	$\frac{1}{4}$	$\frac{1}{8}$	$\frac{1}{16}$	$\frac{1}{16}$	0	0	0
$\frac{3}{4}$	$\frac{3}{8}$	$\frac{3}{16}$	$\frac{3}{32}$	$\frac{3}{32}$	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0
0	0	0	0	0	0	0	0

- Modify the basis function;

- Linear independency;
- Positivity;
- perfect local refinement;
- Positivity;
- affine invariance;
- **reduce regularity: more DOF.**

B-splines

B-splines:

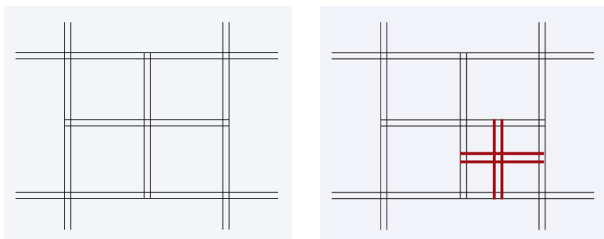
$$N_i^0 = \begin{cases} 1, & u_j \leq u < u_{j+1}; \\ 0, & \text{otherwise.} \end{cases}$$

$$N_i^p(u) = \frac{u - u_j}{u_{i+p} - u_j} N_i^{p-1}(u) + \frac{u_{i+p+1} - u}{u_{i+p+1} - u_{i+1}} N_{i+1}^{p-1}(u).$$

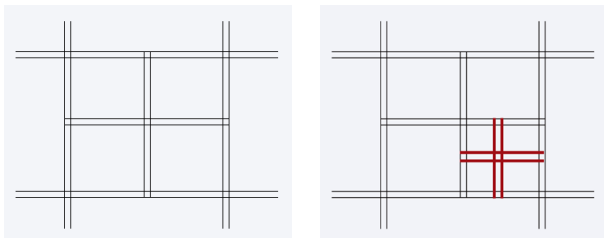
$N_i^p(u)$ is only associated with knots $u_j, u_{j+1}, \dots, u_{j+p+1}$, i.e., $N[u_j, u_{j+1}, \dots, u_{j+p+1}]$.

B-spline refinement:

$$N[u_j, u_{j+1}, \dots, u_{j+p+1}] = \frac{u_* - u_j}{u_{i+p} - u_j} N[u_j, \dots, u_*, \dots, u_{i+p}] + \frac{u_{i+p+1} - u_*}{u_{i+p+1} - u_{i+1}} N[u_{i+1}, \dots, u_*, \dots, u_{i+p+1}].$$

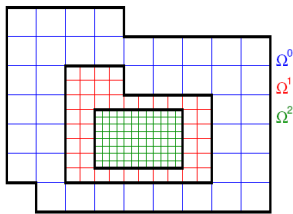


- For one basis function $N = N[0, 1, 1, 2, 2] \times N[0, 0, 1, 1, 2]$
- Four new basis functions:
 $N_1 = N[1, 1, 1.5, 1.5, 2] \times N[0, 0, 0.5, 0.5, 1]$,
 $N_2 = N[1, 1, 1.5, 1.5, 2] \times N[0, 0.5, 0.5, 1, 1]$,
 $N_3 = N[1, 1.5, 1.5, 2, 2] \times N[0, 0, 0.5, 0.5, 1]$,
 $N_4 = N[1, 1.5, 1.5, 2, 2] \times N[0, 0.5, 0.5, 1, 1]$

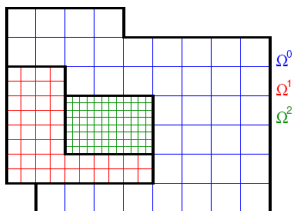


- Origin basis: $N = \frac{5}{32} N_1 + \frac{25}{64} N_2 + \frac{1}{16} N_3 + \frac{5}{32} N_4 + \dots$,
- Modified basis: $\hat{N} = N - (\frac{5}{32} N_1 + \frac{25}{64} N_2 + \frac{1}{16} N_3 + \frac{5}{32} N_4)$.

Hierarchical B-splines [A.-V. Vuong, C. Giannelli, et al. 2012]



- Nested domains;
- Each domain spanned by B-splines;
- Nested spaces;

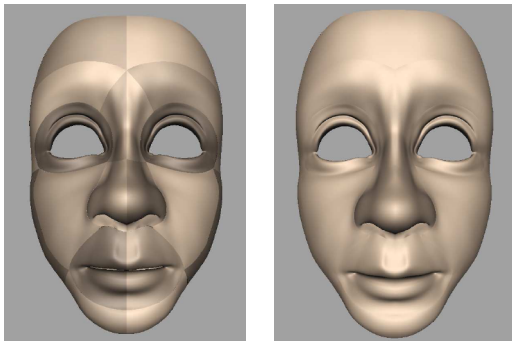


- Strict nested domains to make linear independency;

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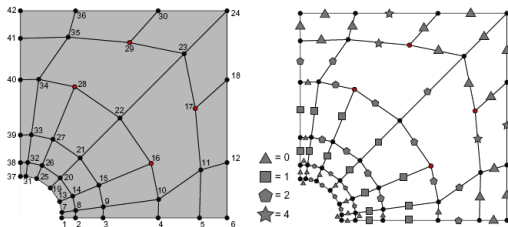
Merging



- T-junction cannot be avoided;
- Using the local information;
- Nested structure is not acceptable.

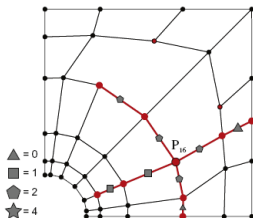
T-splines

Sederberg, et al, 2003, Sederberg, Cardon, Finnigan, North, Zheng, Lyche, 2004



- A T-grid and a valid knot interval configuration;

T-splines



- $T(\xi) = \sum_{i=1}^n C_i T_i(\xi);$
- $C_i = (x_i, y_i, z_i)$ or $C_i = (\omega_i x_i, \omega_i y_i, \omega_i z_i, \omega_i)$.

T-splines

T-splines are attractive:

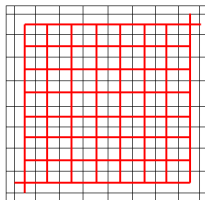
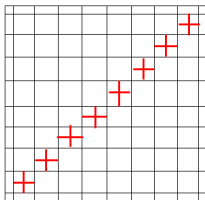
- NURBS compatible;
- efficient local refinement;
- trimmed NURBS to T-splines conversion: watertight;
- patch gluing : an example;



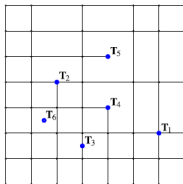
T-splines

However,

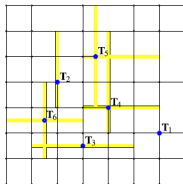
- Linear independence;
- Possible severe fill-in of the T-mesh
- No well characterization



Analysis-suitable T-splines [X. Li et al 2012]



(a) T-mesh.



(b) Extensions.

Definition

- An AS T-mesh is one on which no horizontal T-junction extension intersects a vertical T-junction extension;
- AS T-splines are defined on AS T-meshes

Analysis-suitable T-splines

- Positivity;
- Linear independence;
- Affine invariance: $\sum_{i=1}^n T_i(\xi) = 1$;
- Convex hull;
- Relatively local refinement (numerics);
- Characterization in terms of piecewise polynomials;
- Projections and approximation properties.
 - 1 Dual basis [Veiga, Buffa, and Sangalli, 2012];
 - 2 Characterization.

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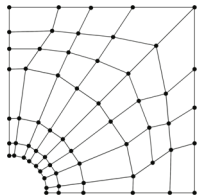
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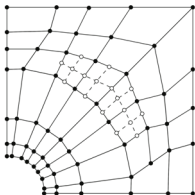
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Local refinement [M. A. Scott, X. Li, etal 2012]

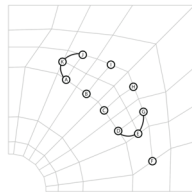
- Direct insert the control points and make the final T-mesh to be analysis-suitable;
- Use greedy strategy to find analysis-suitable refinement



Initial T-mesh

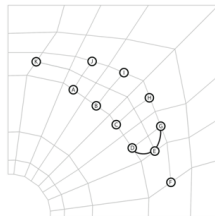
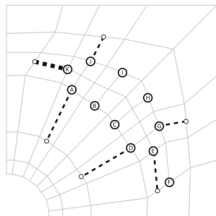


Initial Refinement

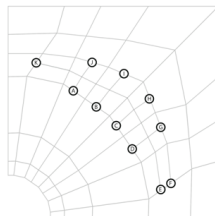
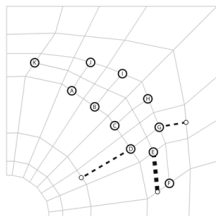


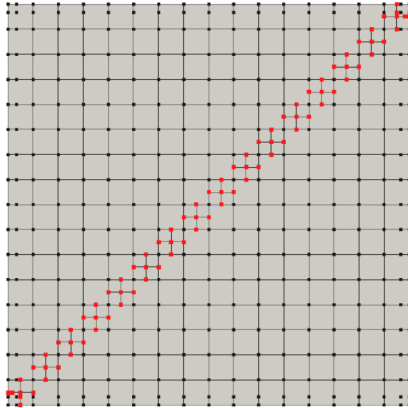
Not analysis-suitable

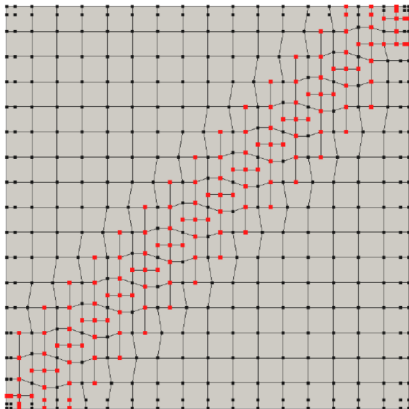
Iteration 1

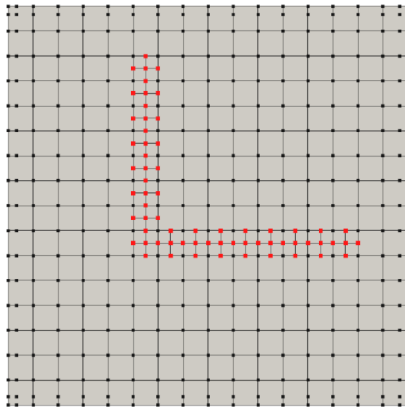


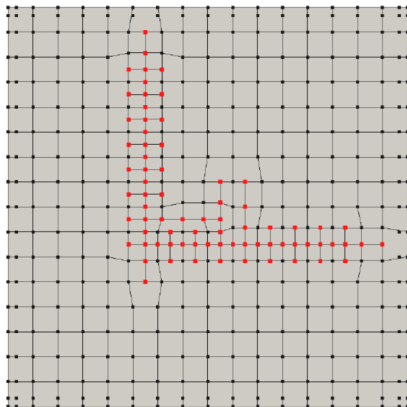
Iteration 2











Characterization

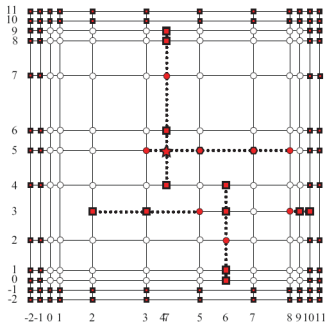
T-spline space

$$\mathcal{T} = \left\{ f(\xi) \in L^2(\Omega) \mid f = \sum c_i T_i(\xi), c_i \in \mathbb{R} \right\} \quad (3)$$

where $L^2(\Omega)$ is the space of square integrable functions over Ω .

Characterization

If the extended T-mesh of an analysis-suitable T-mesh T has **no overlap vertices and no zero knot intervals**, then the associated T-splines space \mathcal{T} and $\mathcal{S}(d_1, d_2, d_1 - 1, d_2 - 1, T_{ext})$ are identical spline spaces.

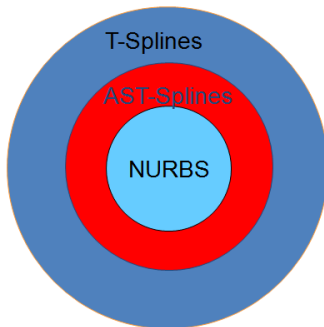


Characterization

The space of bi-degree (d_1, d_2) polynomials lives in the associated T-spline space \mathcal{T} for an analysis-suitable T-mesh T .

Analysis-suitable T-splines

- ✓ Watertight
- ✓ Affine covariance
- ✓ Trimless option
- ✓ Simply implemented in FEA codes
- ✓ Used in design
- ✓ Backwards compatible with NURBS
- ✓ Exact representation of conic sections
- ✓ Higher-order smoothness
- ✓ Linearly independent
- ✓ Partition of unity property
- ✓ Optimized locally refineable
- ✓ Characterization



Summary

- We introduce PHT:
 - perfect local refinement,
 - reduced regularity.
- We introduce analysis-suitable T-splines:
 - NURBS-compatible design-through-analysis technology.
 - Arbitrary topological analysis-suitable T-splines (in progress);
 - Gauss quadrature rules for analysis-suitable T-splines.

Thank you for your attention!

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