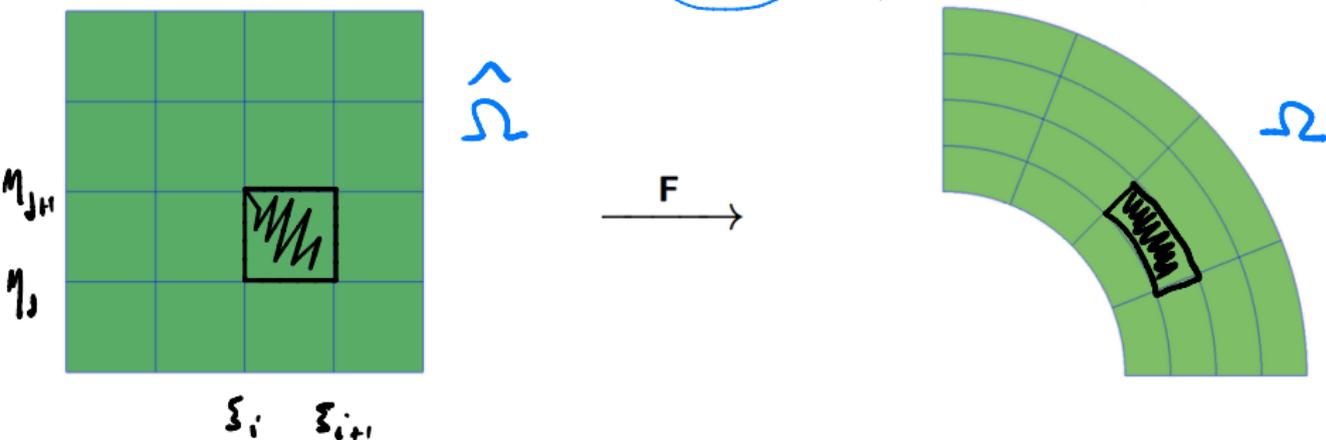


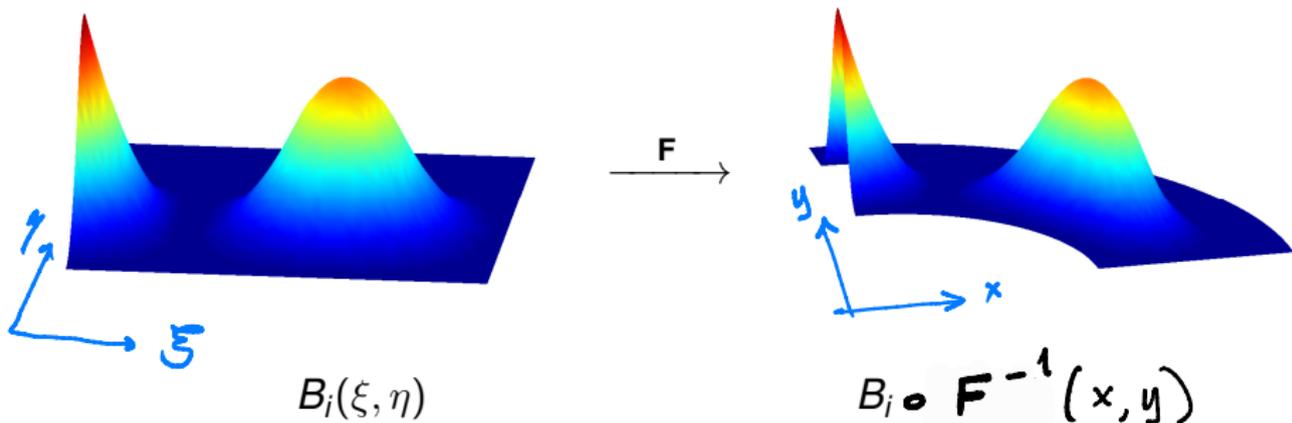
IGA main concepts

The computational domain Ω is parametrized by spline/NURBS:
 $\mathbf{F} : \hat{\Omega} \rightarrow \Omega$, where $\mathbf{F}(\xi, \eta) = \sum_i \mathbf{C}_i B_i(\xi, \eta)$, and \mathbf{C}_i are the control points



IGA main concepts

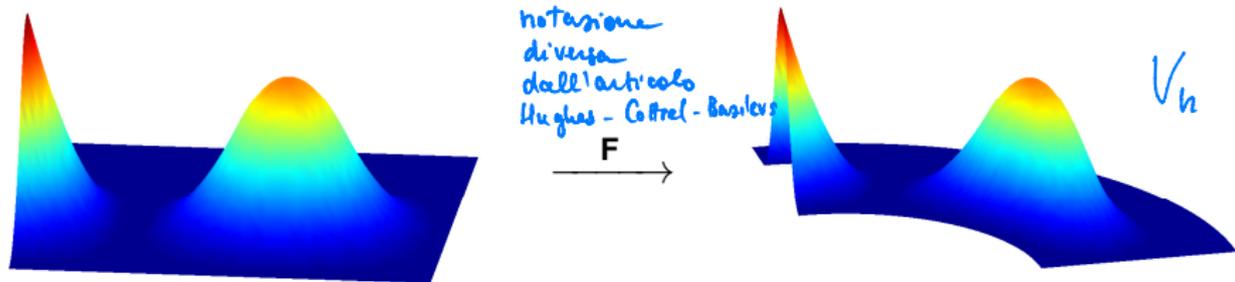
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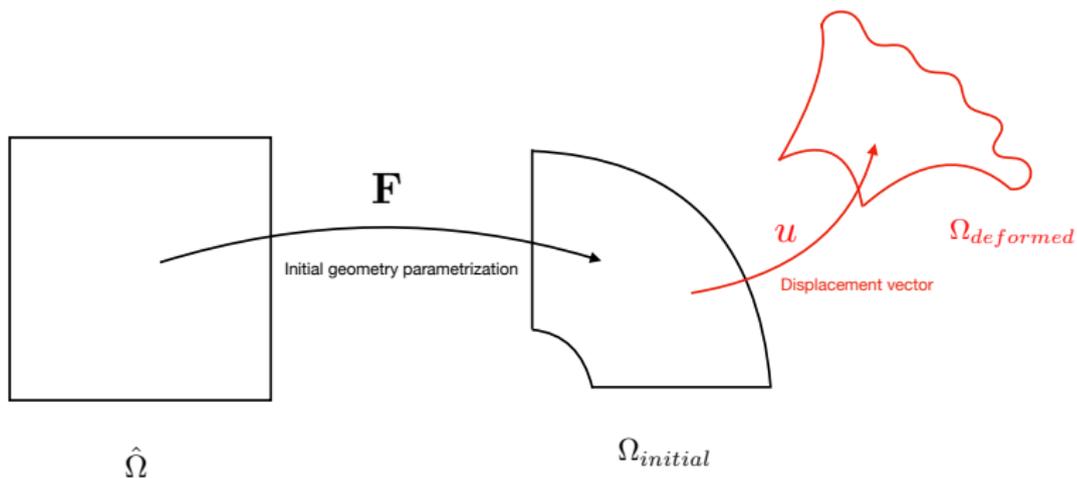
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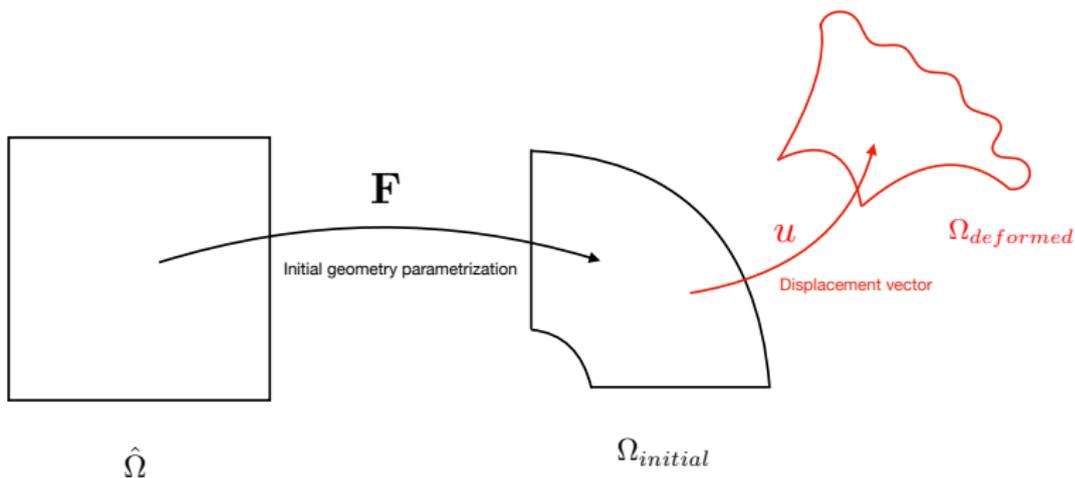
IGA has been proposed by structural engineers:

- **Isoparametric paradigm:** push-forward of splines/NURBS basis functions on the computational domain Ω to approximate the solution of the PDE.
- **Finite Element** kind method (splines etc. replace piecewise polynomials)

Isoparametric concept I



Isoparametric concept I

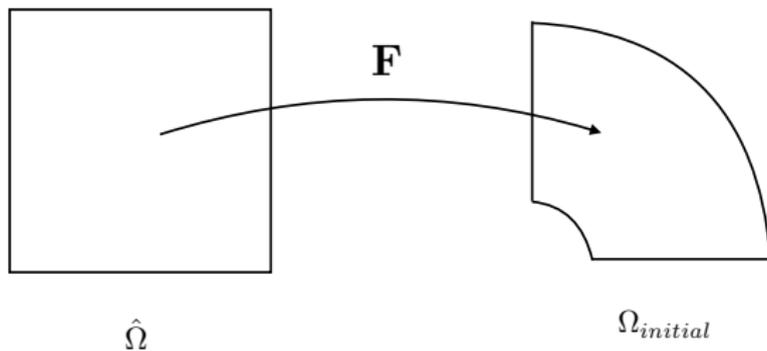


$\Omega_{deformed}$ is parametrized by $(\mathbf{F} + \underbrace{\mathbf{u} \cdot \mathbf{F}}_{\hat{\mathbf{u}}})$

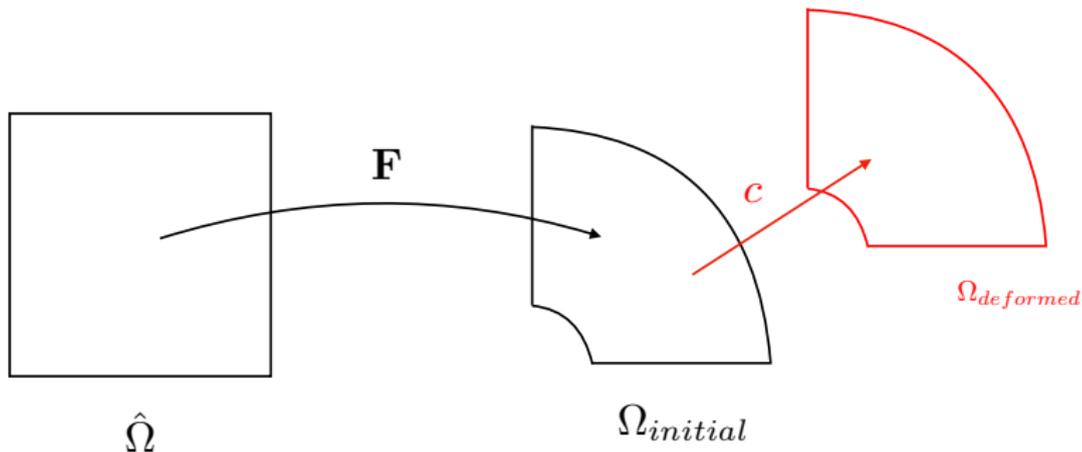
Isoparametric construction

The unknown written w.r.t. the parametric variables ($\hat{\mathbf{u}} : \hat{\Omega} \rightarrow \Omega_{deformed}$) is represented by the same functions that are used for the geometry parametrization $\mathbf{F} : \hat{\Omega} \rightarrow \Omega_{initial}$

Isoparametric concept II

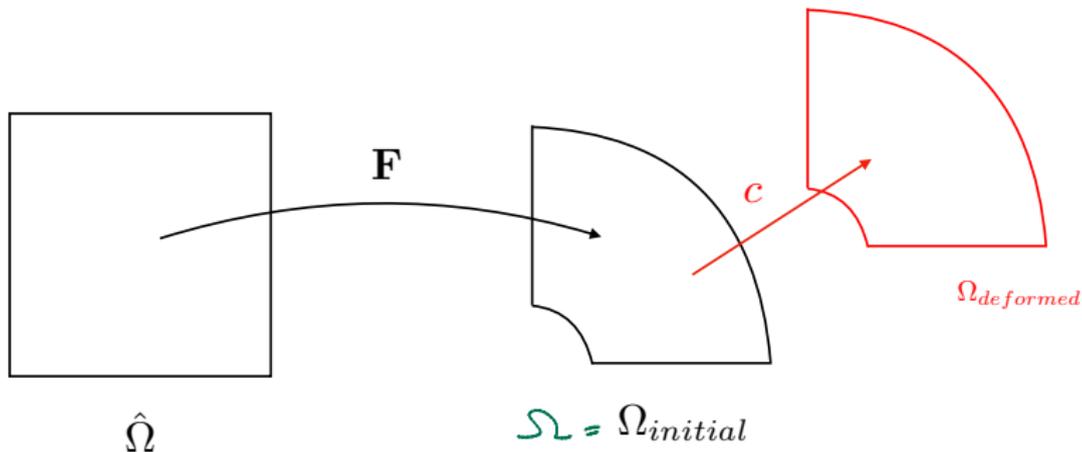


Isoparametric concept II



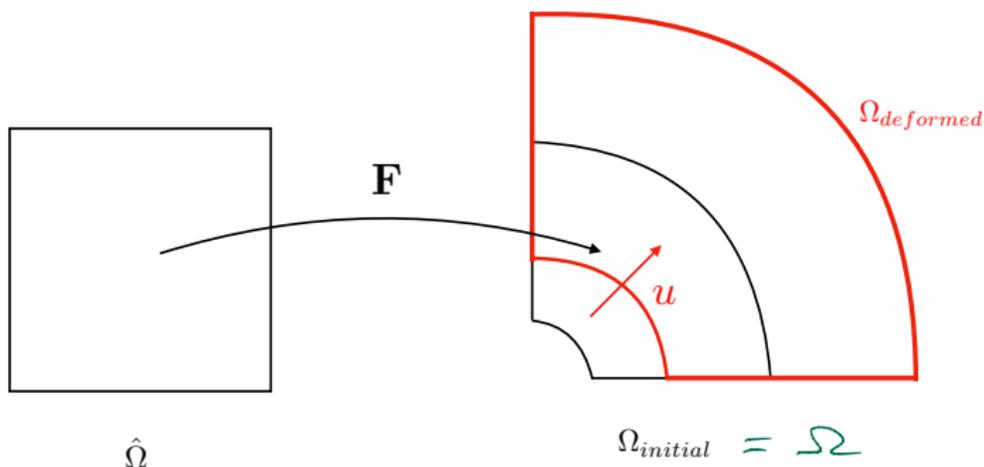
- a constant \mathbf{c} belongs to the isoparametric space if the same constant $\hat{\mathbf{c}} = \mathbf{c} \cdot \mathbf{F}$ is represented in the basis over $\hat{\Omega}$...

Isoparametric concept II



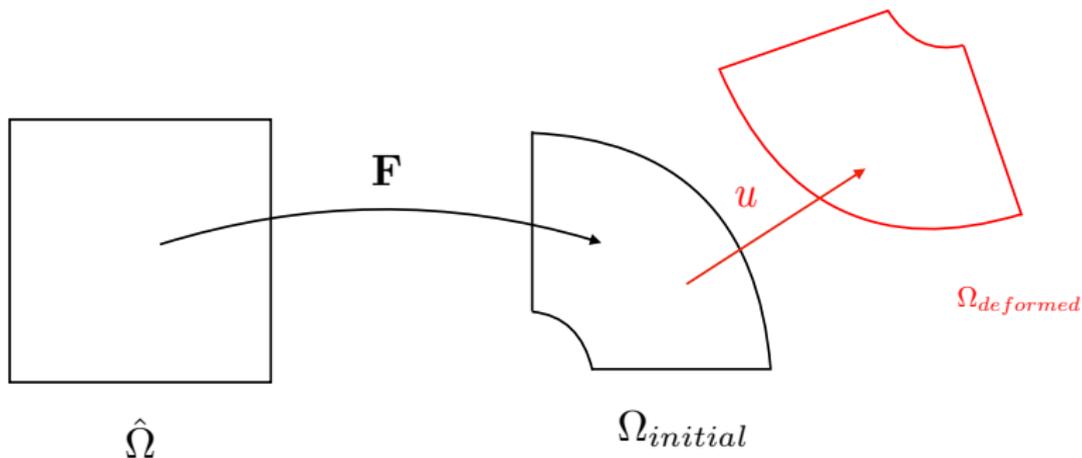
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Isoparametric concept II



- a constant \mathbf{c} belongs to the isoparametric space if the same constant $\hat{\mathbf{c}} = \mathbf{c} \cdot \mathbf{F}$ is represented in the basis over $\hat{\Omega}$... ok for splines and NURBS (partition of the unity)
- $\mathbf{u}(x, y) = \mathbf{A} \begin{bmatrix} x \\ y \end{bmatrix}$ is in **any** isoparametric space since $\hat{\mathbf{u}}(\xi, \eta) = \mathbf{A} \mathbf{F} \begin{bmatrix} \xi \\ \eta \end{bmatrix} = \mathbf{A} \begin{bmatrix} F_1(\xi, \eta) \\ F_2(\xi, \eta) \end{bmatrix}$ is a vector field whose components are linear combination of the parametrization components $F_1(\xi, \eta)$ and $F_2(\xi, \eta)$, and then is represented in the same basis

Isoparametric concept II



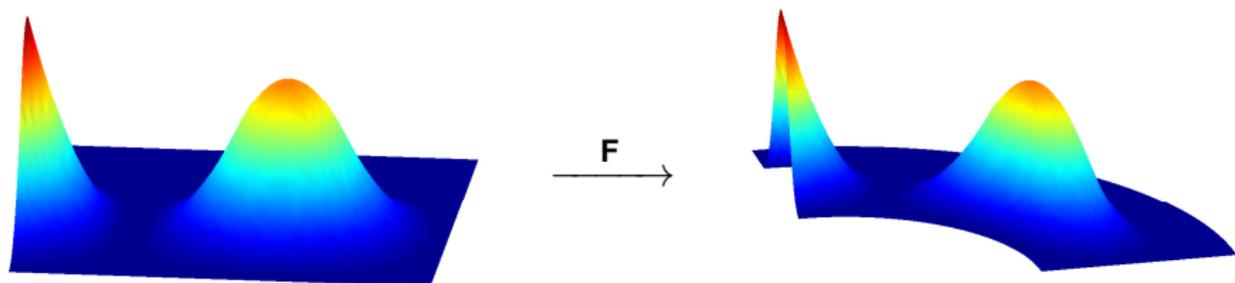
The isoparametric space contains any rigid body motion

$$\mathbf{u}(x, y) = \mathbf{c} + \mathbf{R} \begin{bmatrix} x \\ y \end{bmatrix}$$

that form the kernel of the internal elastic energy

IGA main side-effect

The computational domain Ω is parametrized by spline/NURBS:
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Isogeometric spaces are smooth